



LEAH WRENN BERMAN

UNIVERSITY OF ALASKA FAIRBANKS

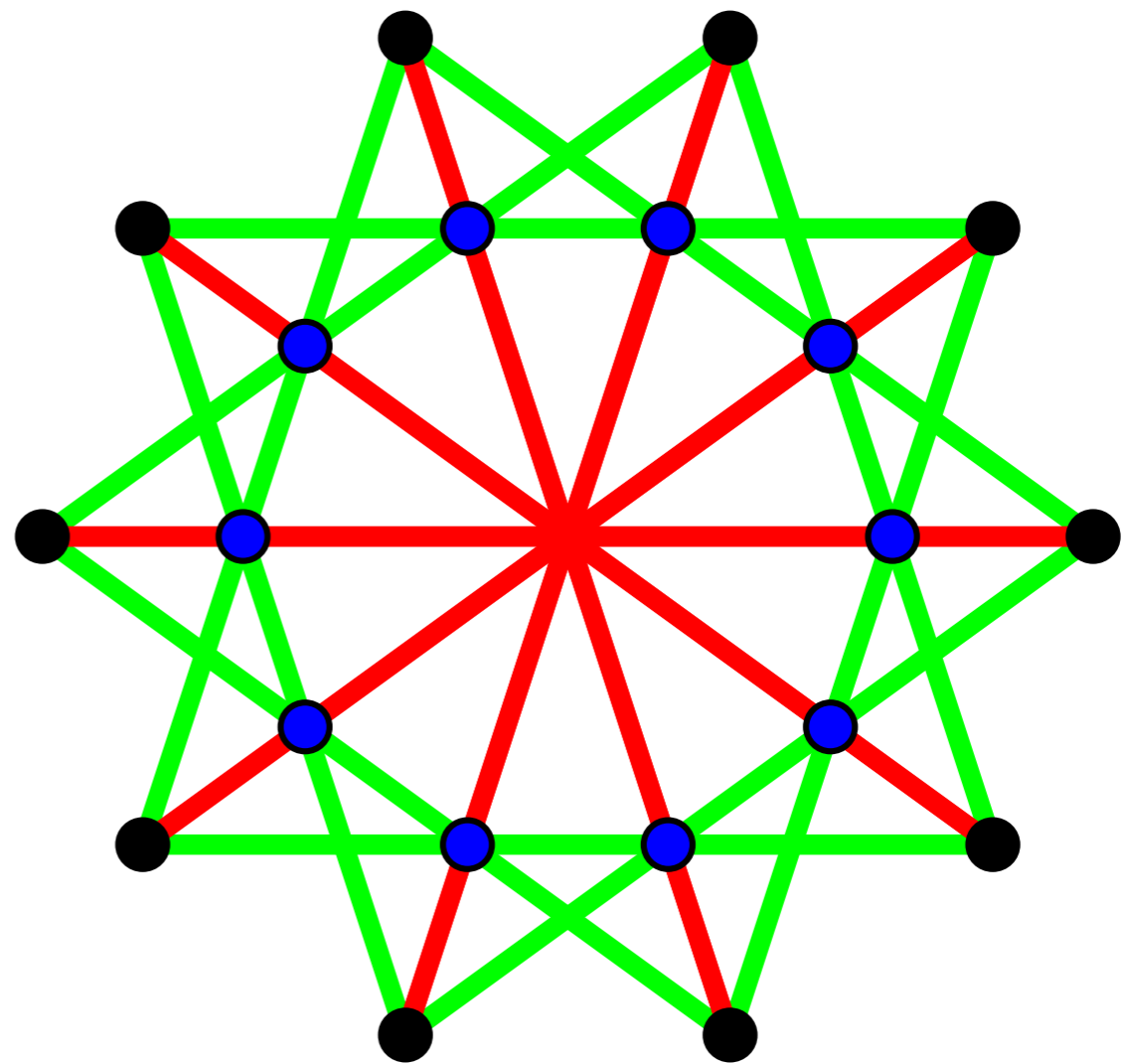
GEOSYM 2015—29 JUNE - 3 JULY 2015, VESZPRÉM, HUNGARY

# SYMMETRIC MOVABLE CONFIGURATIONS

Supported in part by a grant from the Simons  
Foundation

# GEOMETRIC CONFIGURATION

- $p$  points
- $n$  **straight** lines
- $q$  lines/point
- $k$  points/line
- $(p_q, n_k)$  configuration;  
 $(q,k)$ -configuration
- $(n_k)$  configuration;  
 $k$ -configuration

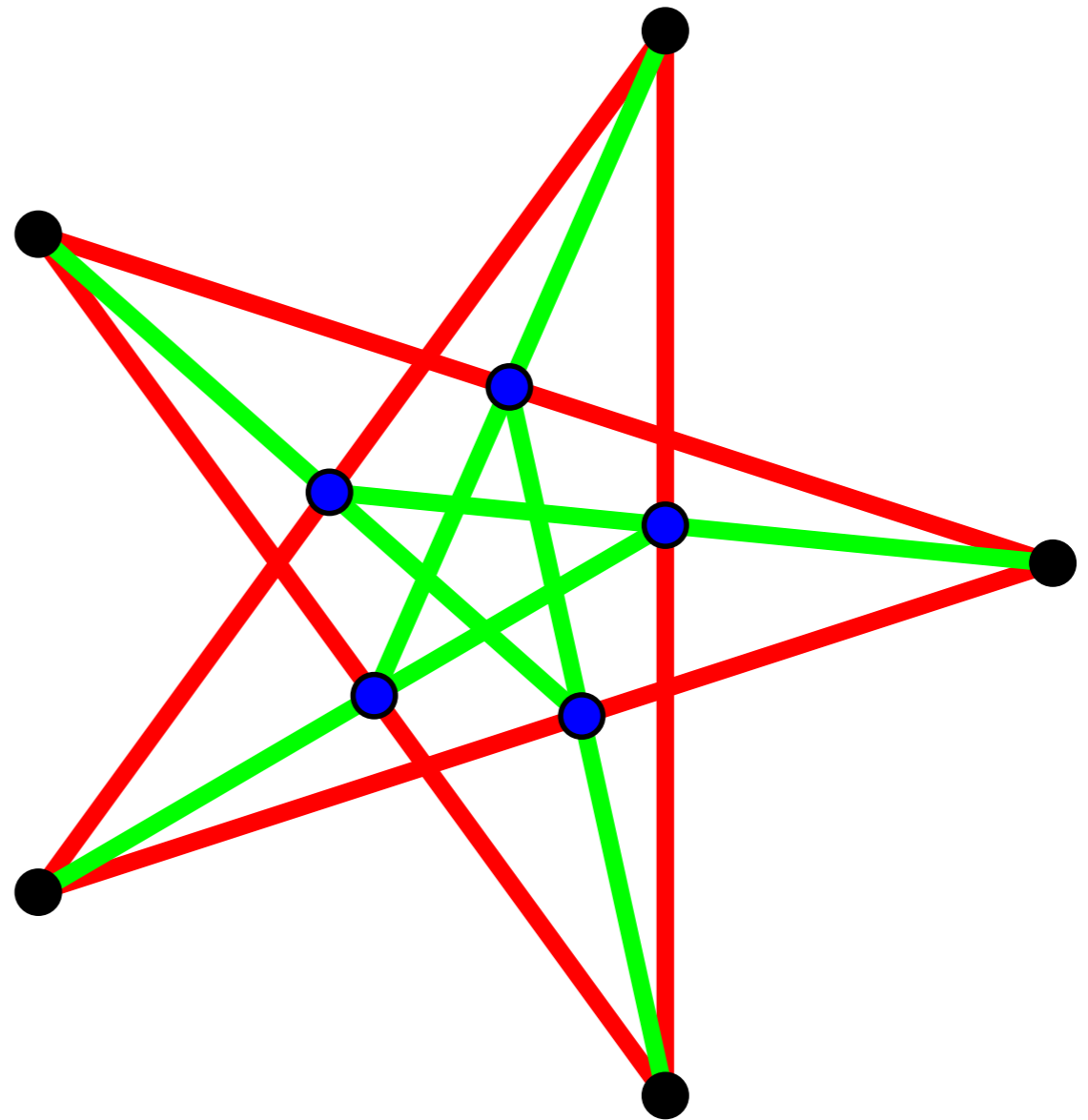


$(20_3, 15_4)$

$(3,4)$ -configuration

# GEOMETRIC CONFIGURATION

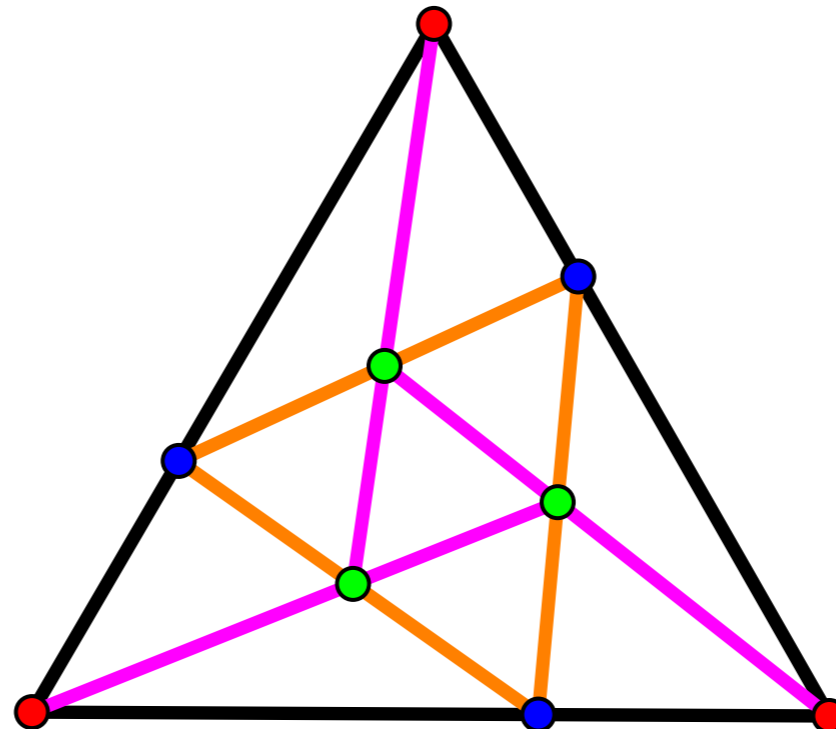
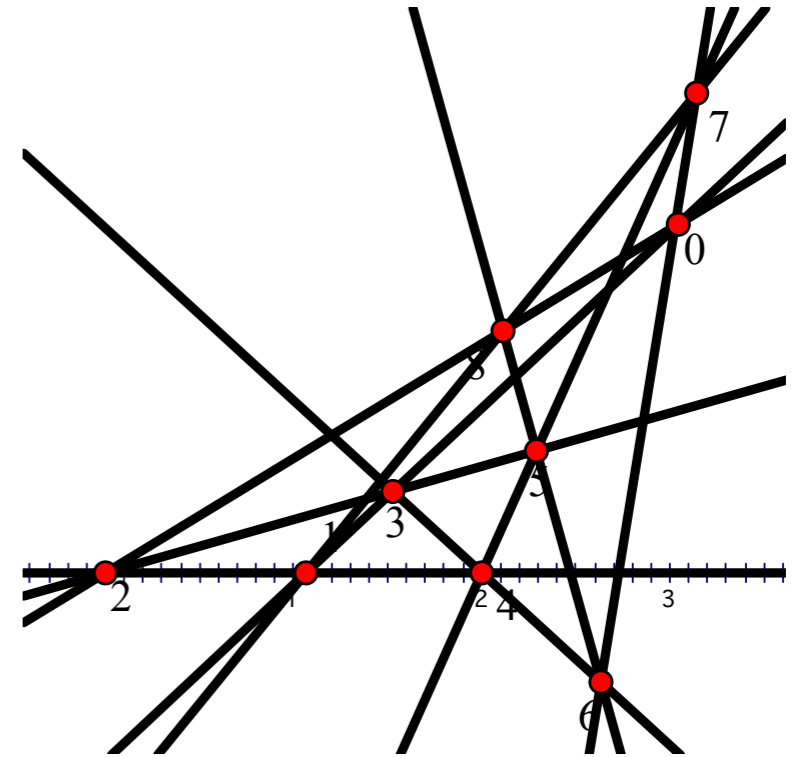
- $p$  points
- $n$  **straight** lines
- $q$  lines/point
- $k$  points/line
- $(p_q, n_k)$  configuration;  
 $(q, k)$ -configuration
- $(n_k)$  configuration;  
 $k$ -configuration



$(10_3, 10_3) = (10_3)$   
3-configuration

# SYMMETRIC CONFIGURATION

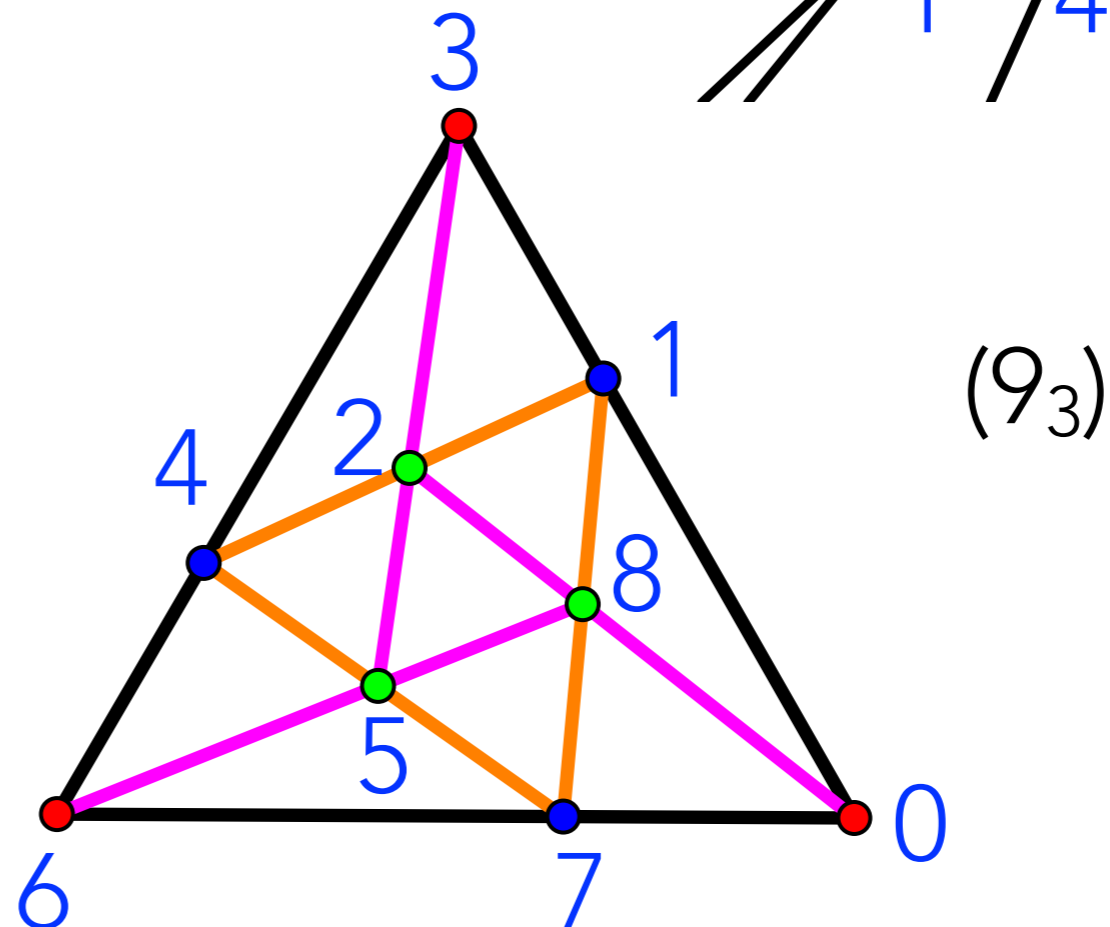
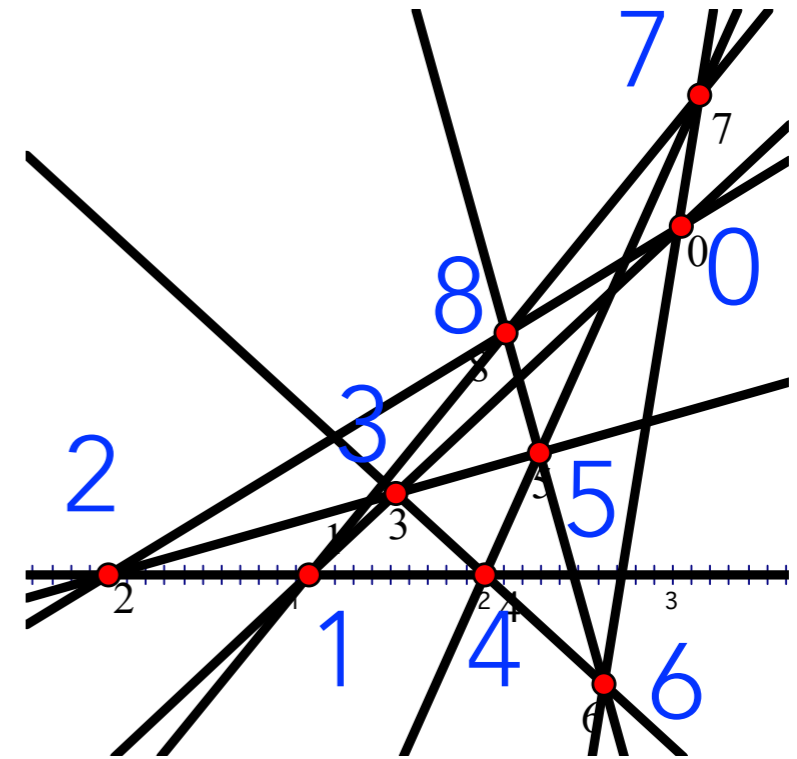
- isomorphism
- *balanced* vs.  
*symmetric*
- **symmetry classes**  
under isometries of  
the configuration



$(9_3)$

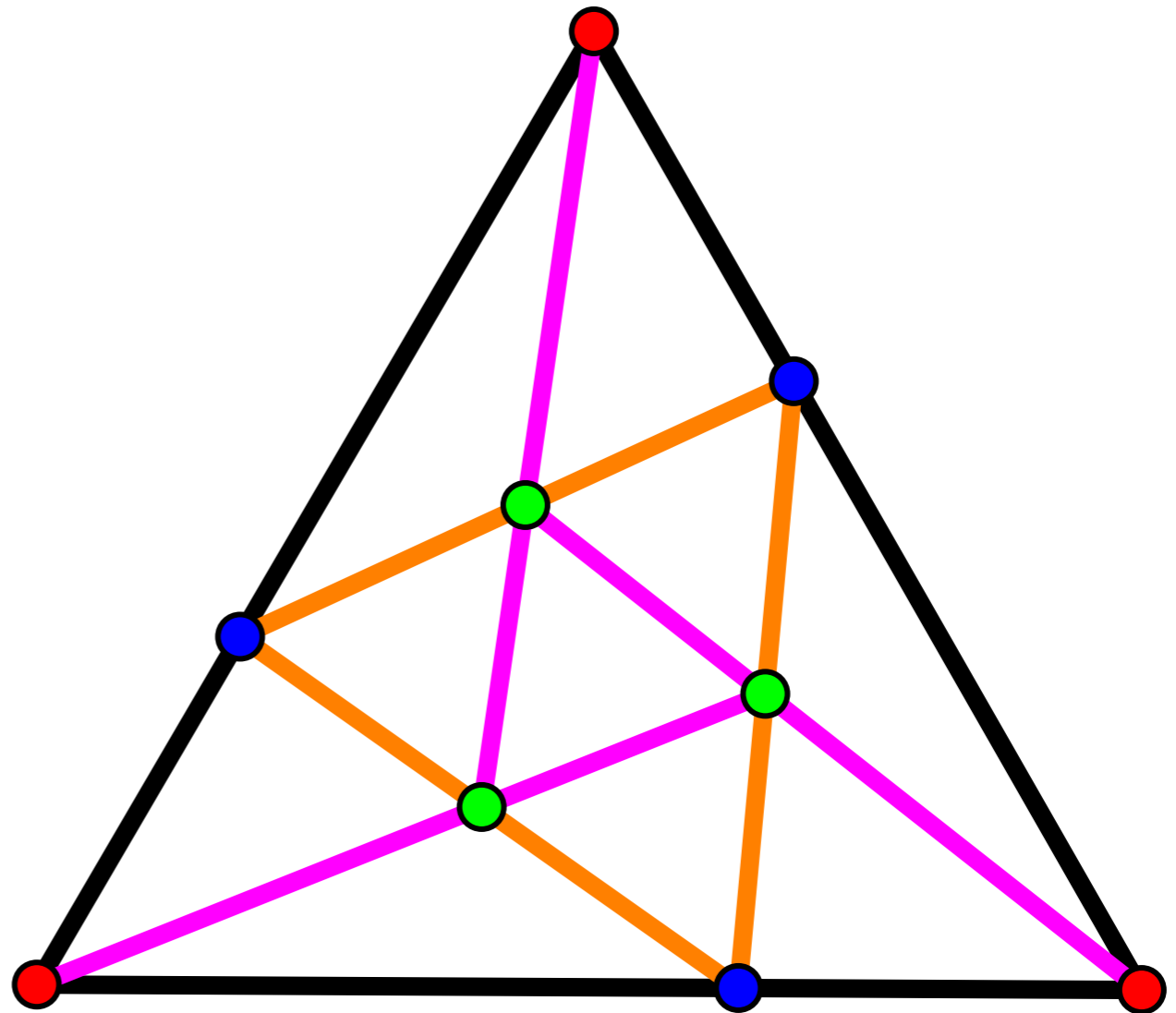
# SYMMETRIC CONFIGURATION

- isomorphism
- *balanced* vs. *symmetric*
- **symmetry classes** under isometries of the configuration



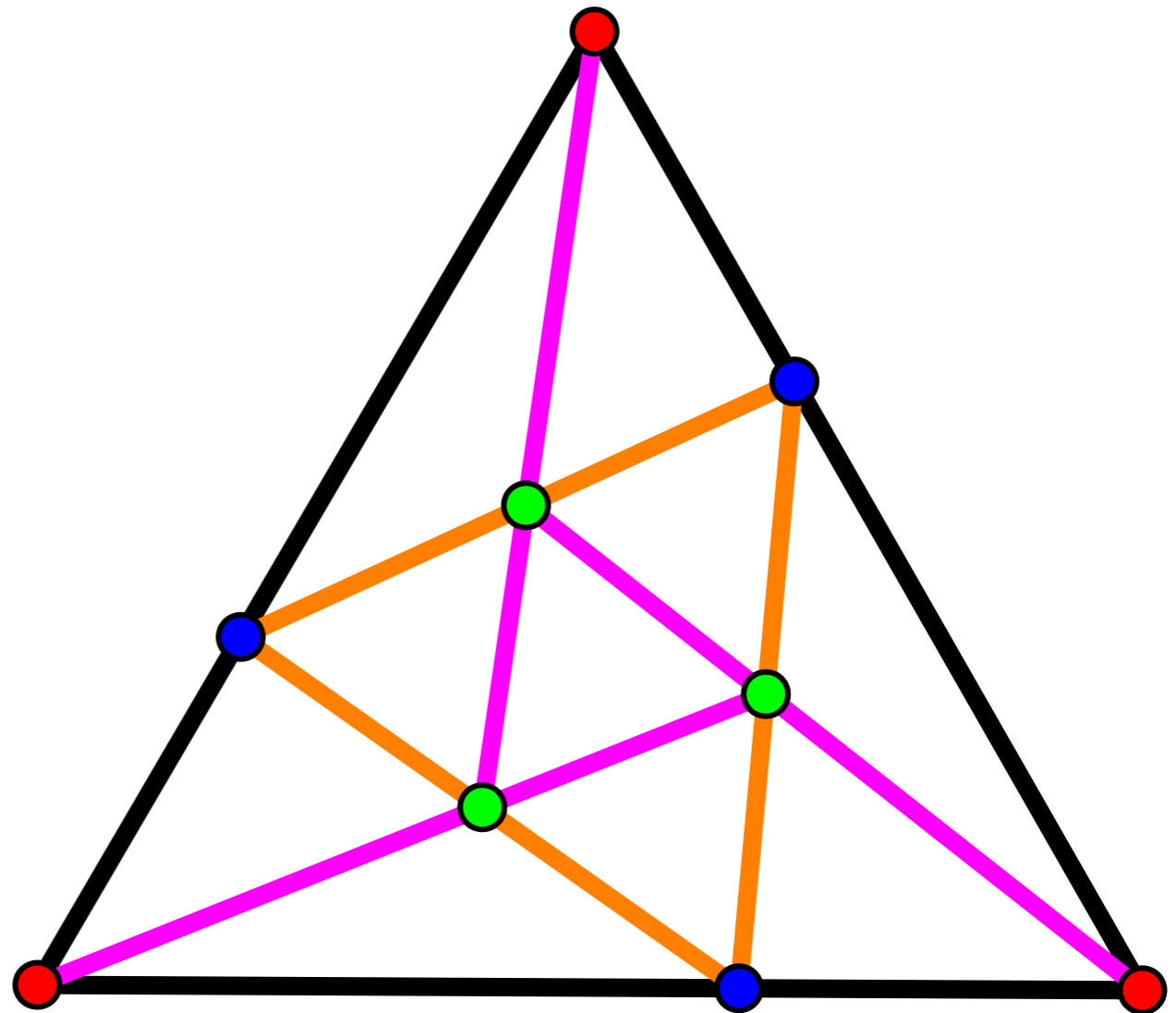
# SYMMETRIC CONFIGURATION

- isomorphism
- *balanced* vs. *symmetric*
- **symmetry classes** under isometries of the configuration

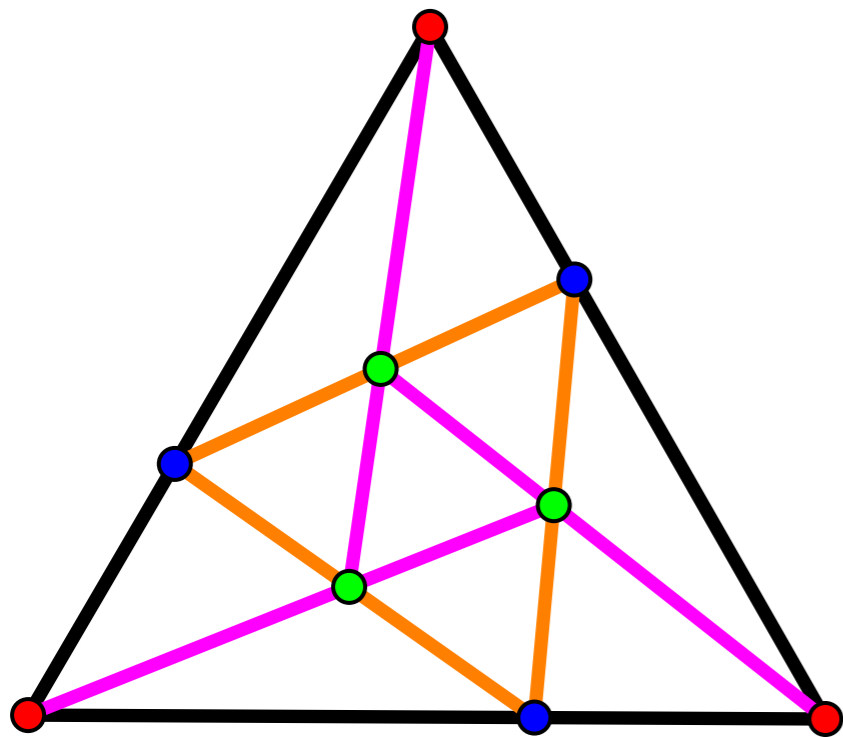


# SYMMETRIC CONFIGURATION

- isomorphism
- *balanced* vs. *symmetric*
- **symmetry classes** under isometries of the configuration

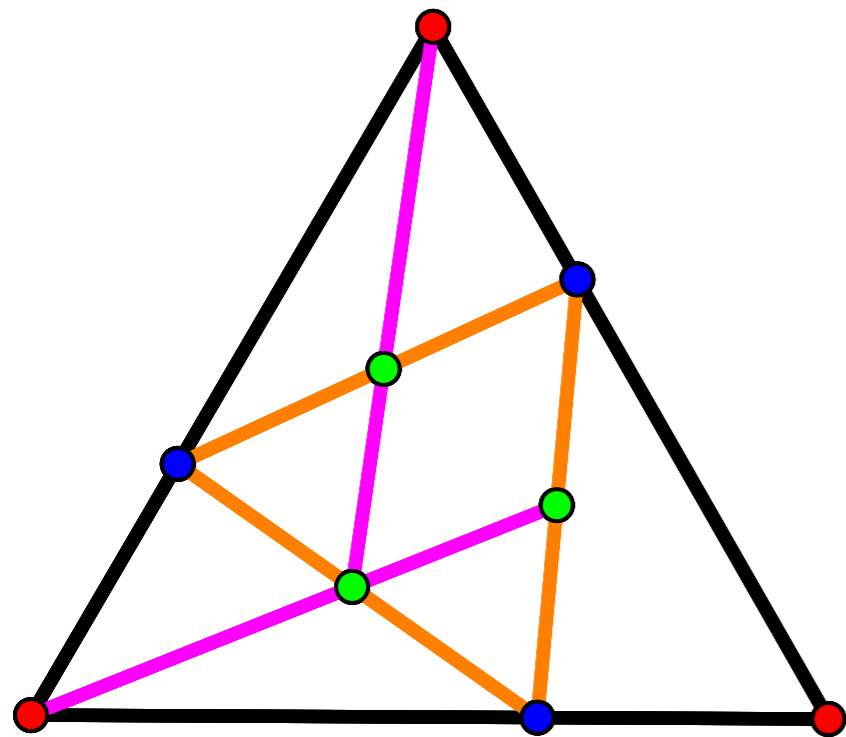


# MOVABLE CONFIGURATION



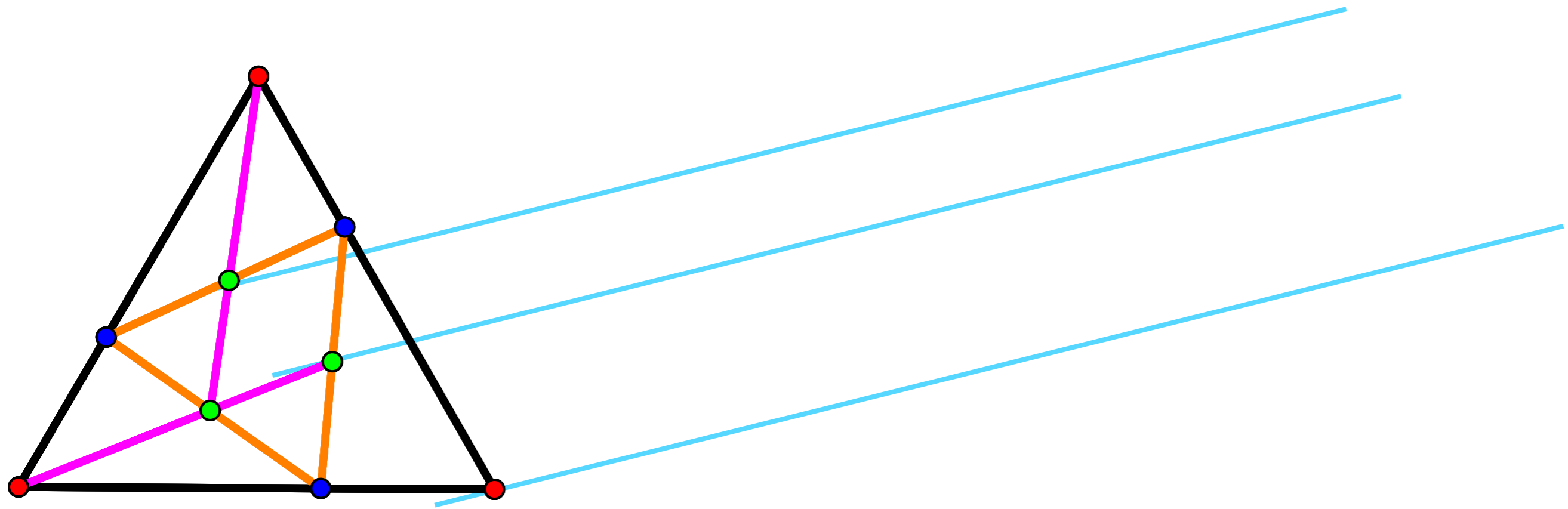
At least 4 points in general position are fixed, but a continuous parameter moves at least one point

# MOVABLE CONFIGURATION



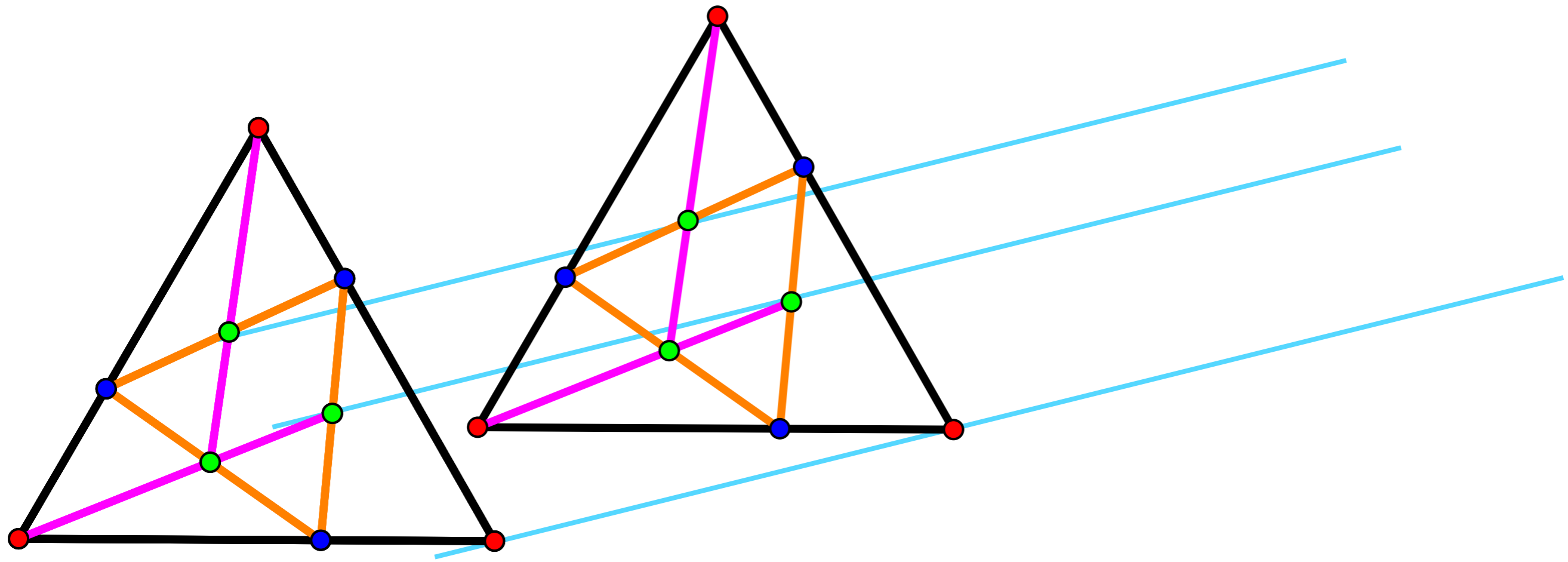
At least 4 points in general position are fixed, but a continuous parameter moves at least one point

# MOVABLE CONFIGURATION



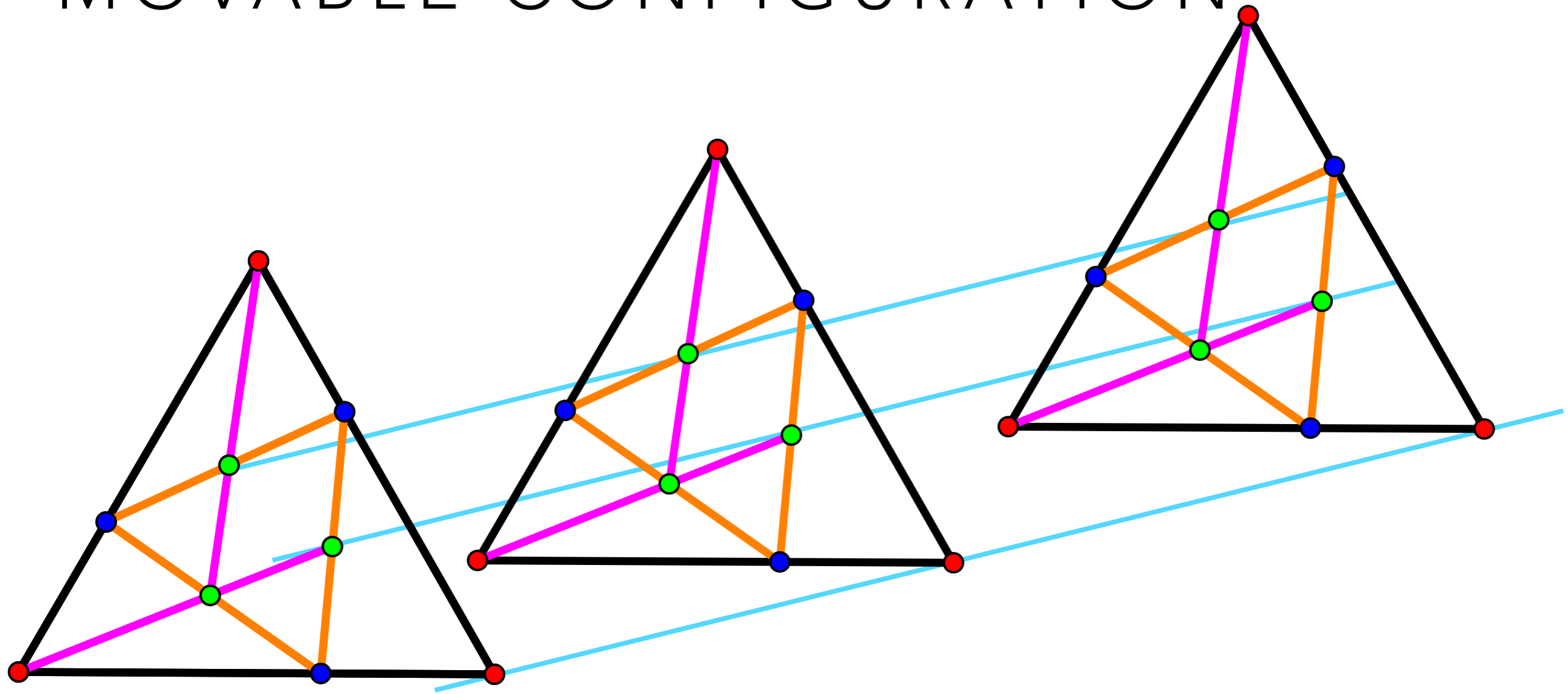
At least 4 points in general position are fixed, but a continuous parameter moves at least one point

# MOVABLE CONFIGURATION



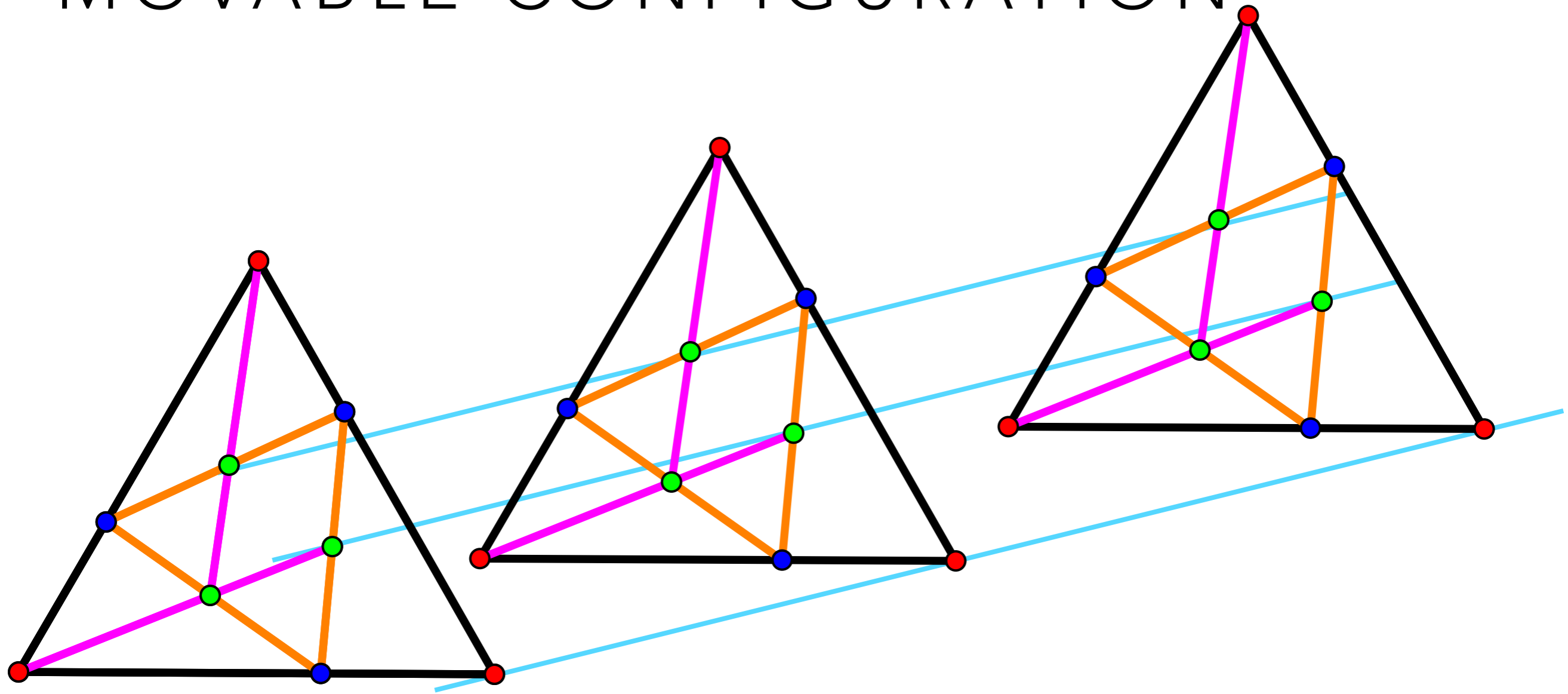
At least 4 points in general position are fixed, but a continuous parameter moves at least one point

# MOVABLE CONFIGURATION



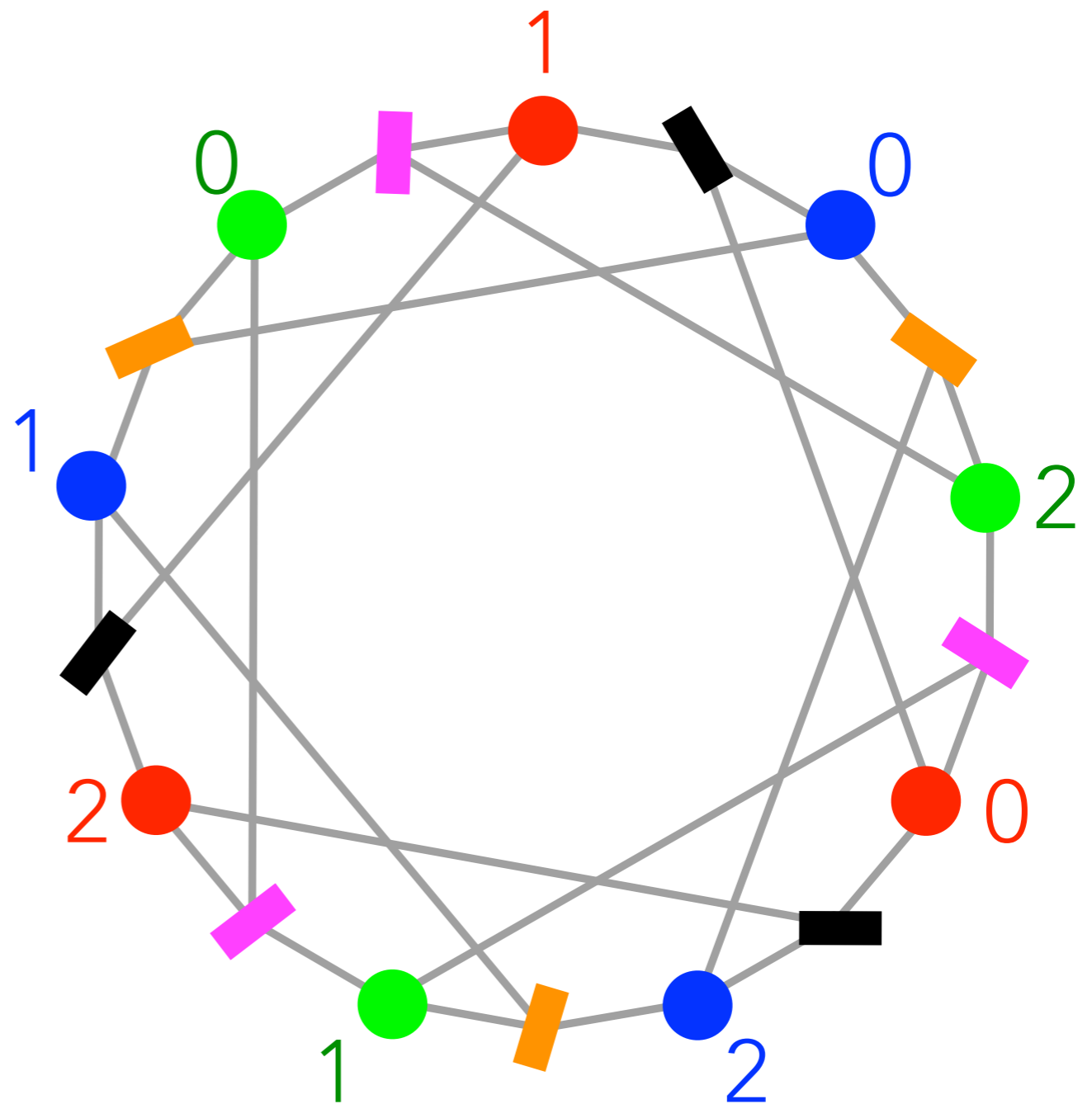
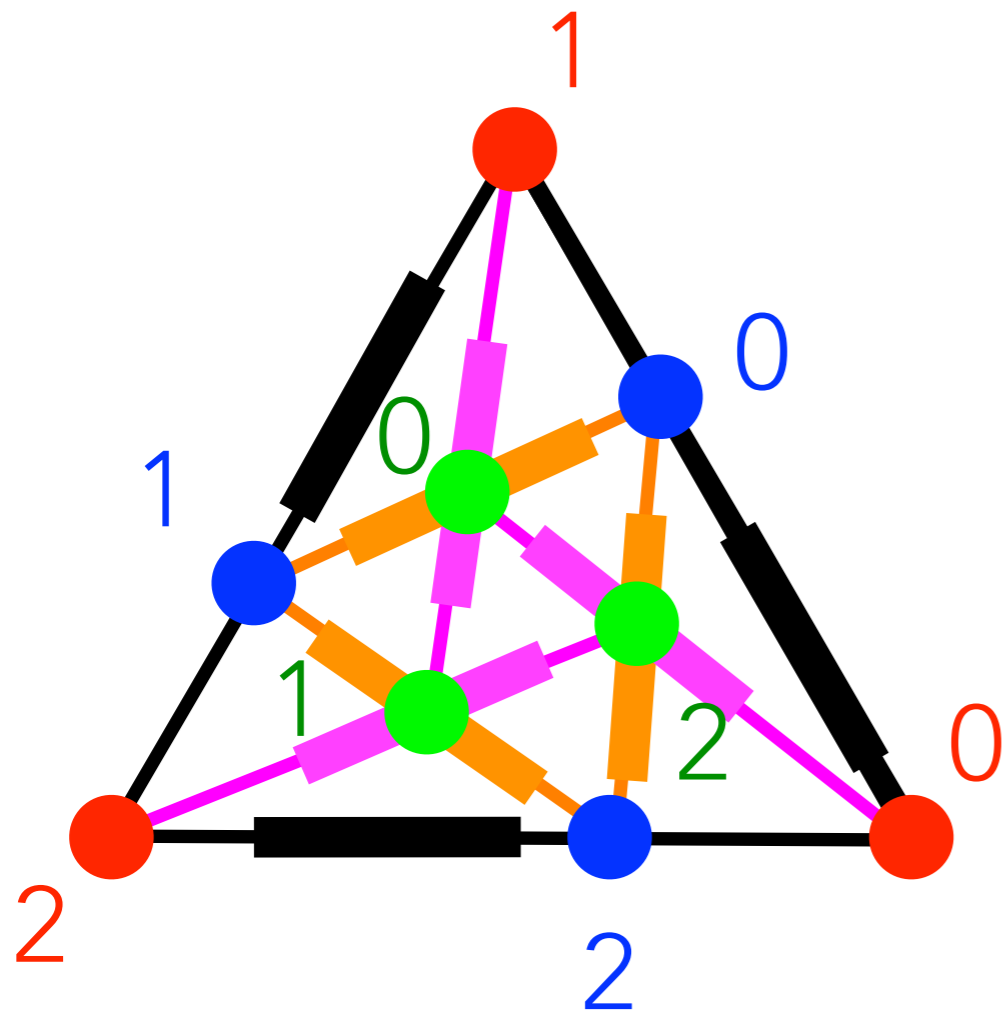
At least 4 points in general position are fixed, but a continuous parameter moves at least one point

# MOVABLE CONFIGURATION

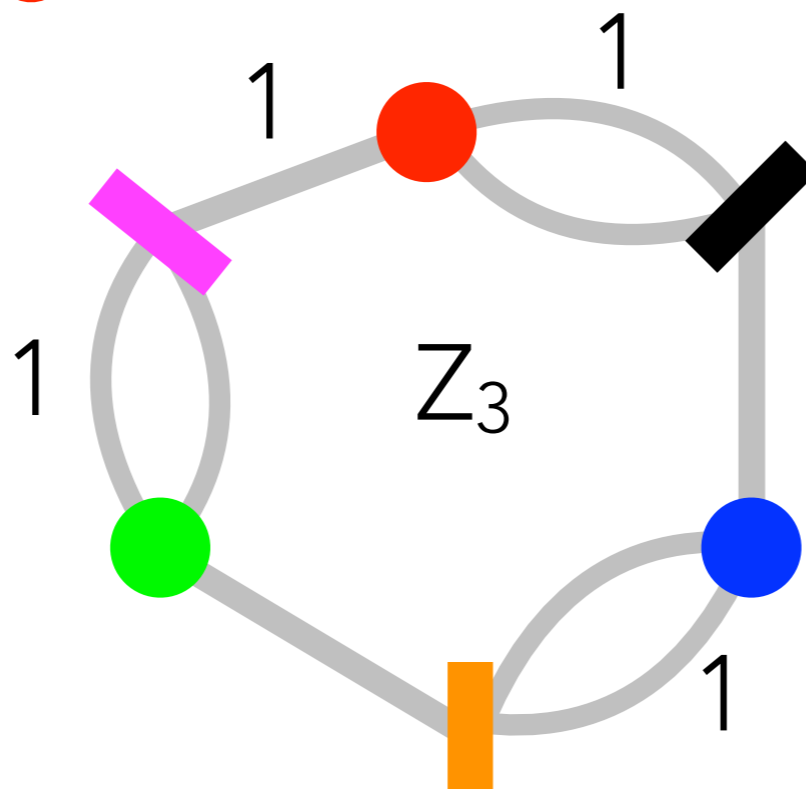
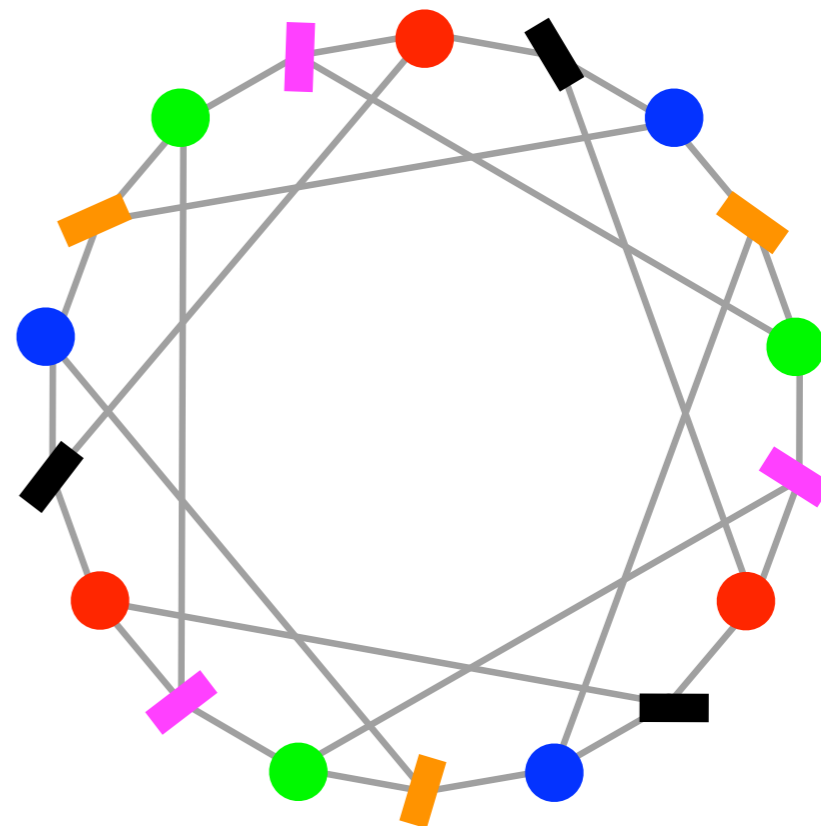
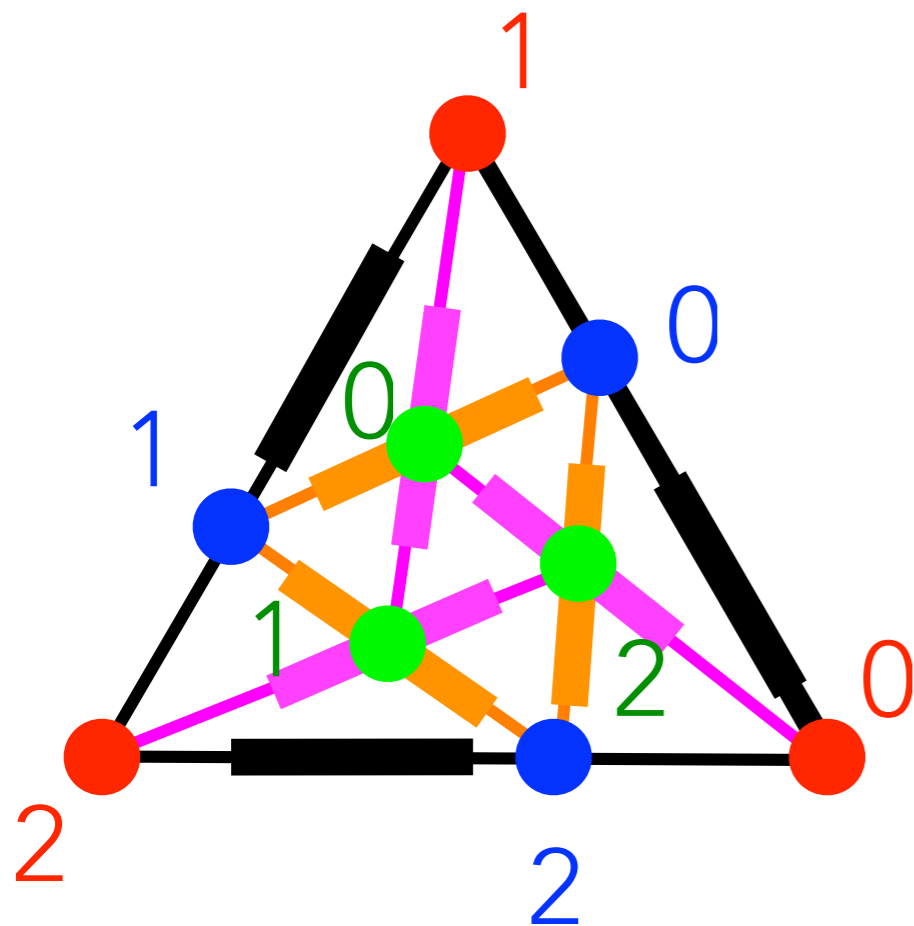


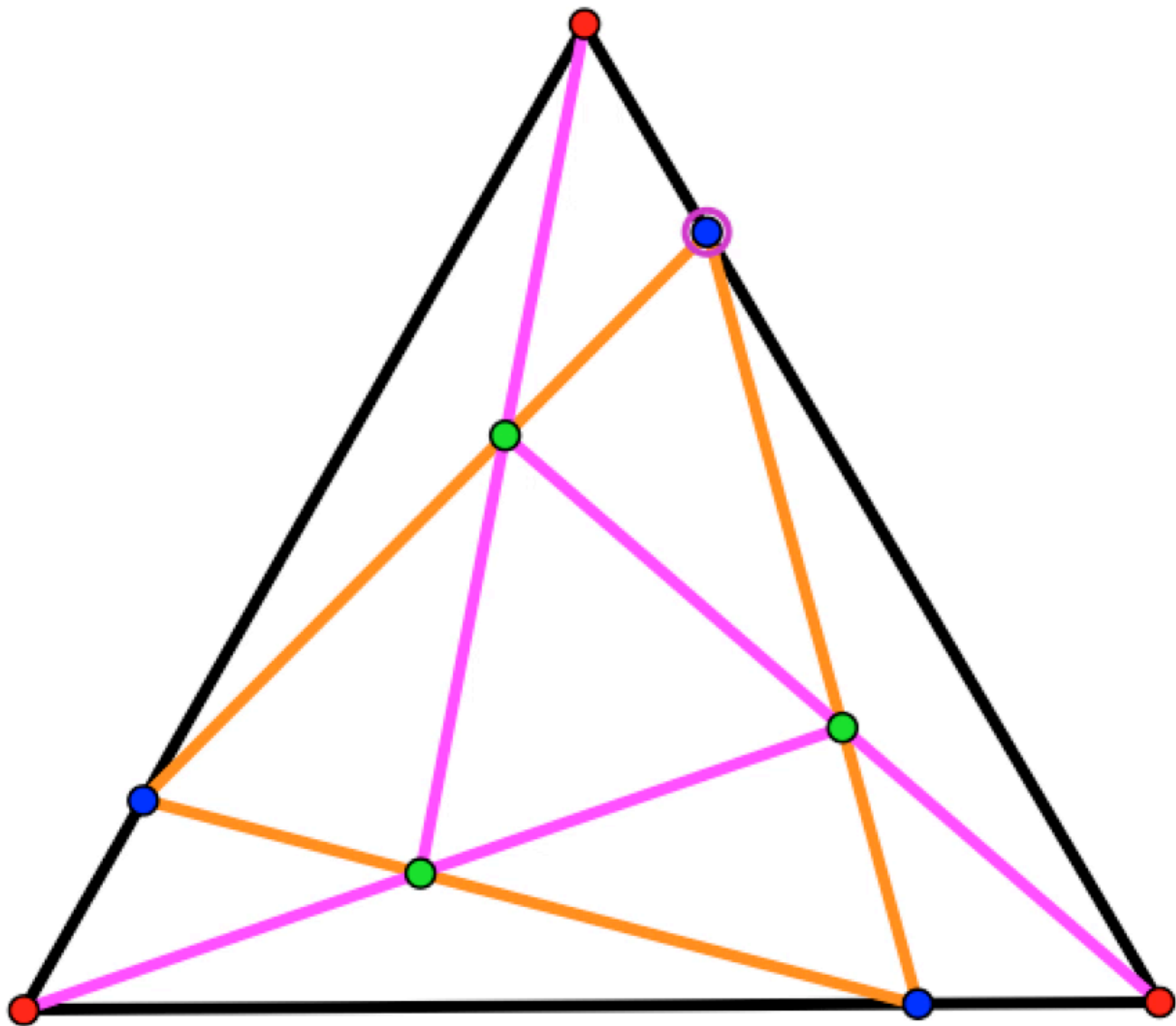
At least 4 points in general position are fixed, but a continuous parameter moves at least one point

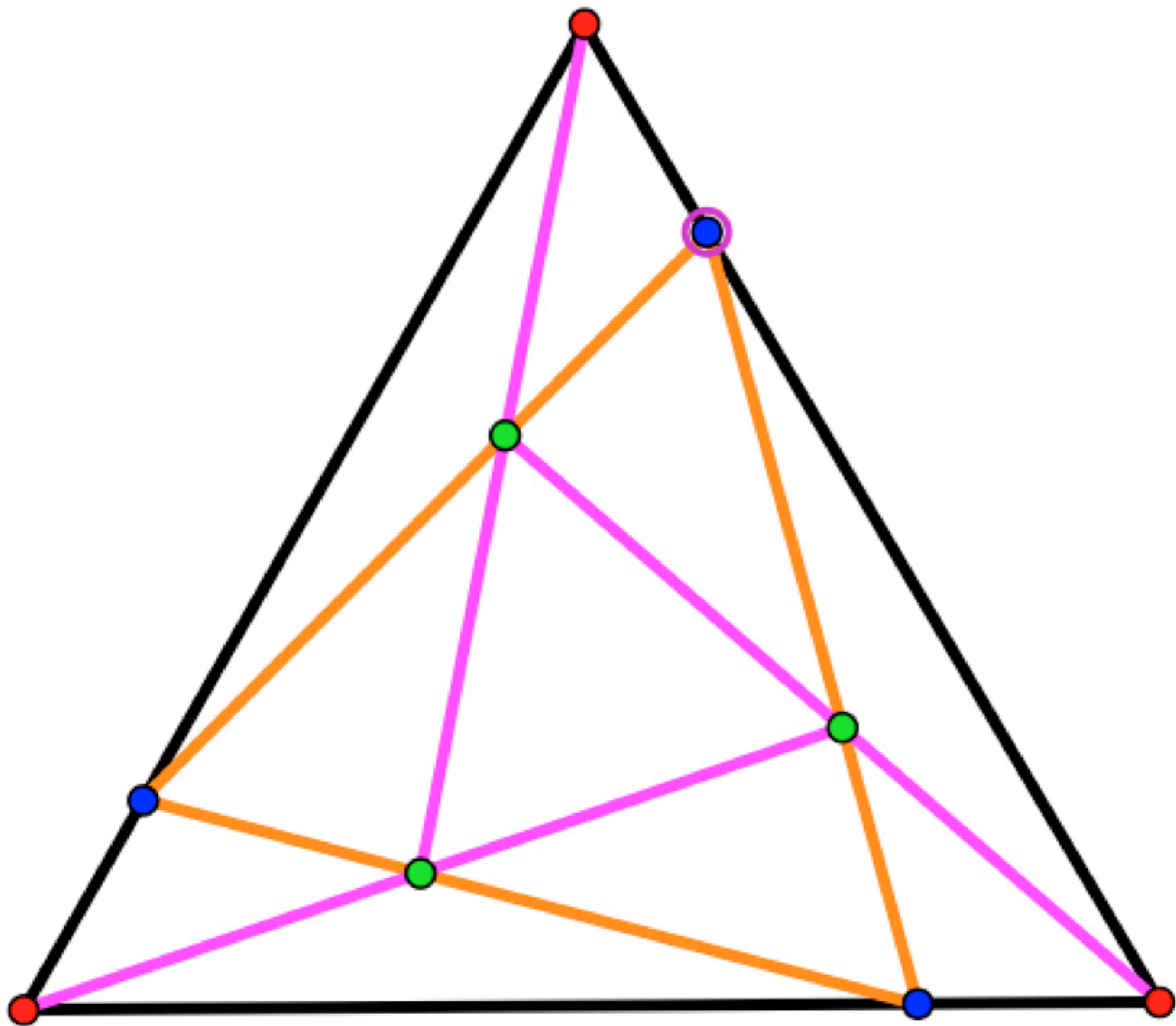
# LEVI GRAPH

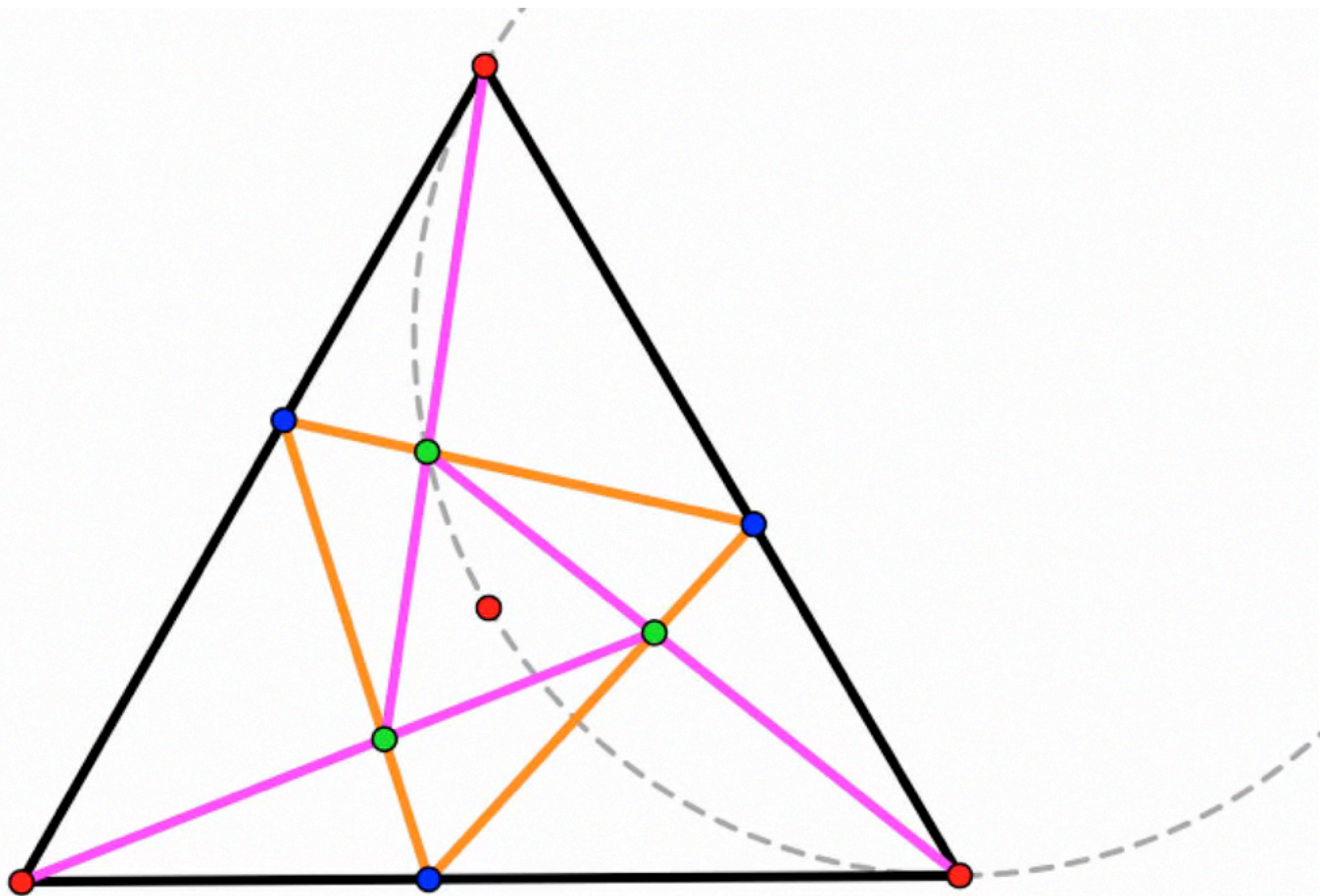


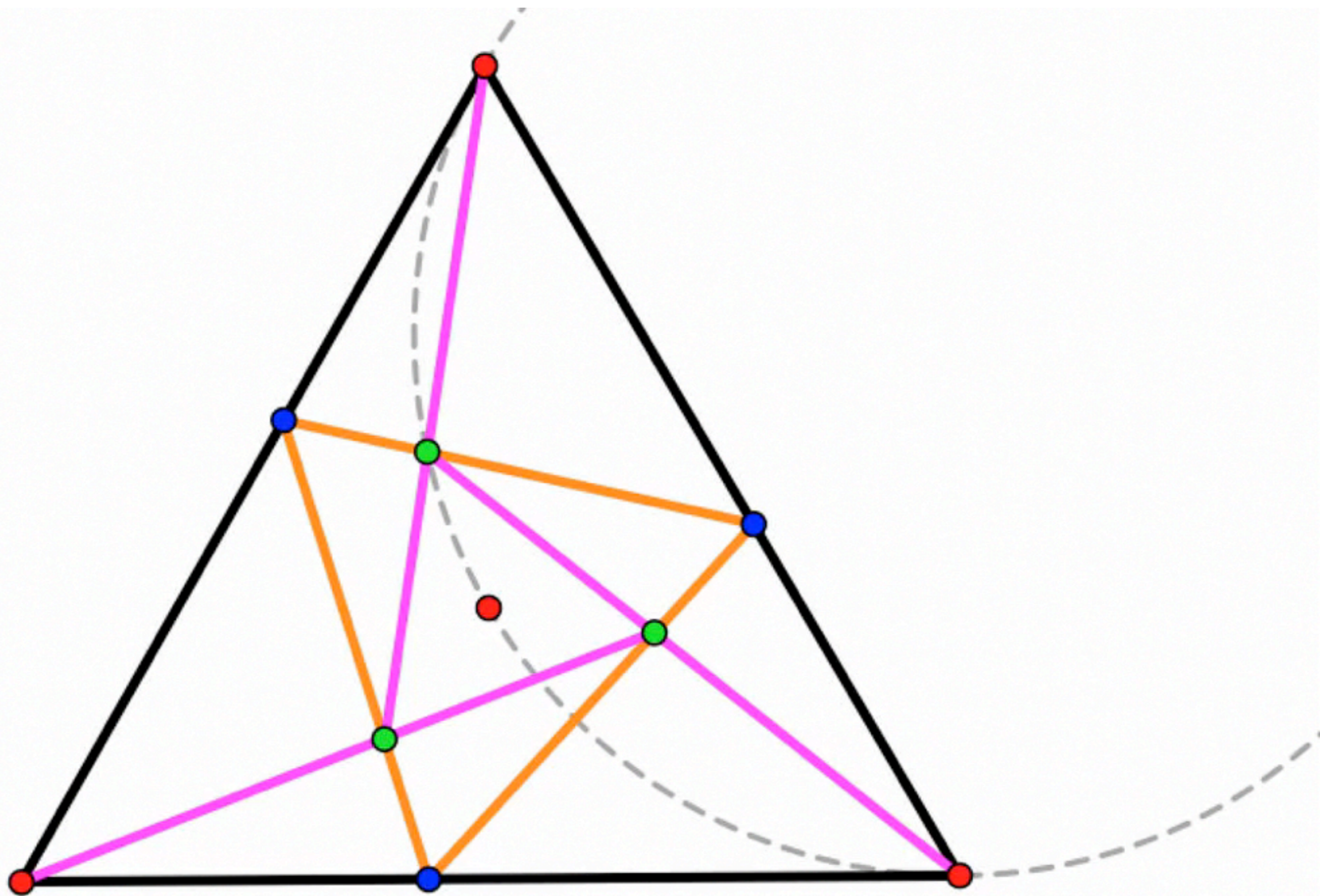
# REDUCED LEVI GRAPH



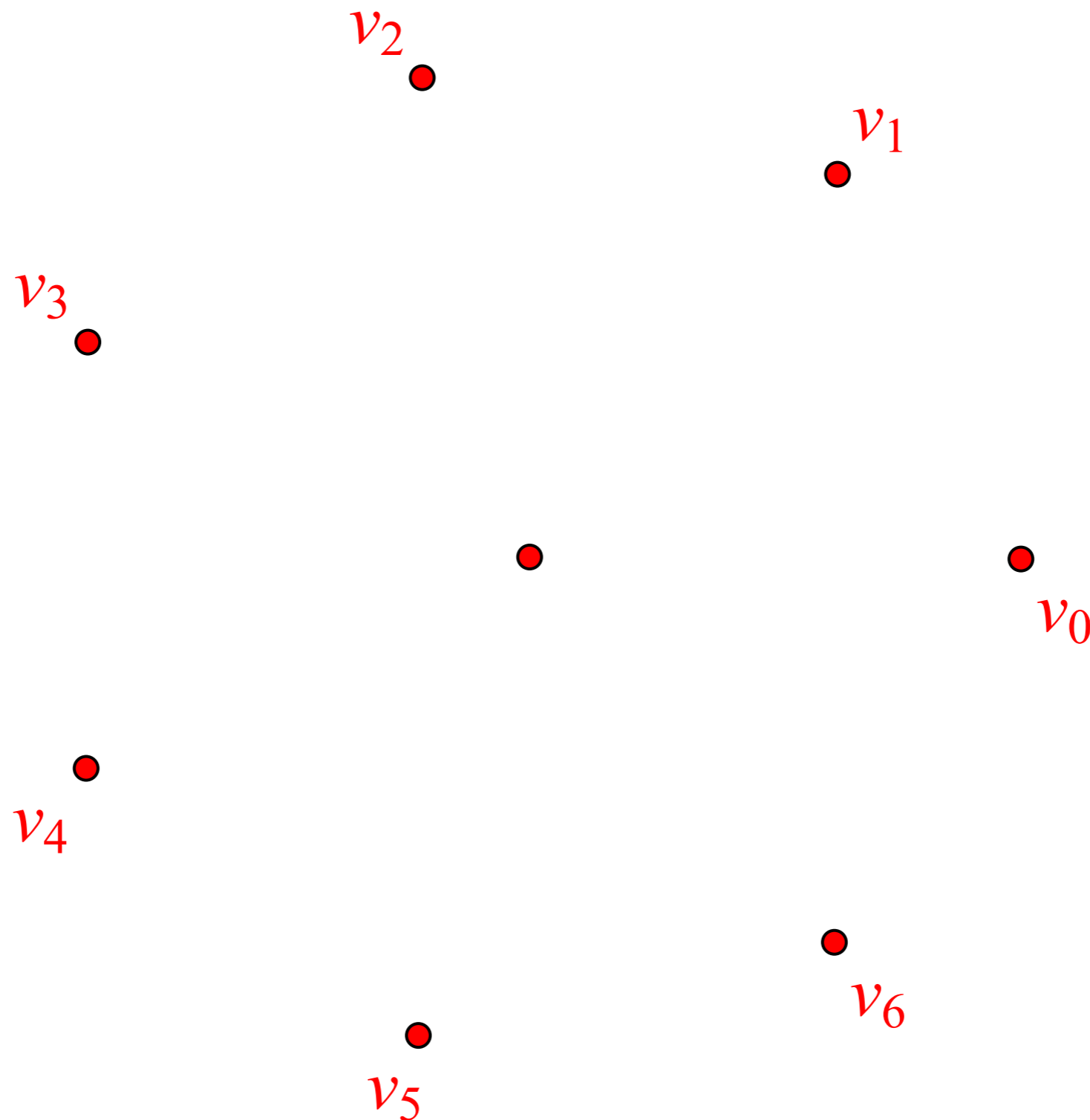






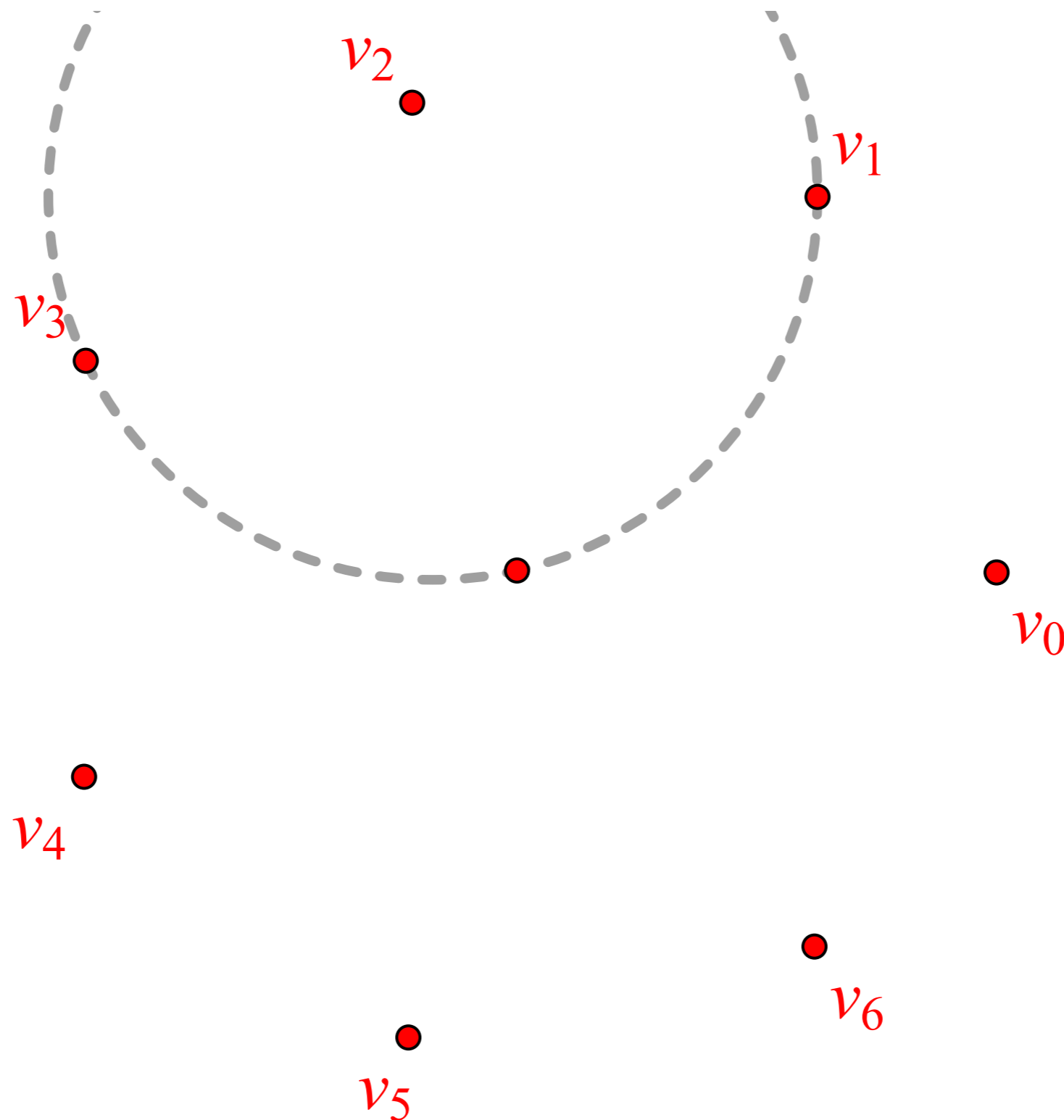


# CONFIGURATION CONSTRUCTION LEMMA

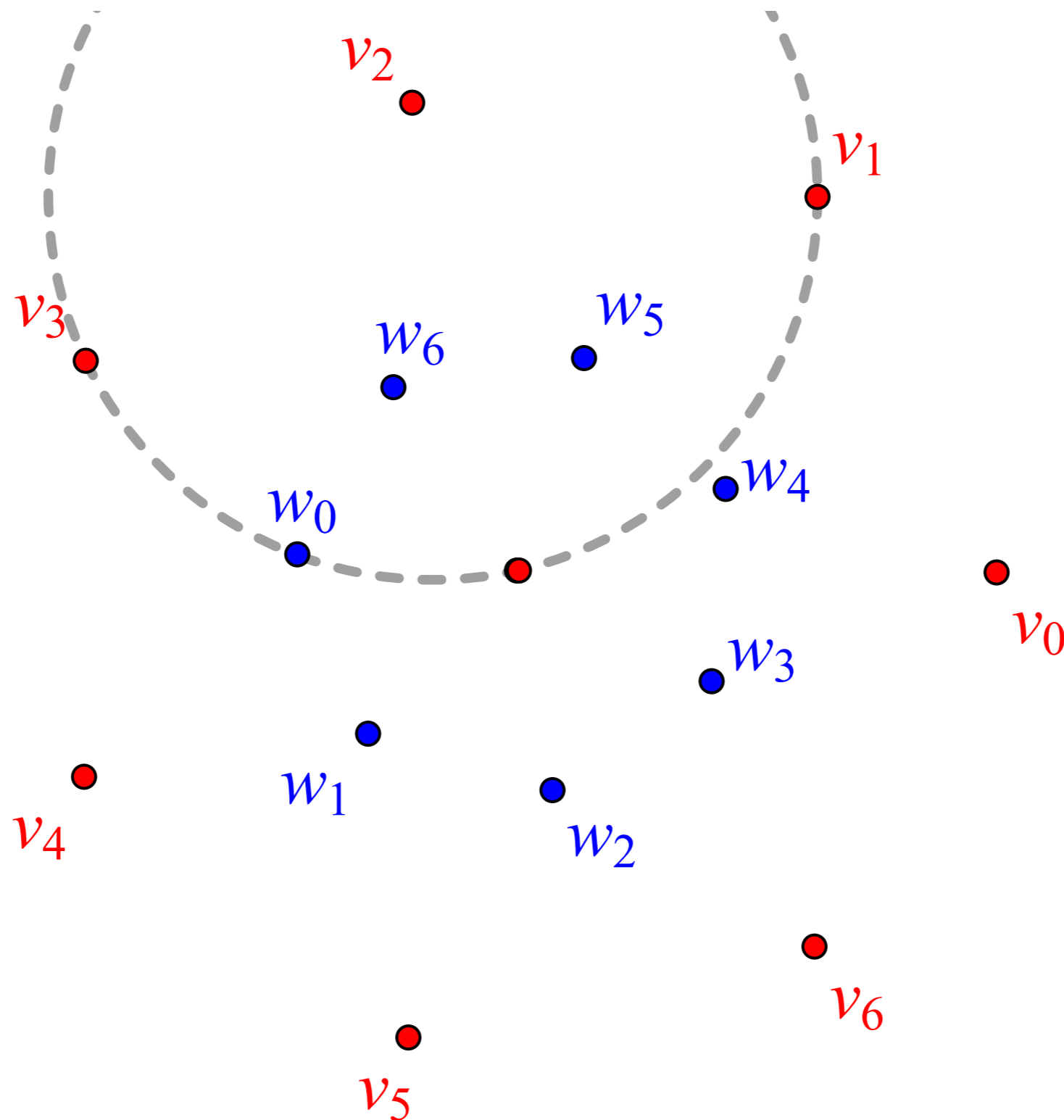


$w_0$  on  
circle  
through  
 $v_a, v_{a-d}, O$   
 $\Leftrightarrow$   
line  
through  
 $w_0, w_d$   
passes  
through  $v_a$

# CONFIGURATION CONSTRUCTION LEMMA

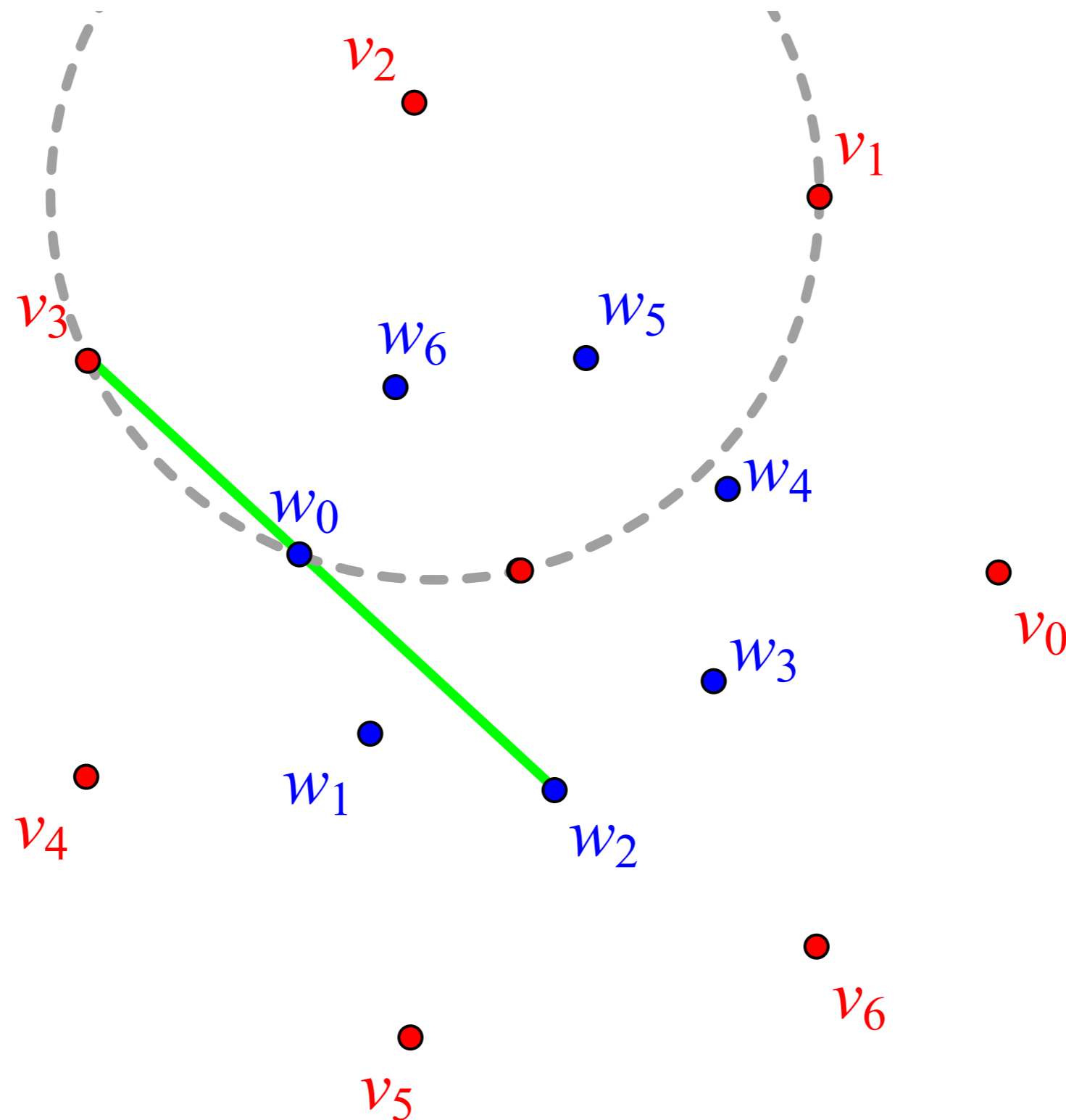


# CONFIGURATION CONSTRUCTION LEMMA



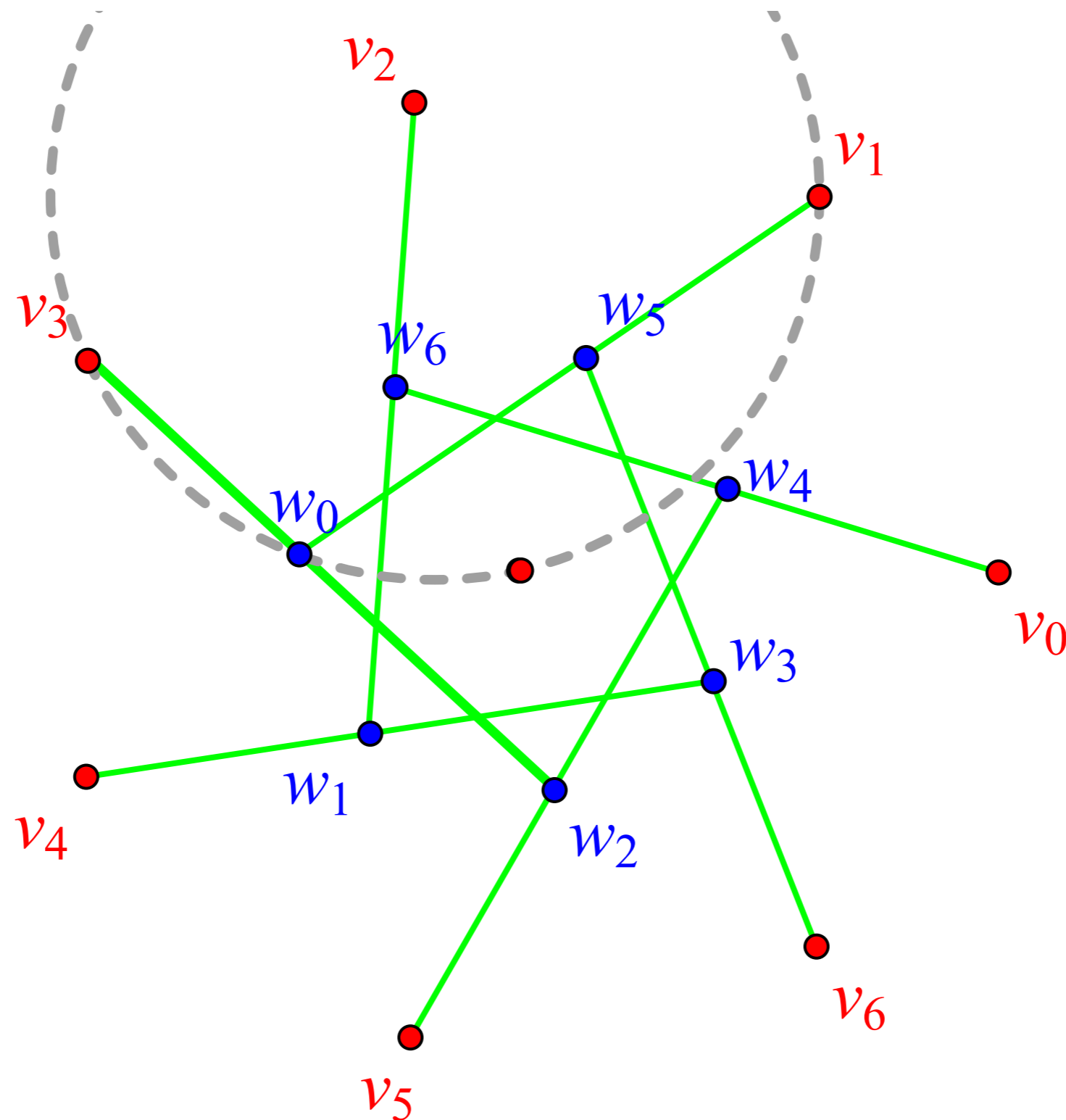
$w_0$  on  
 circle  
 through  
 $v_a, v_{a-d}, O$   
 $\iff$   
 line  
 through  
 $w_0, w_d$   
 passes  
 through  $v_a$

# CONFIGURATION CONSTRUCTION LEMMA



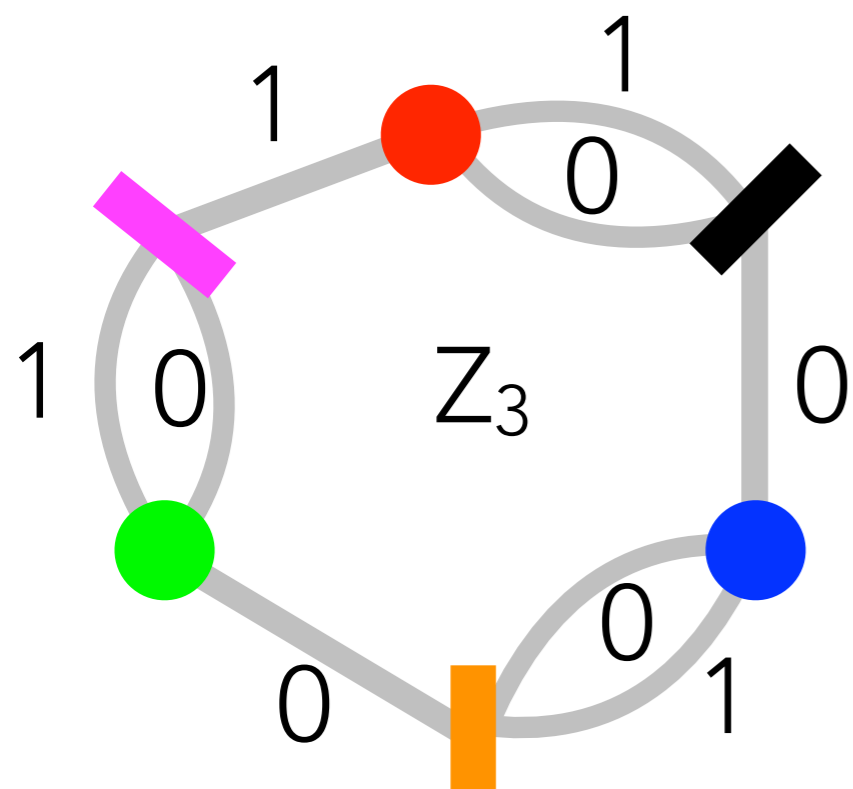
$w_0$  on  
 circle  
 through  
 $v_a, v_{a-d}, O$   
 $\iff$   
 line  
 through  
 $w_0, w_d$   
 passes  
 through  $v_a$

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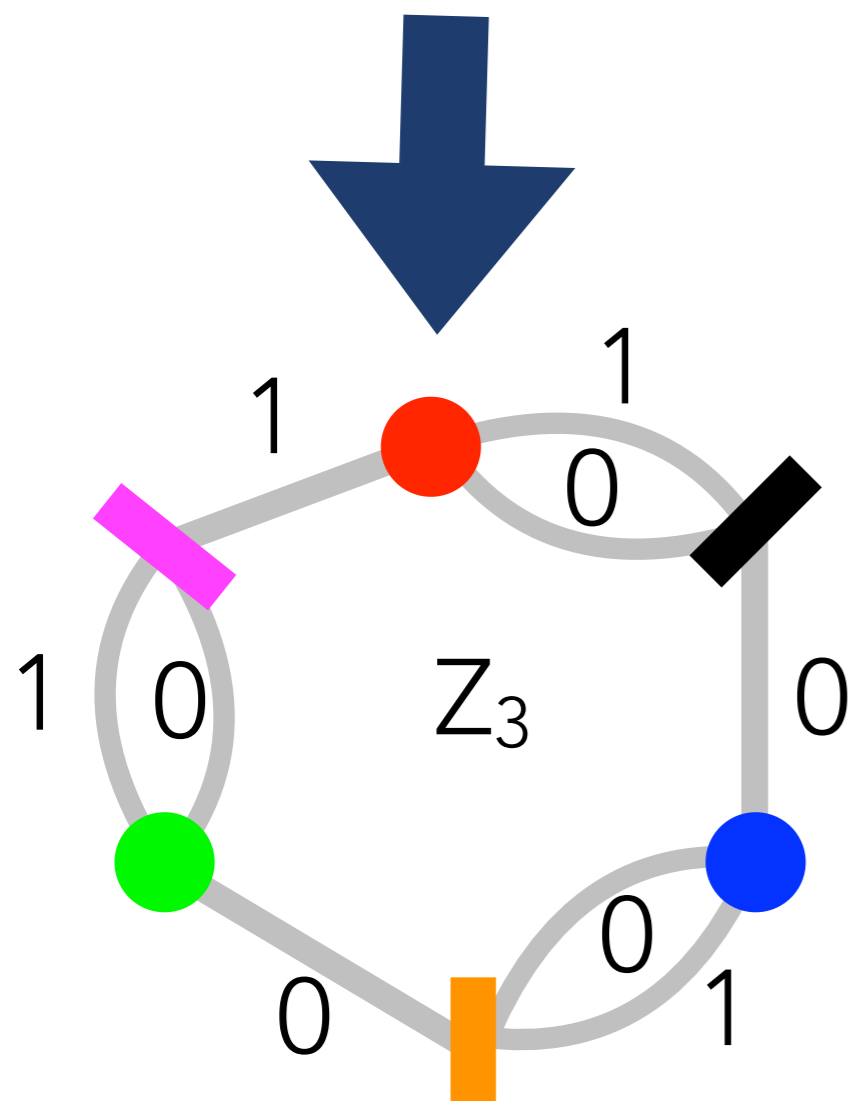


$w_0$  on  
 circle  
 through  
 $v_a, v_{a-d}, O$   
 $\iff$   
 line  
 through  
 $w_0, w_d$   
 passes  
 through  $v_a$

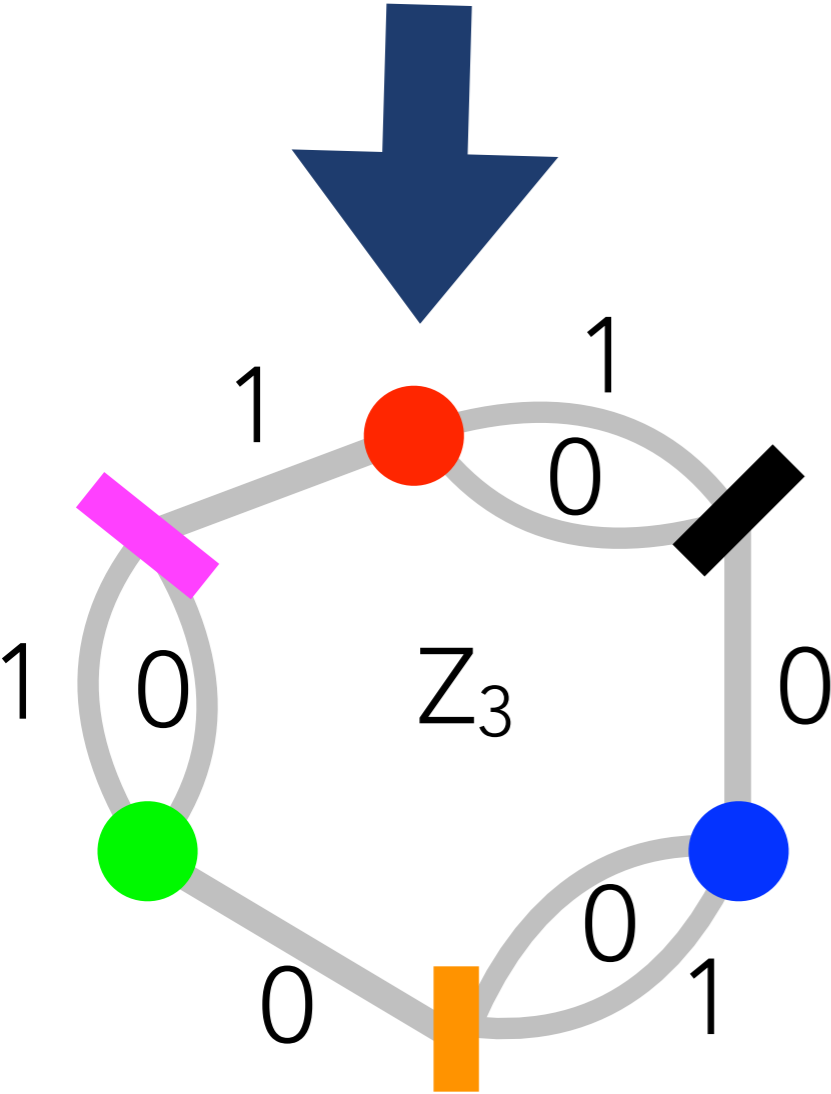
# AN EXAMPLE



# AN EXAMPLE



# AN EXAMPLE



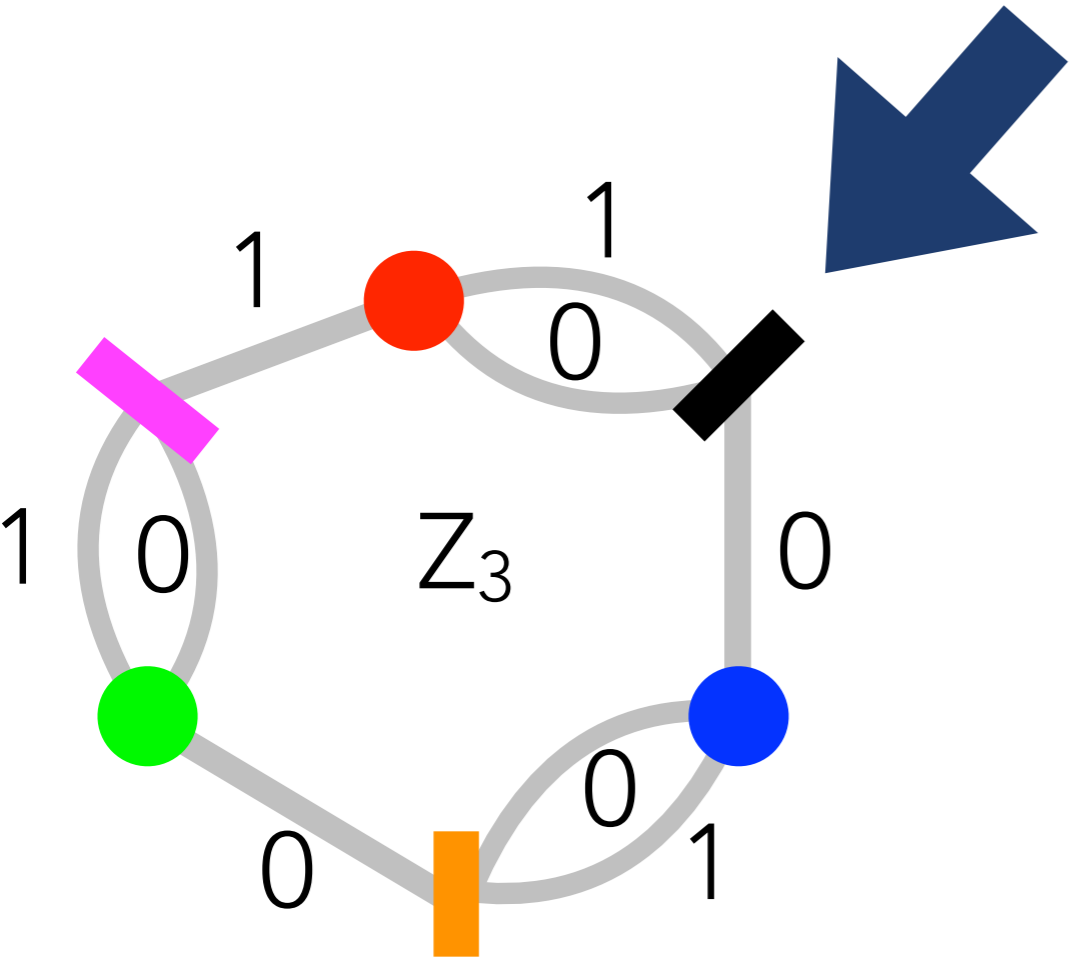
1.

.

2.

0.

# AN EXAMPLE



1

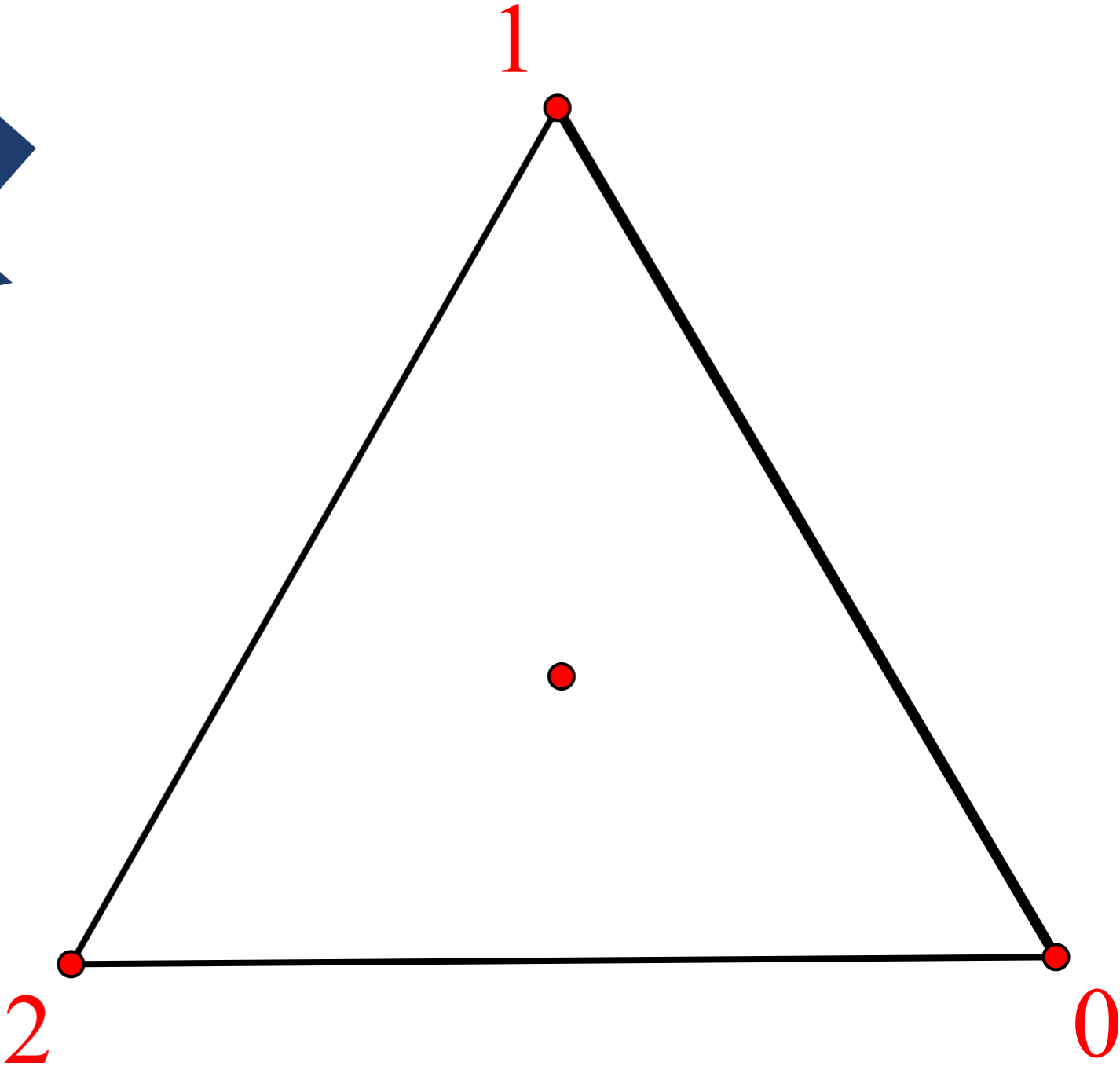
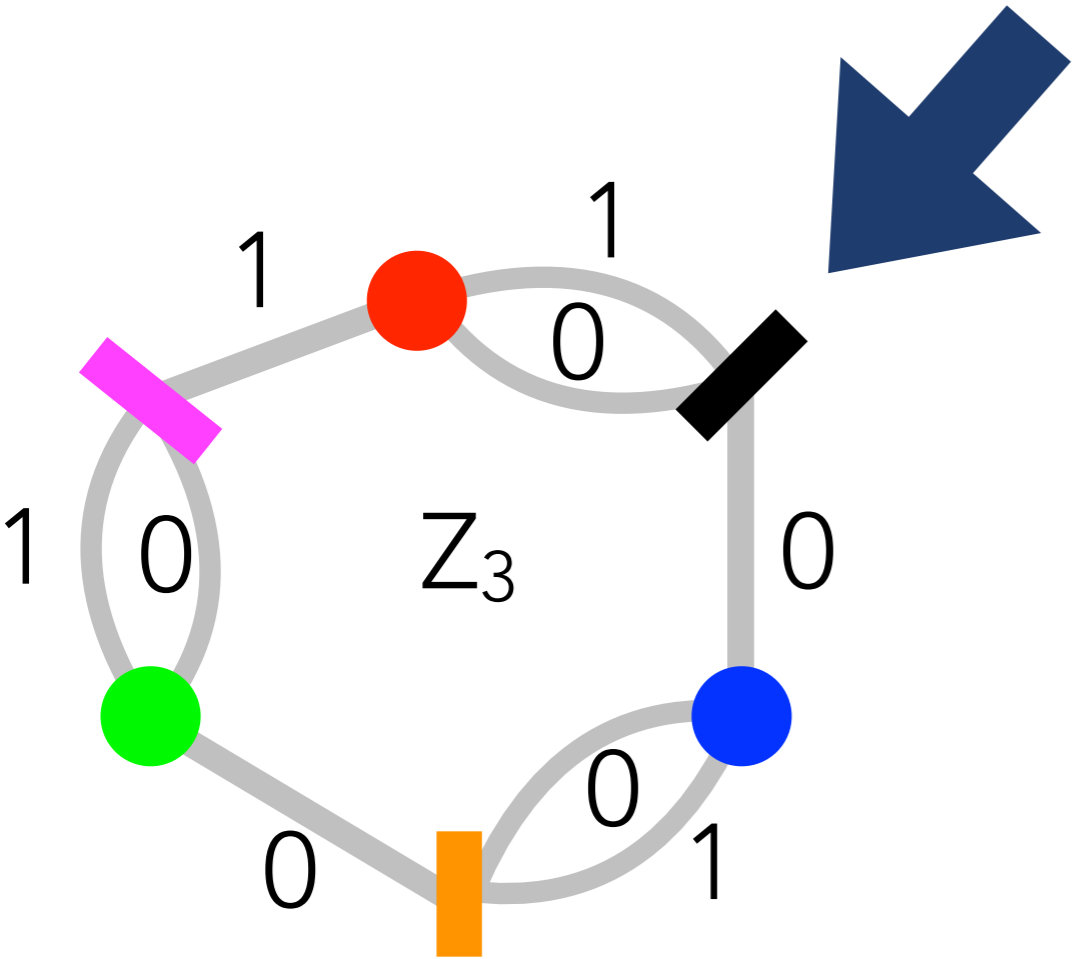


2

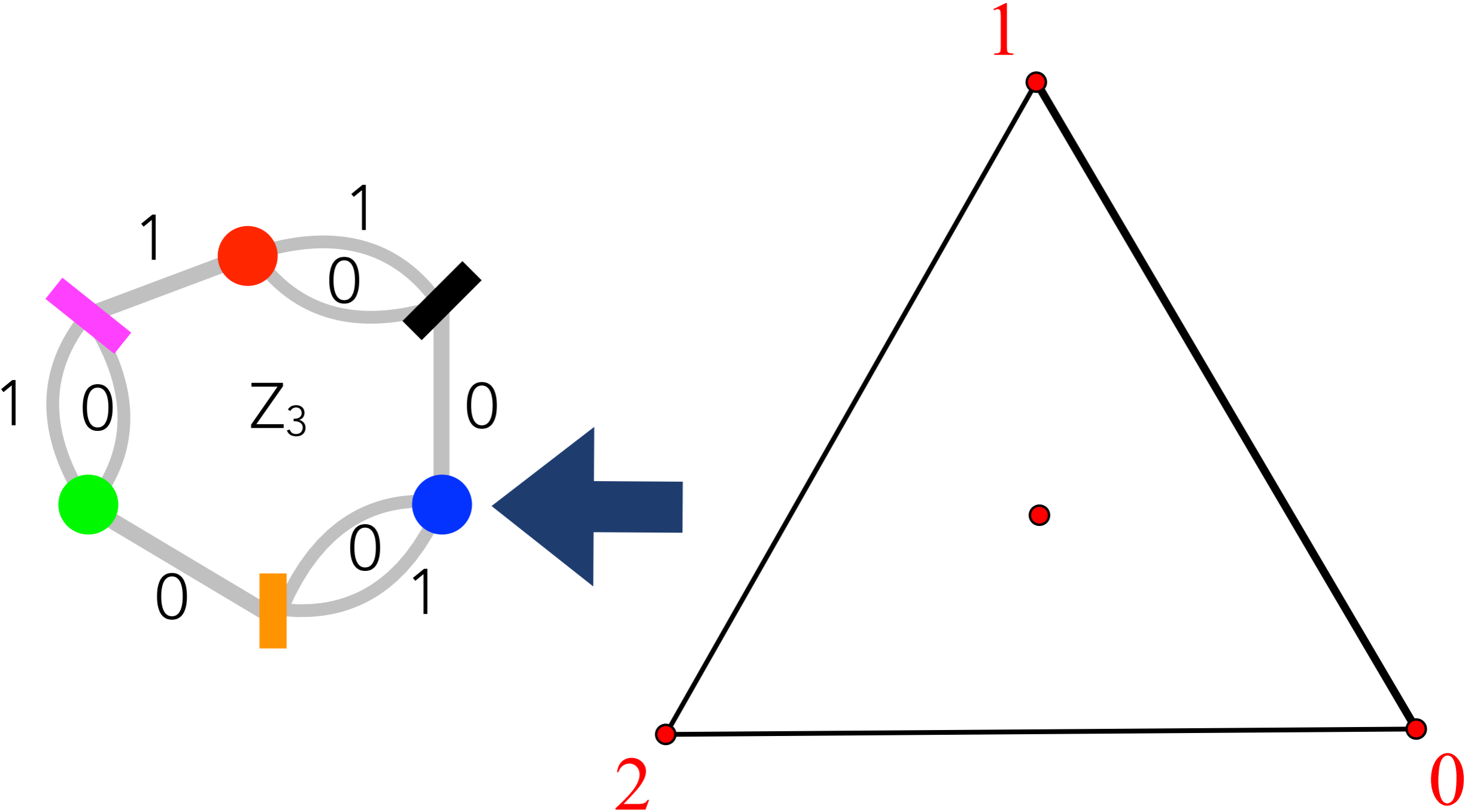


0

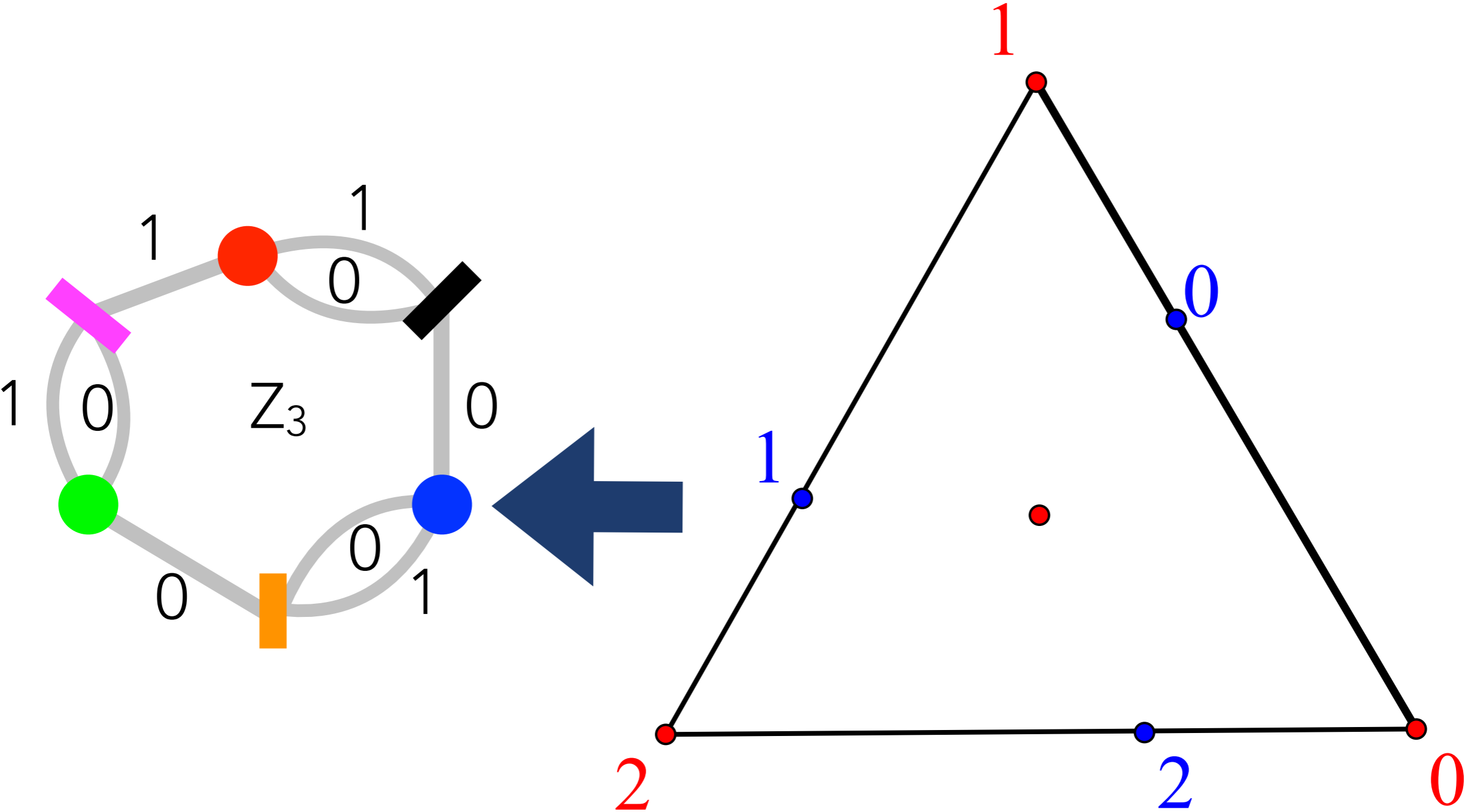
AN EXAMPLE



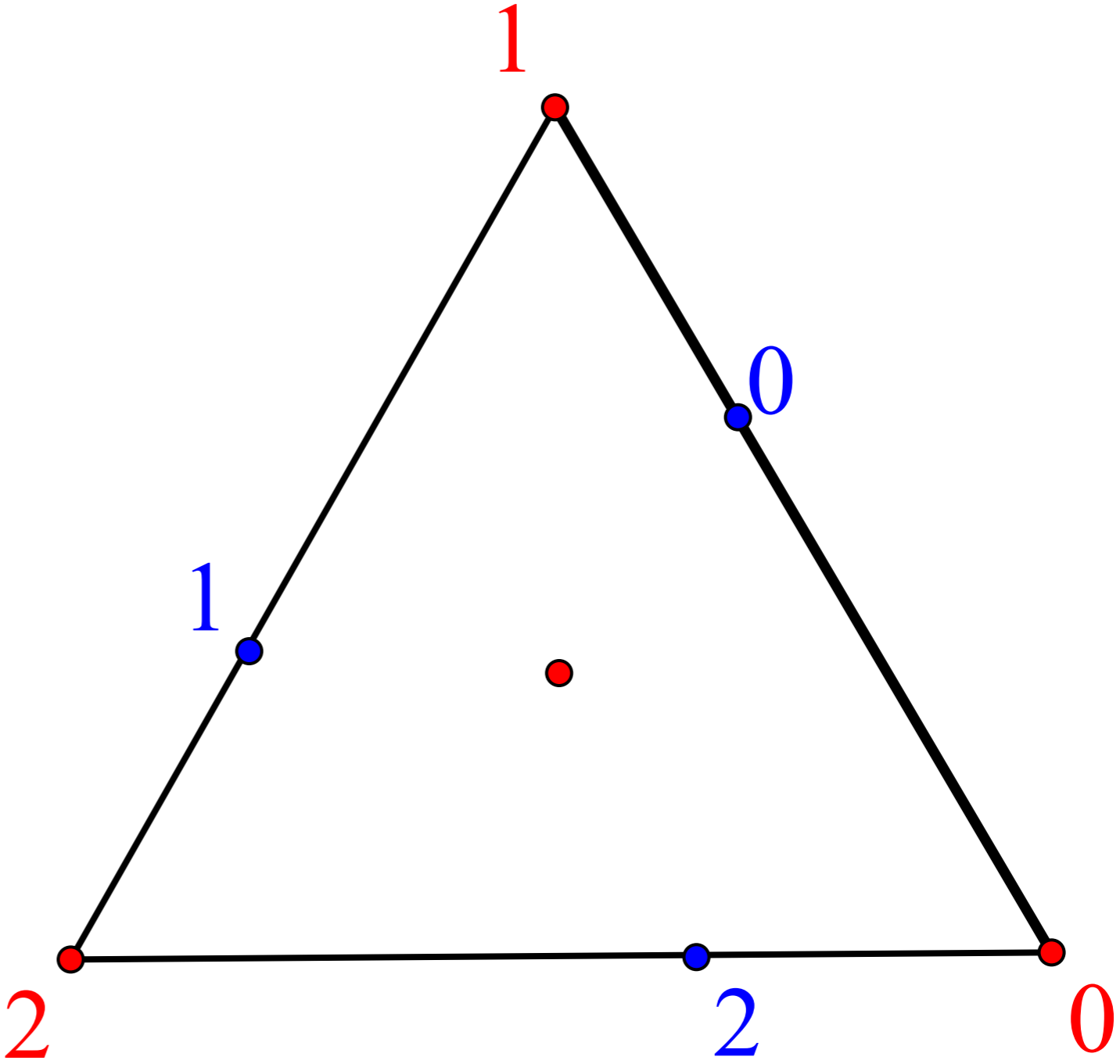
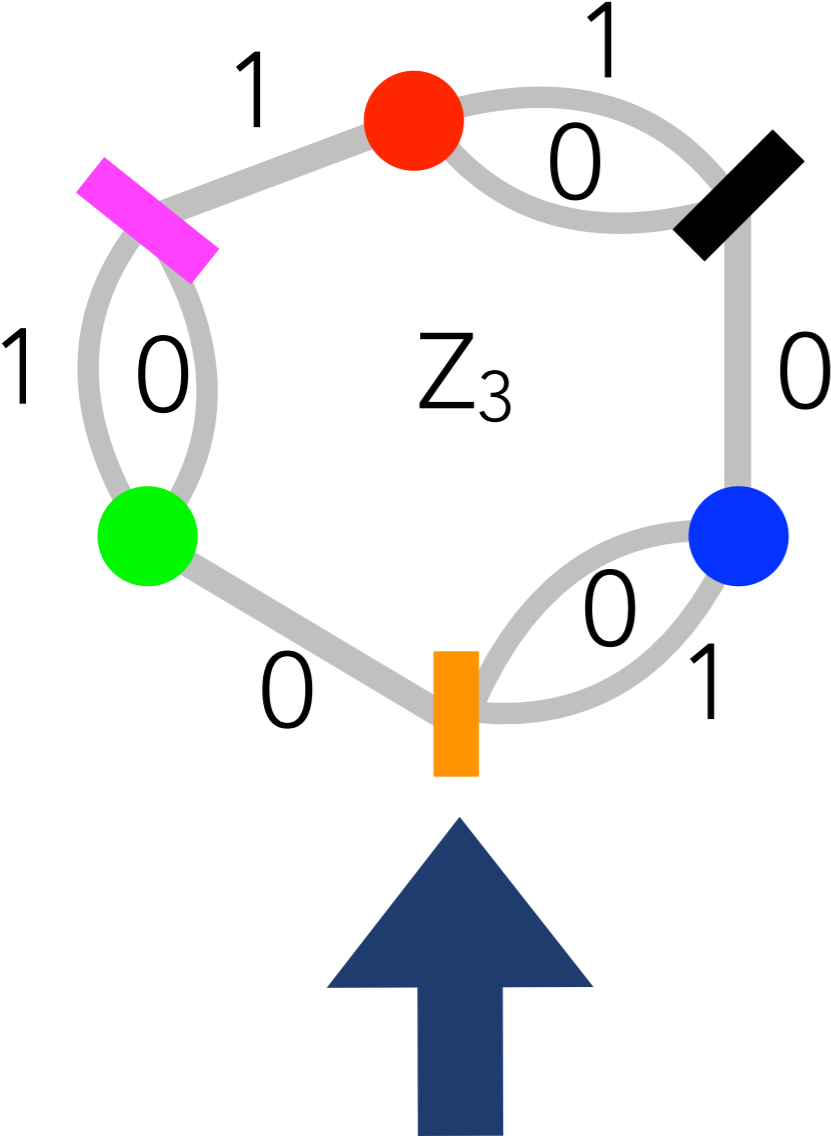
AN EXAMPLE



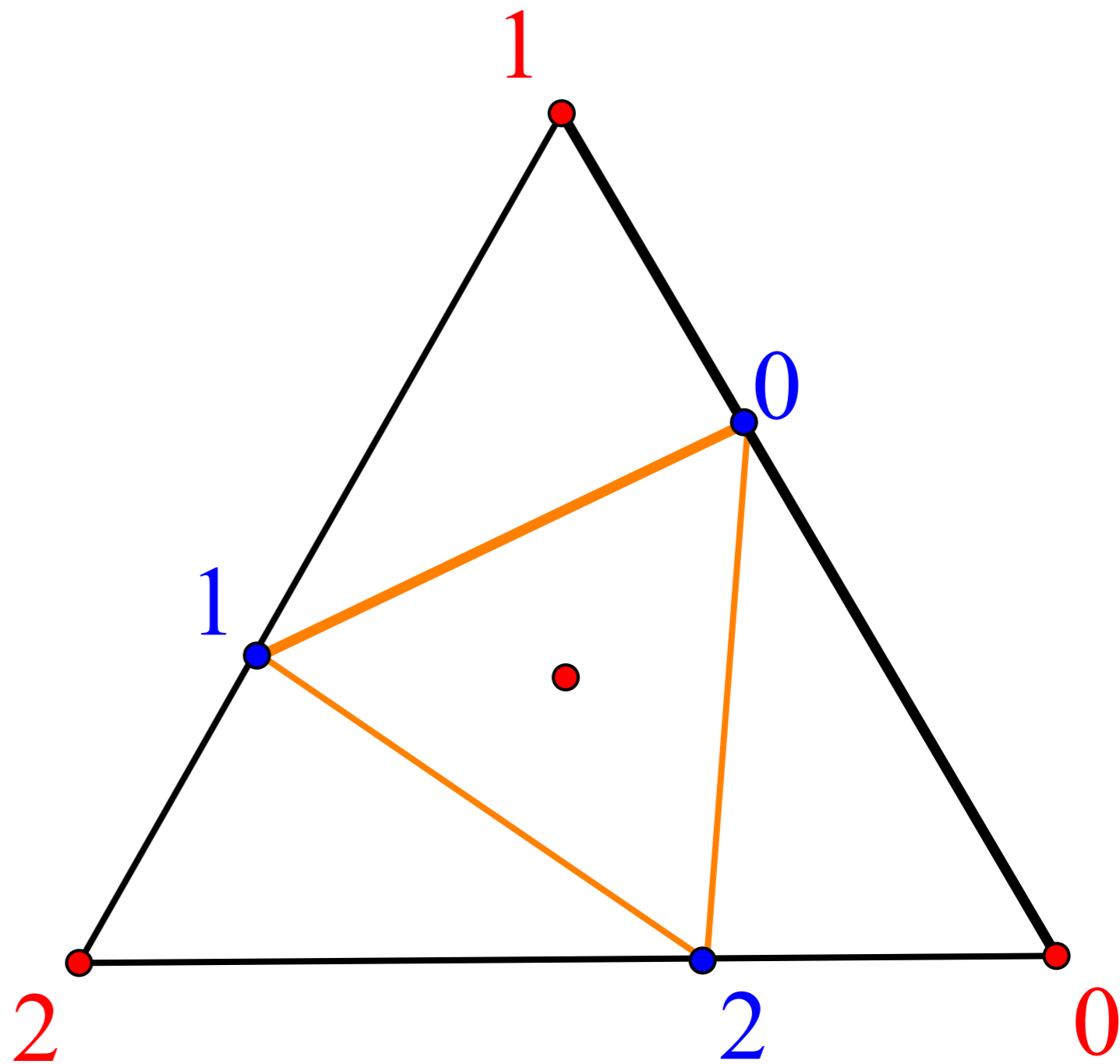
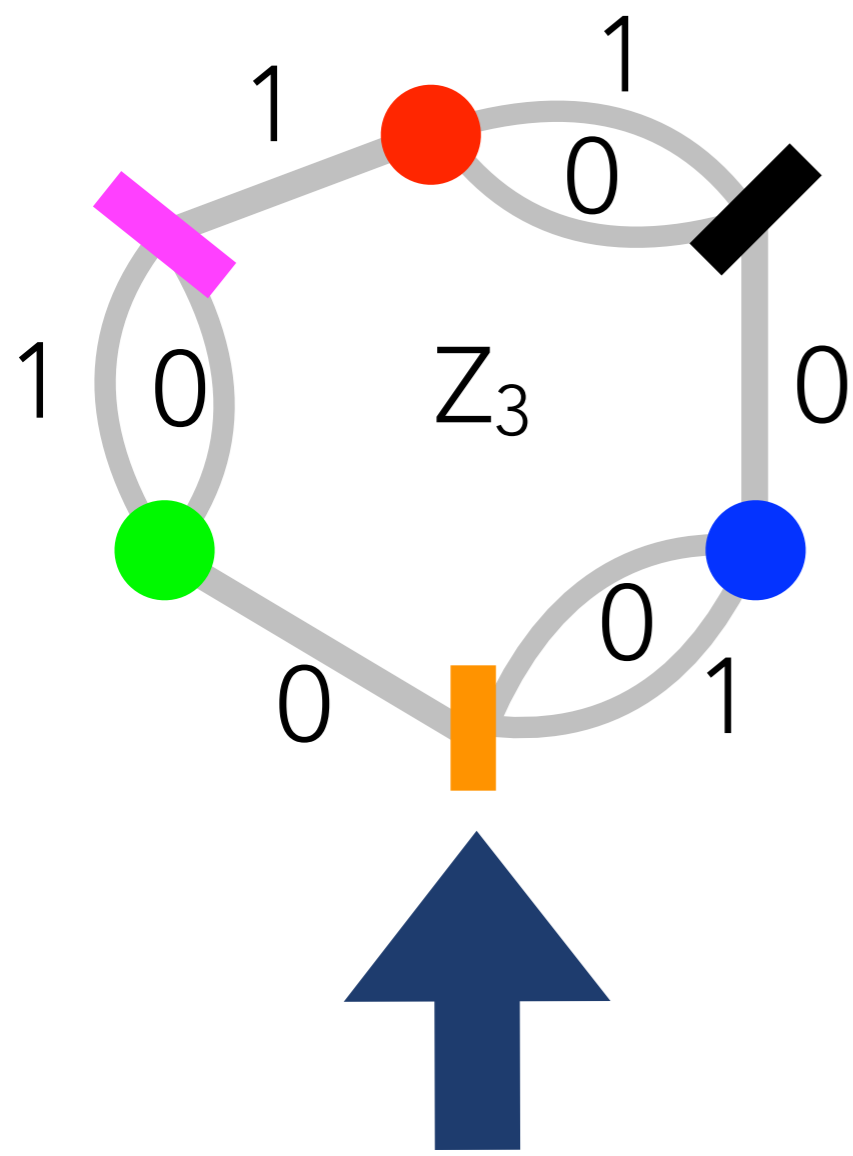
AN EXAMPLE



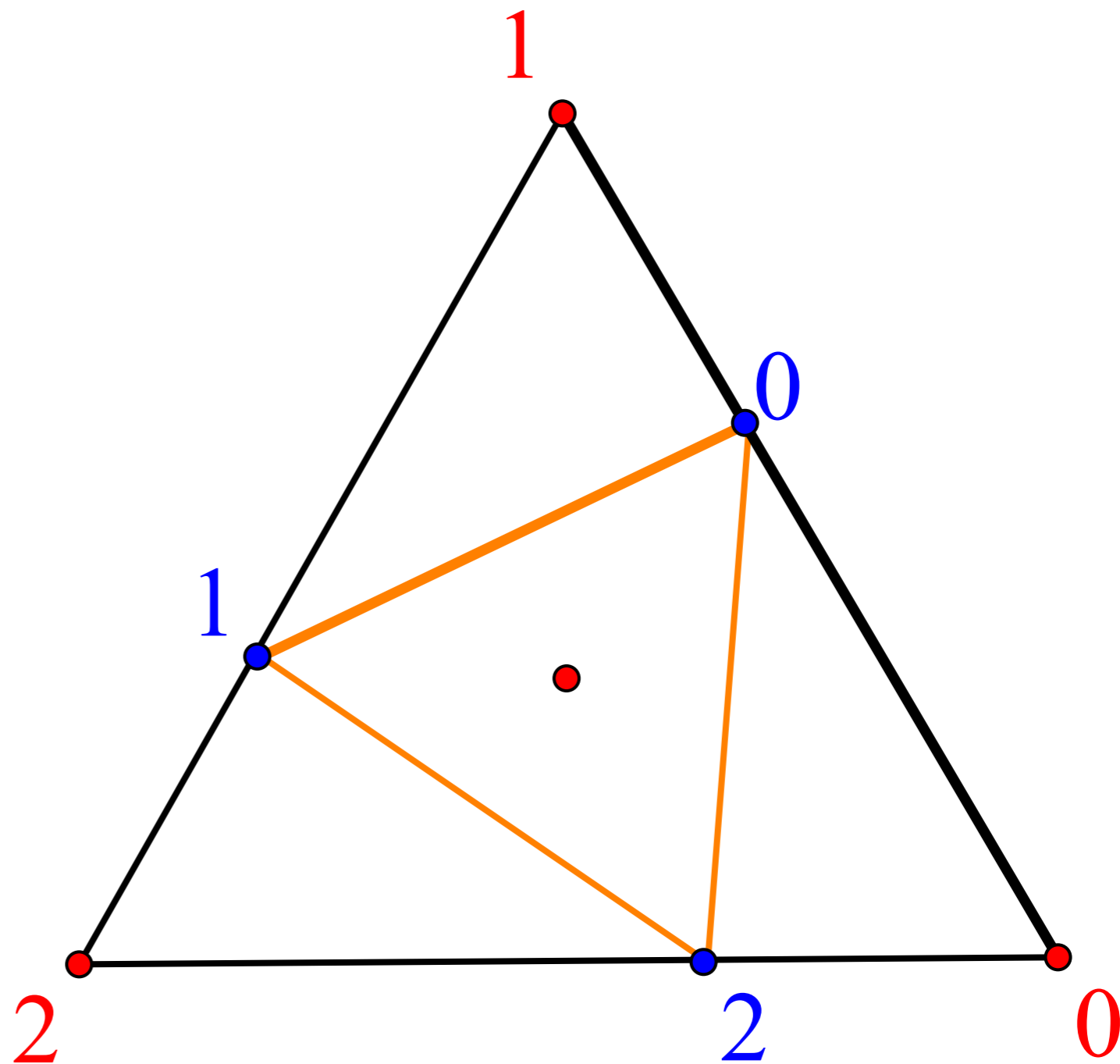
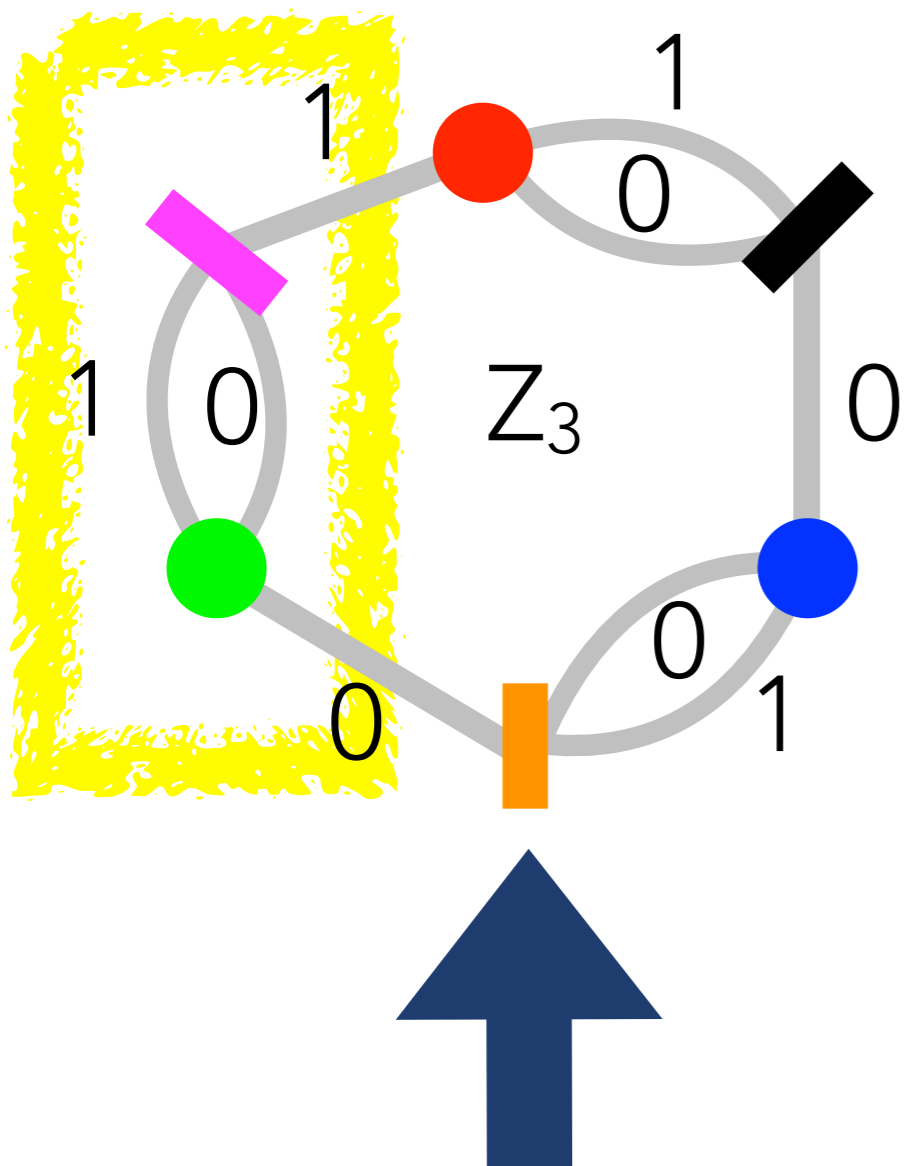
AN EXAMPLE



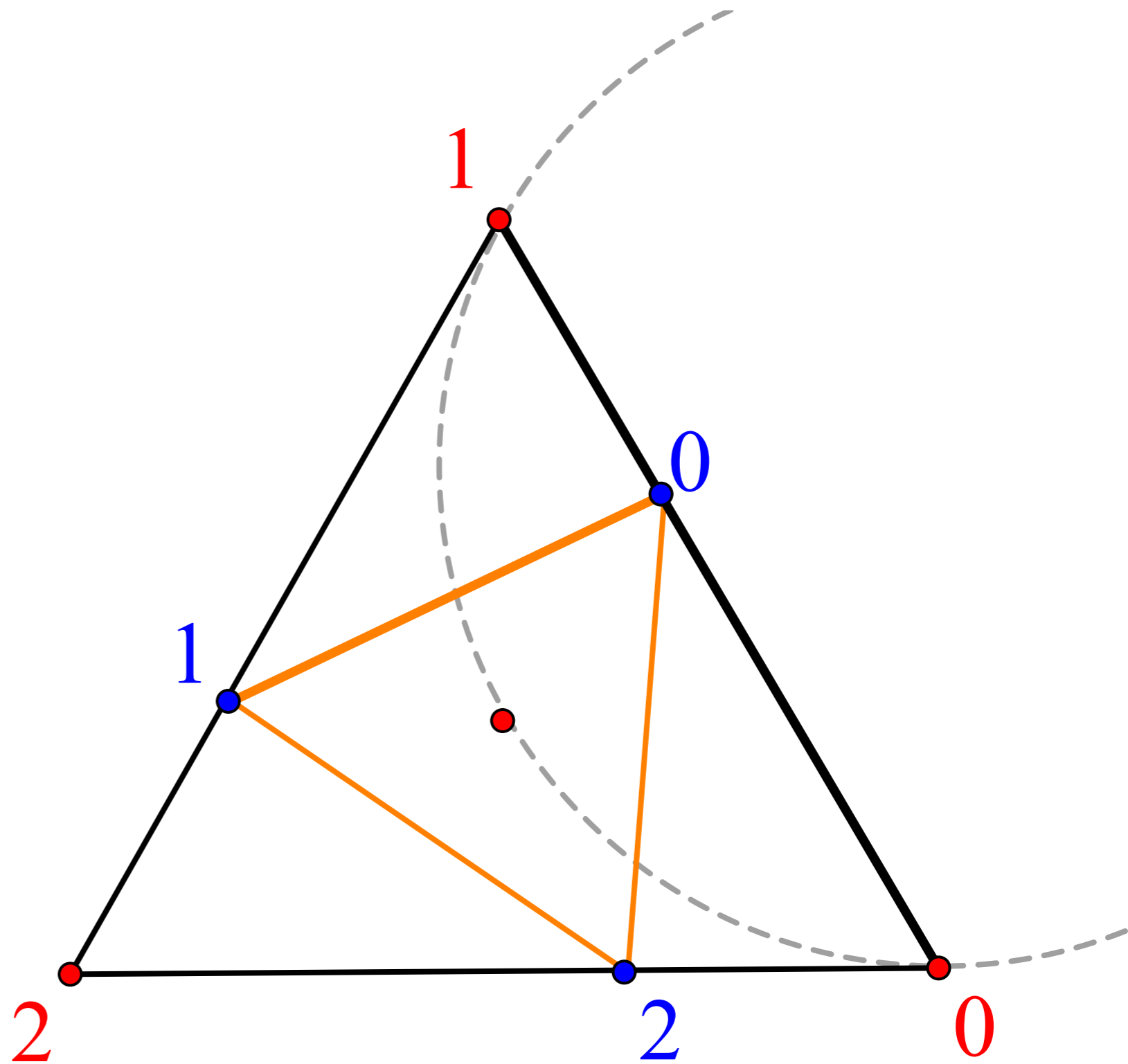
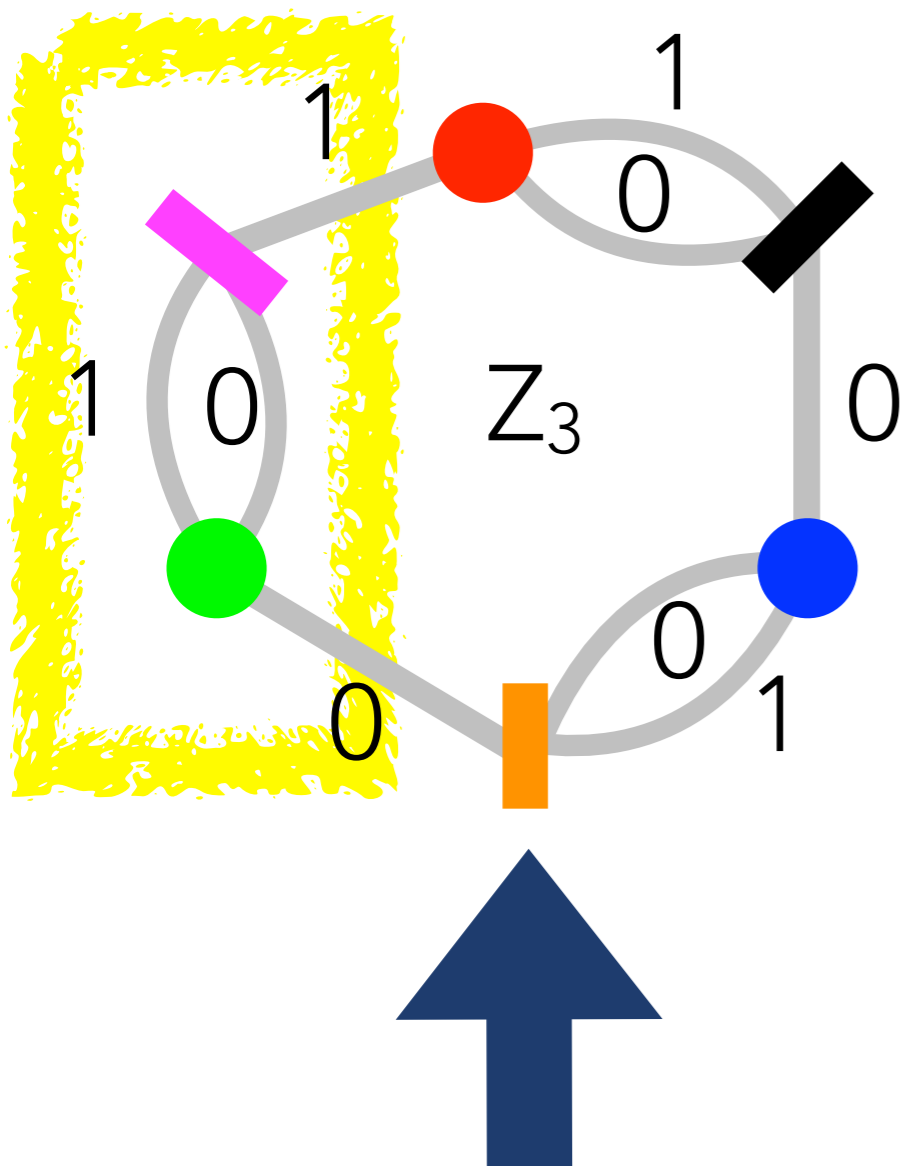
# AN EXAMPLE



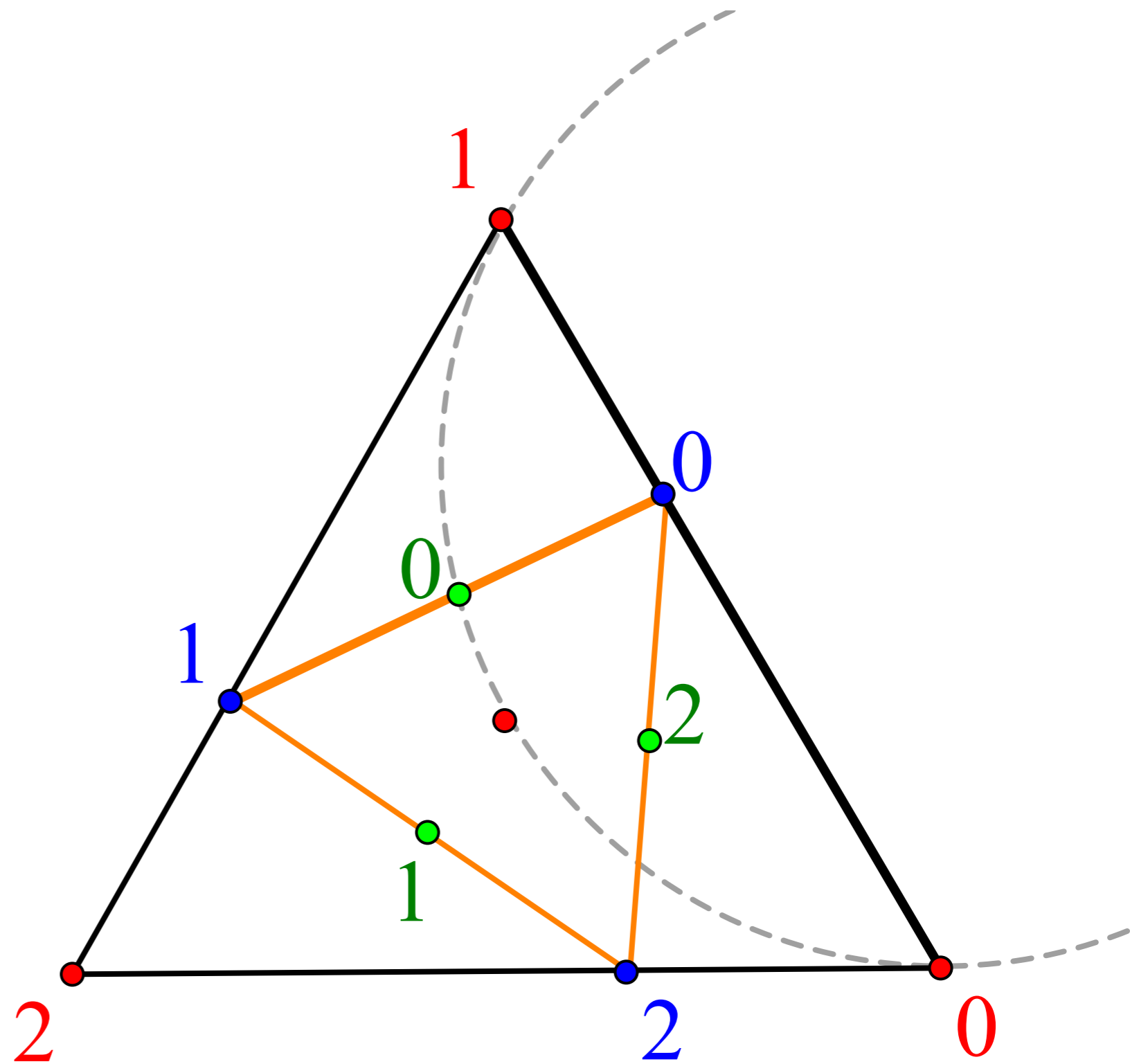
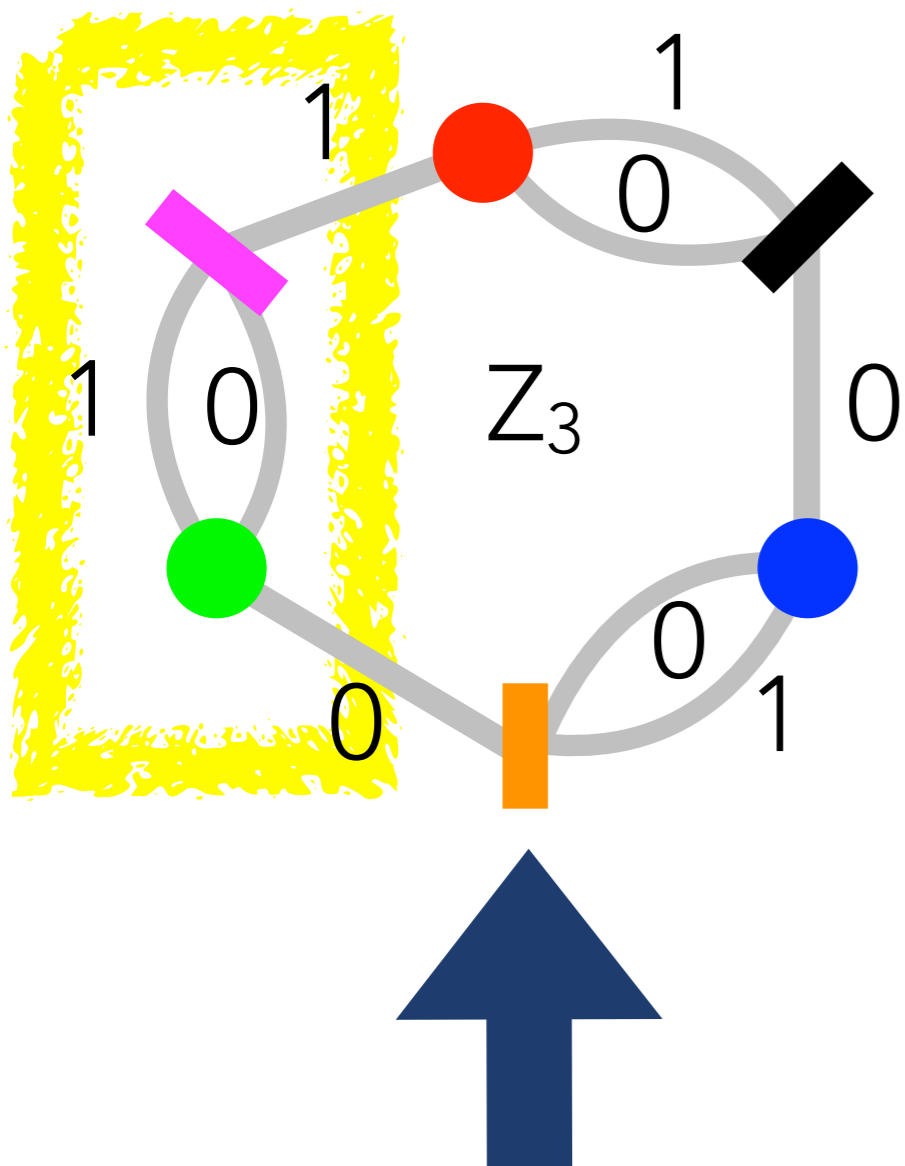
# AN EXAMPLE



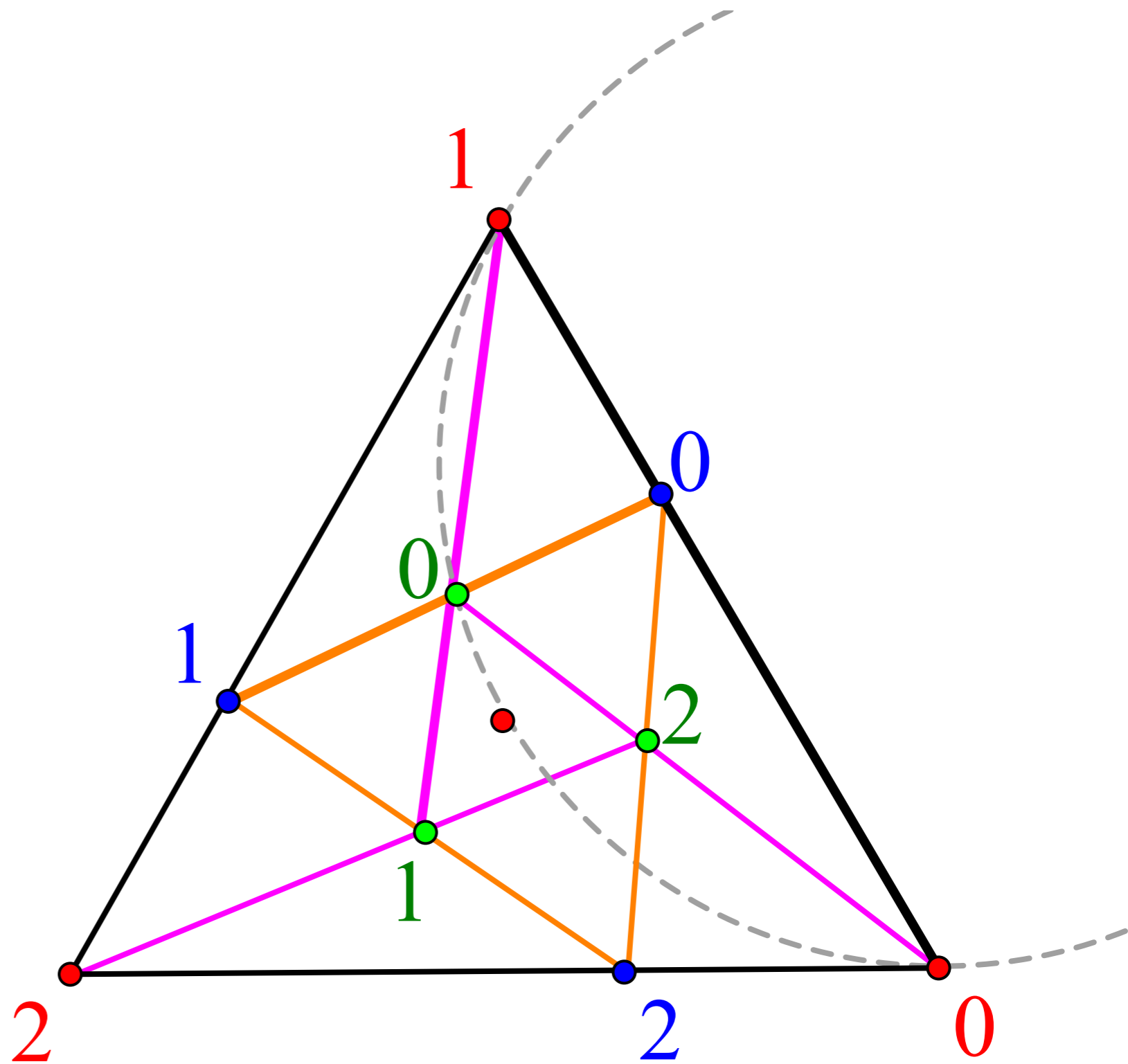
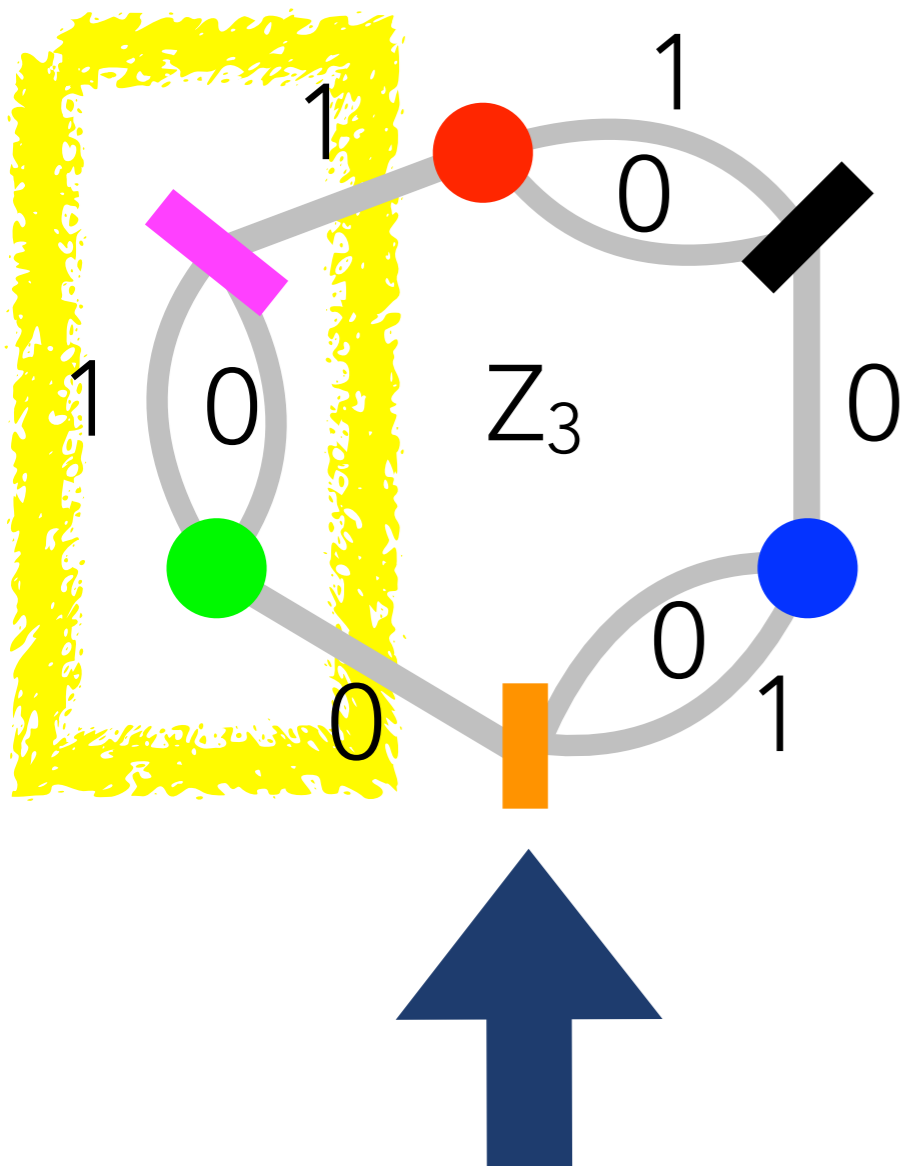
# AN EXAMPLE



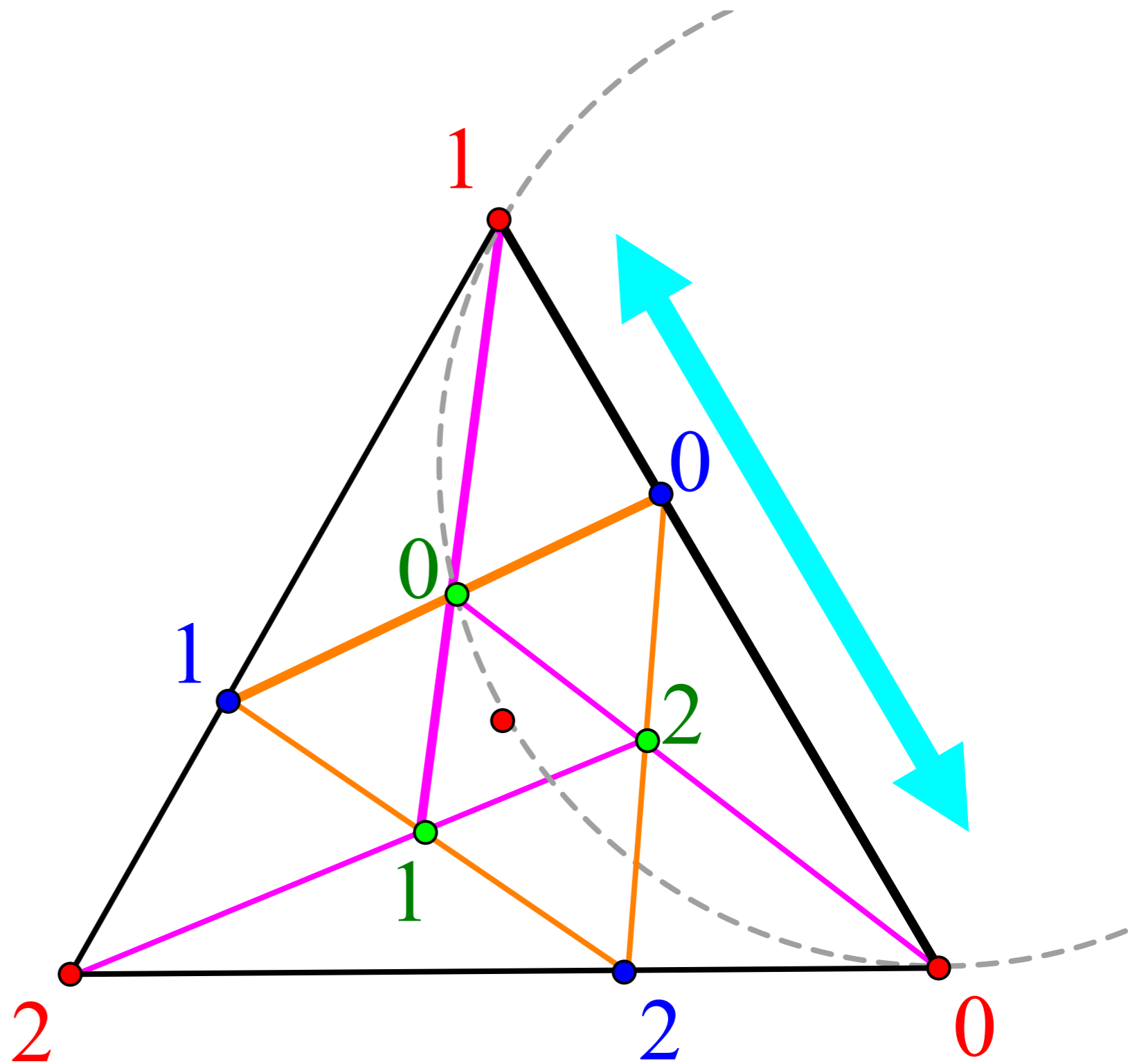
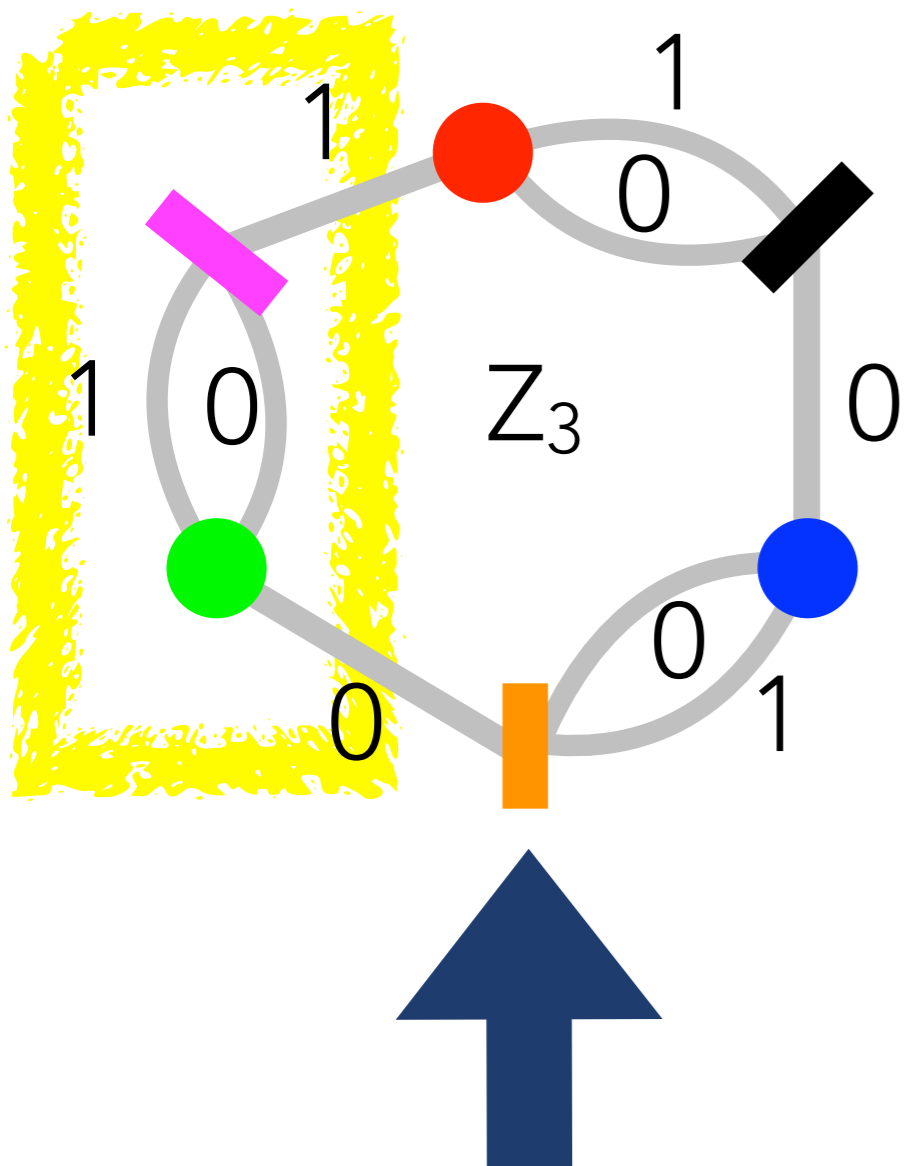
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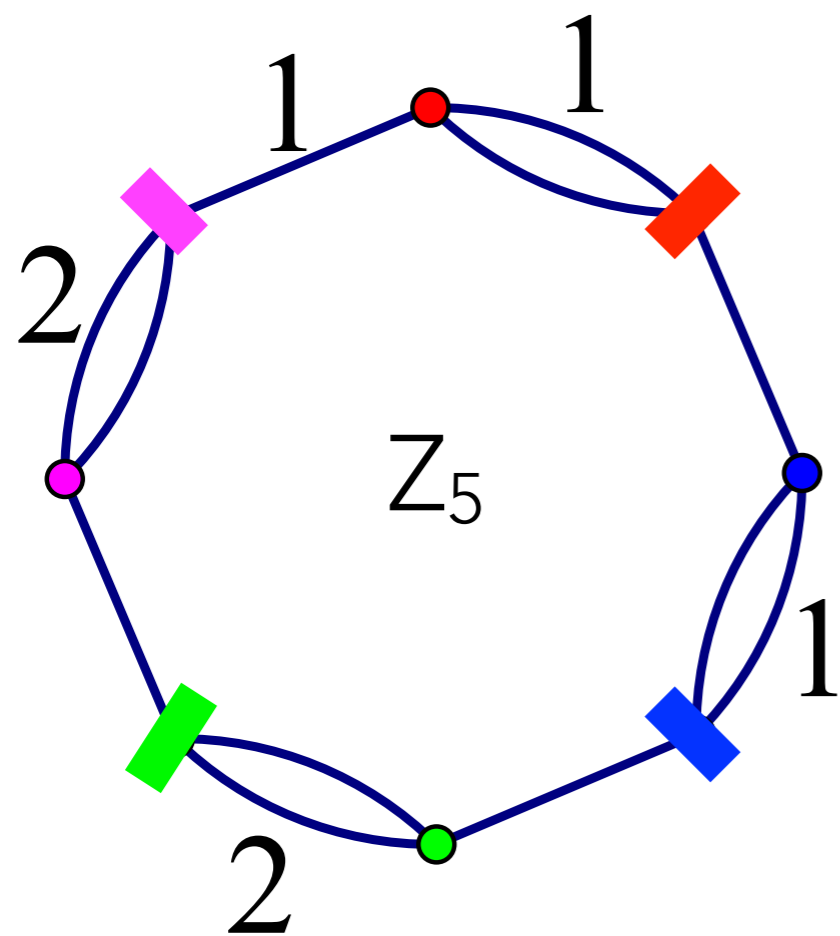
# AN EXAMPLE



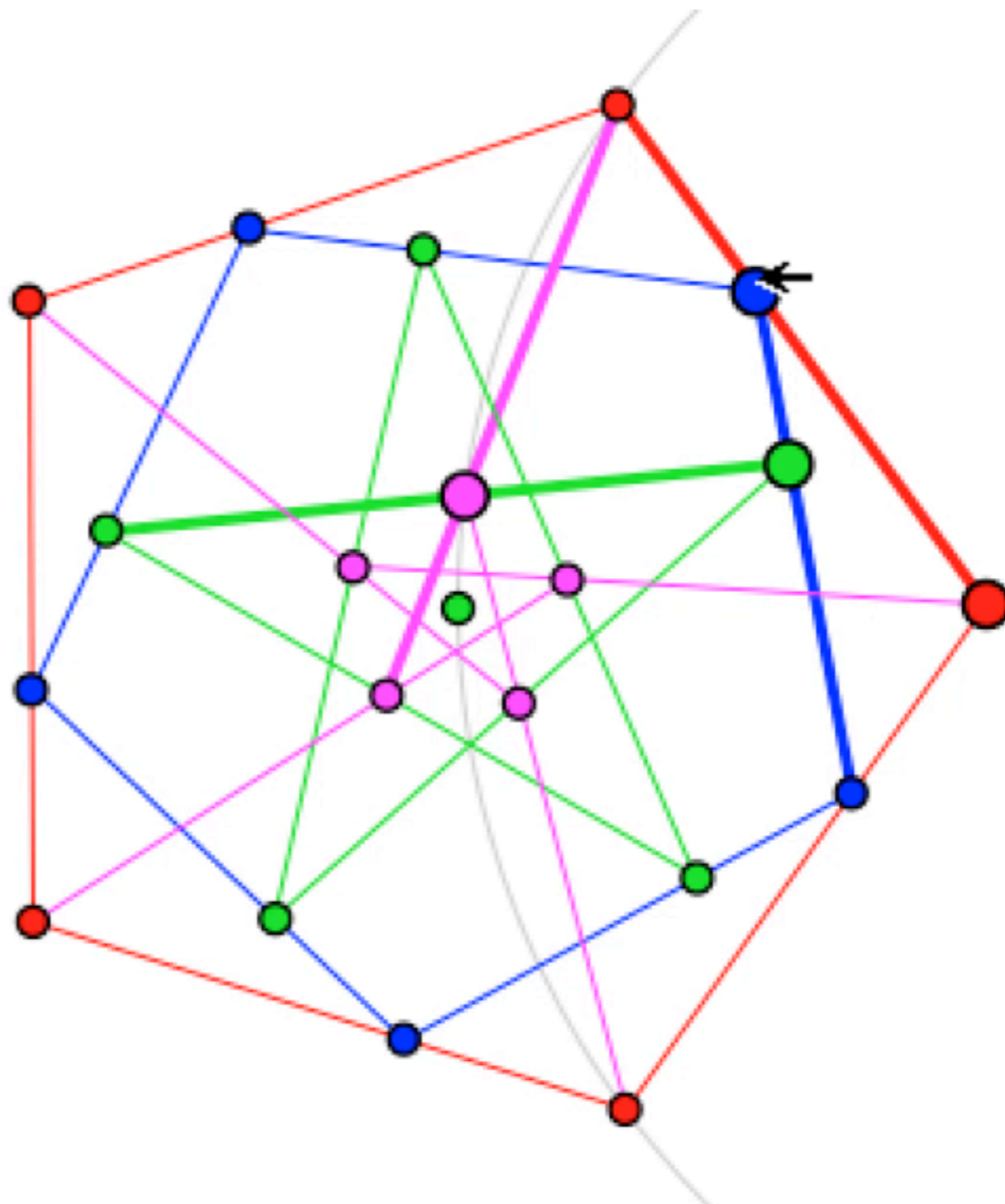
# AN EXAMPLE



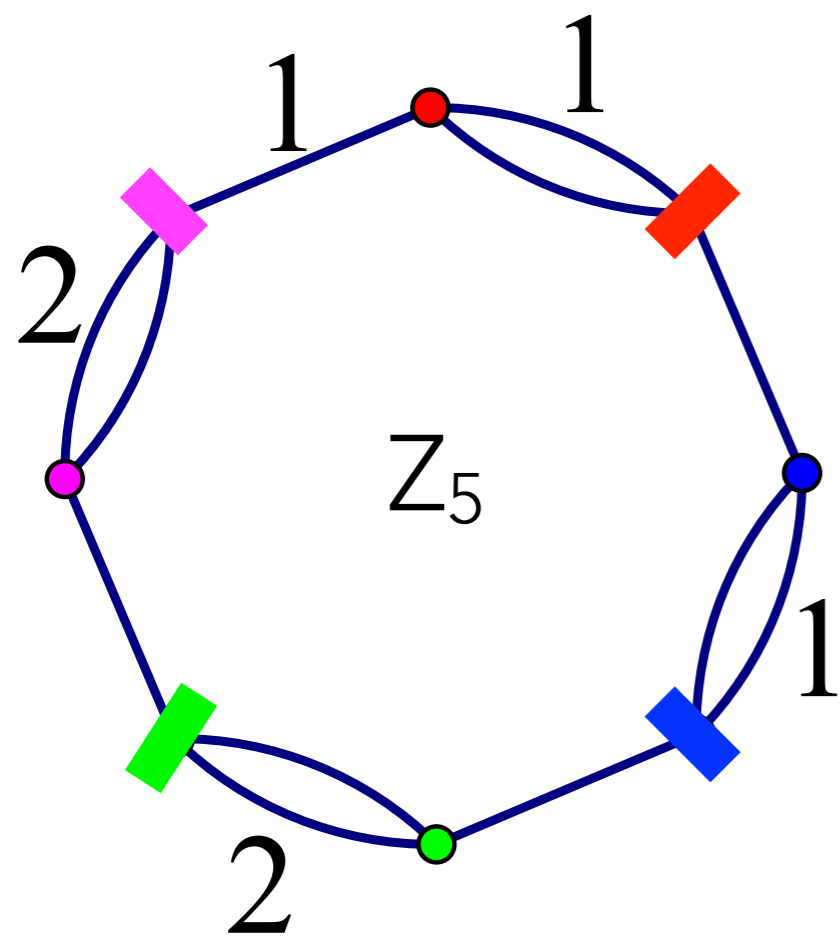
# MOVABLE 3-CONFIGURATIONS



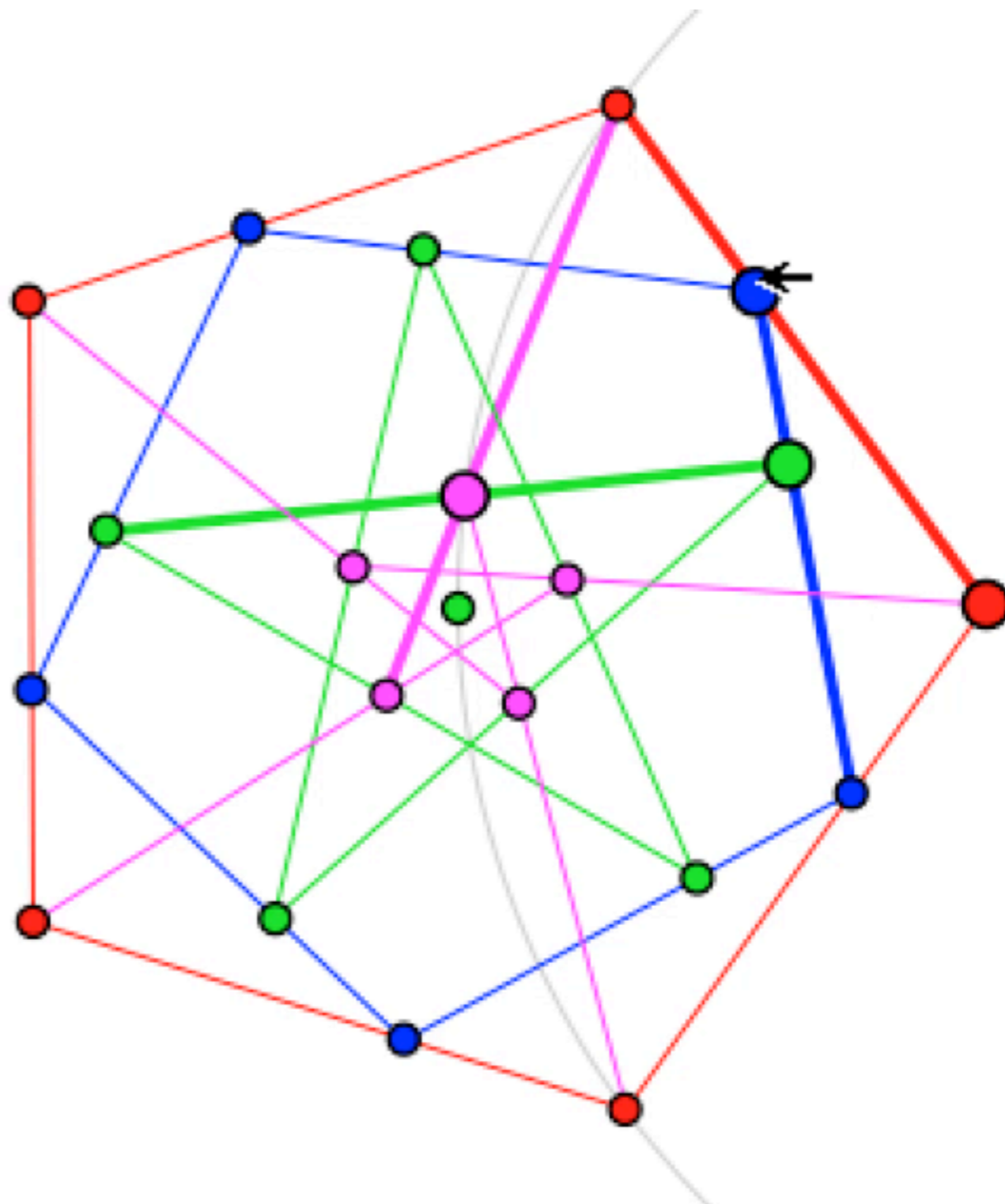
# Multilateral



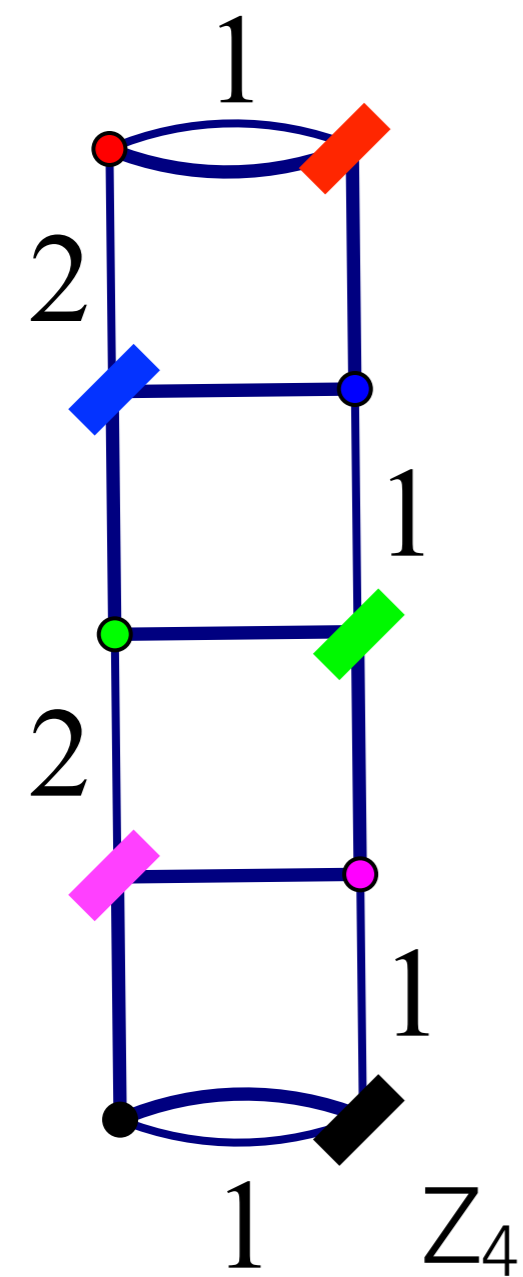
# MOVABLE 3-CONFIGURATIONS



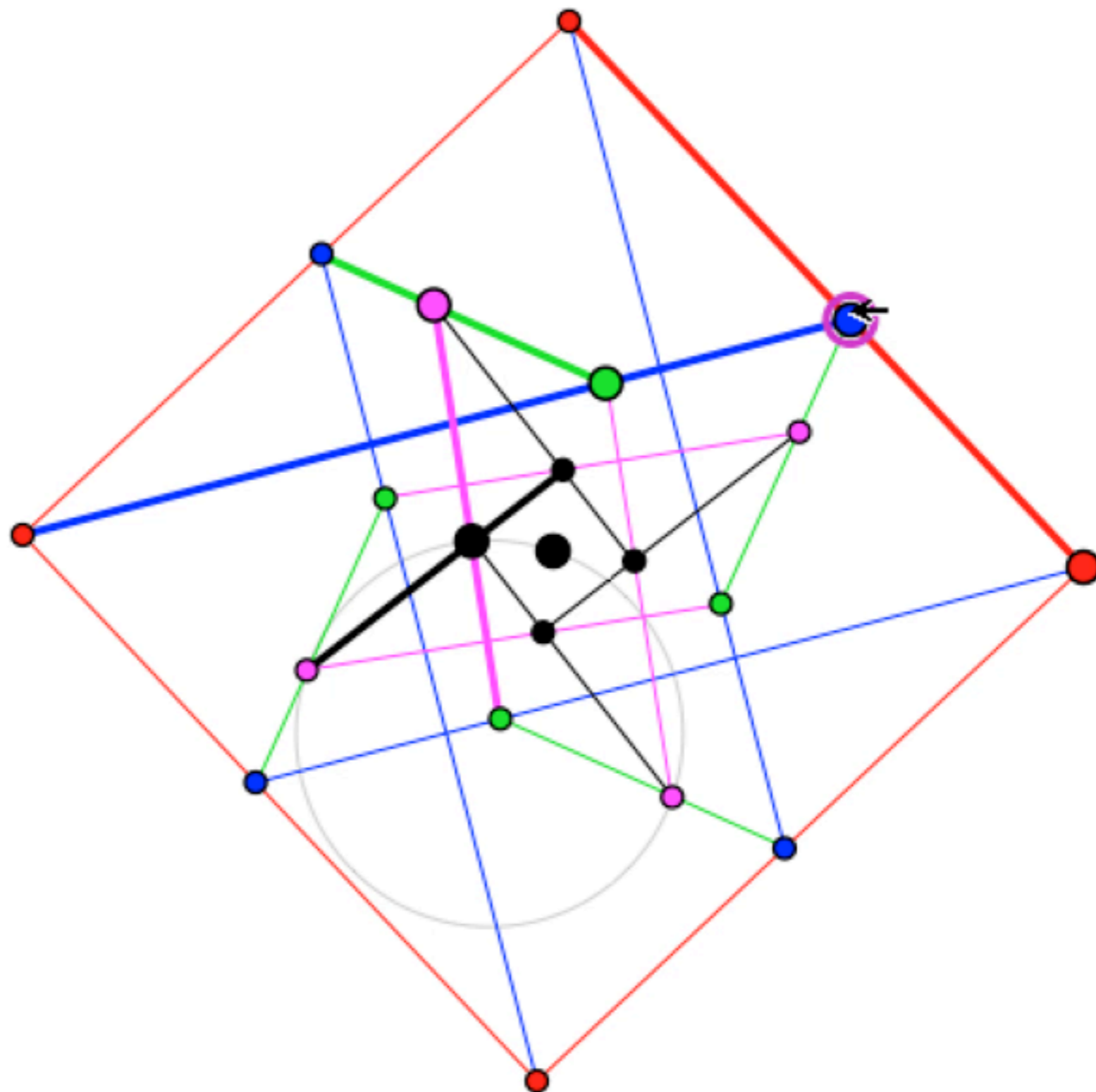
# Multilateral



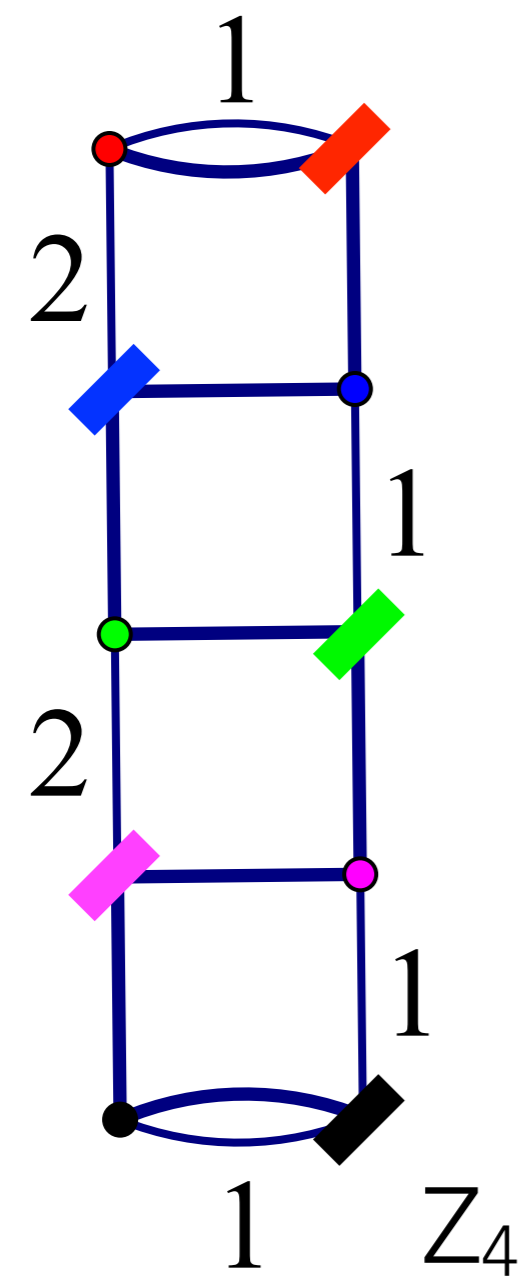
# MOVABLE 3-CONFIGURATIONS



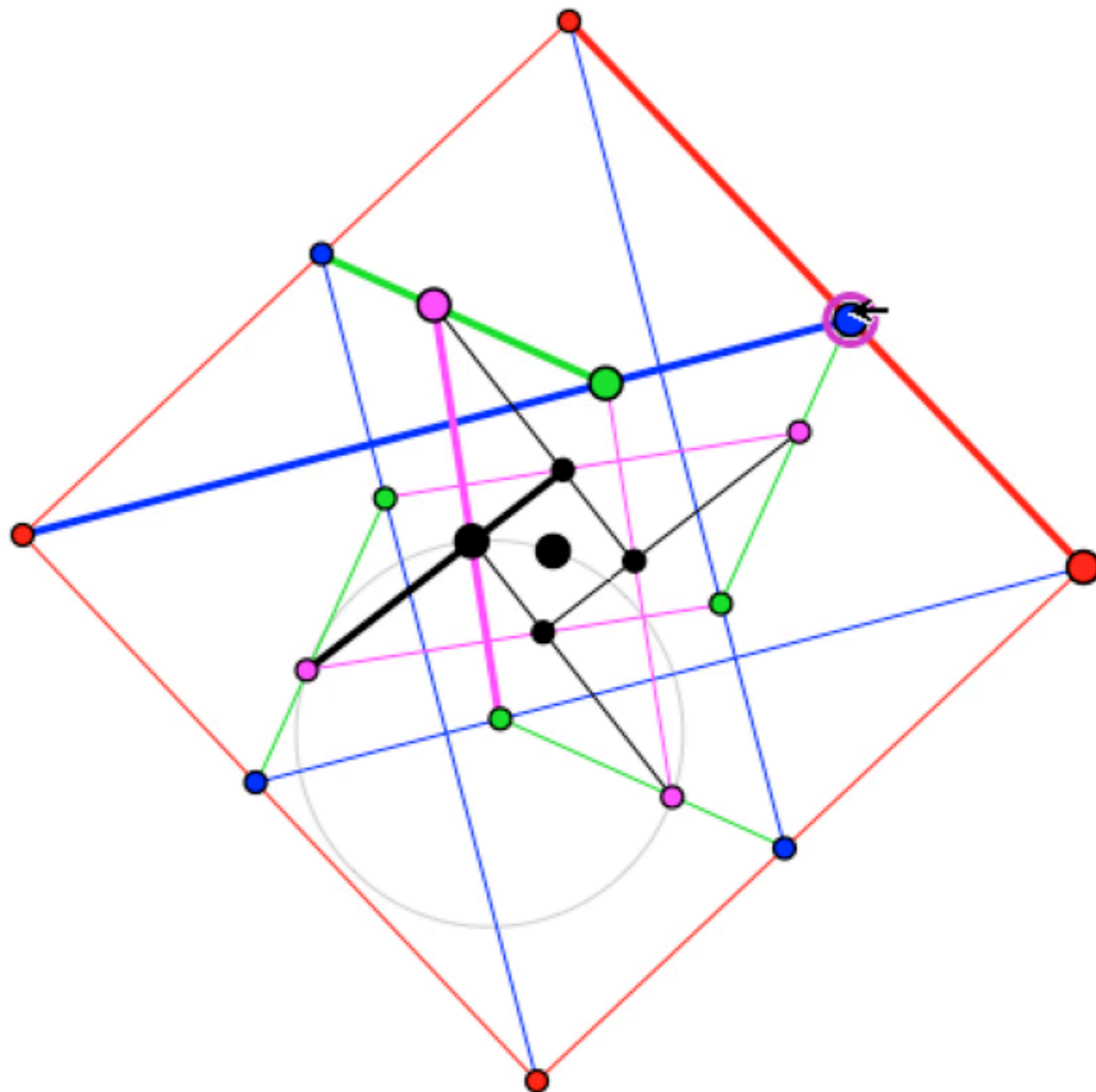
Caterpillar



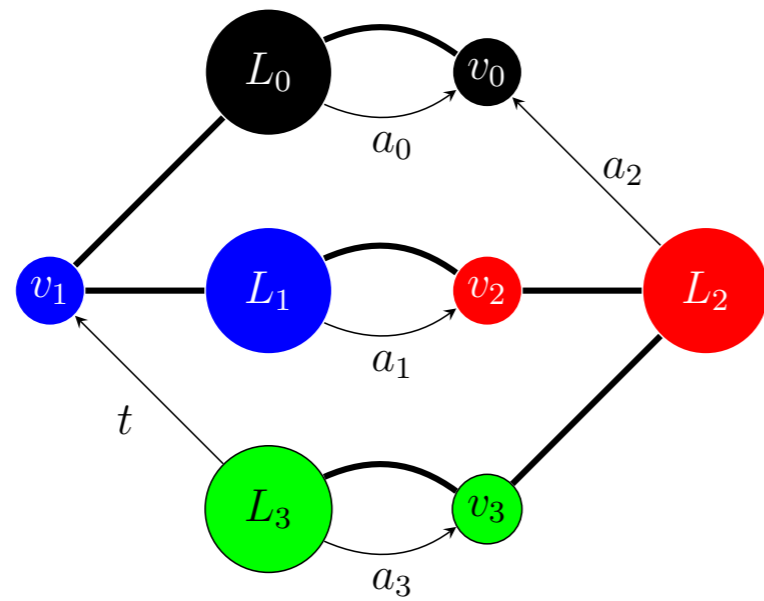
# MOVABLE 3-CONFIGURATIONS



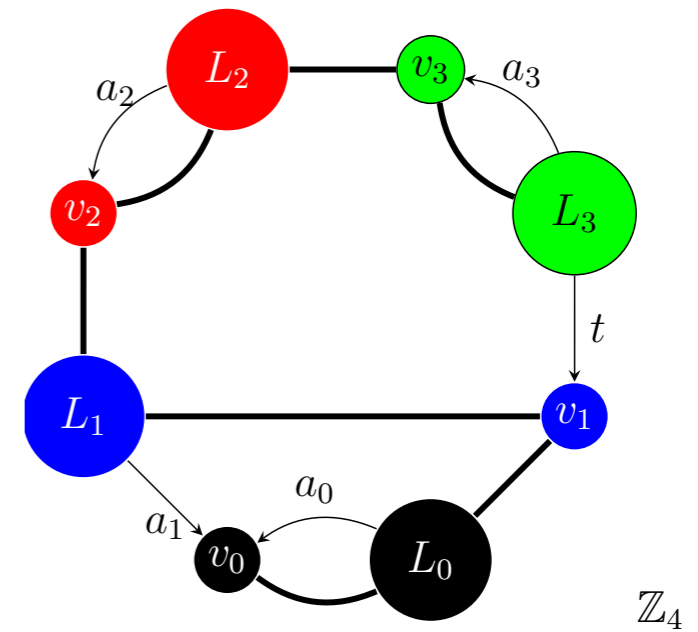
Caterpillar



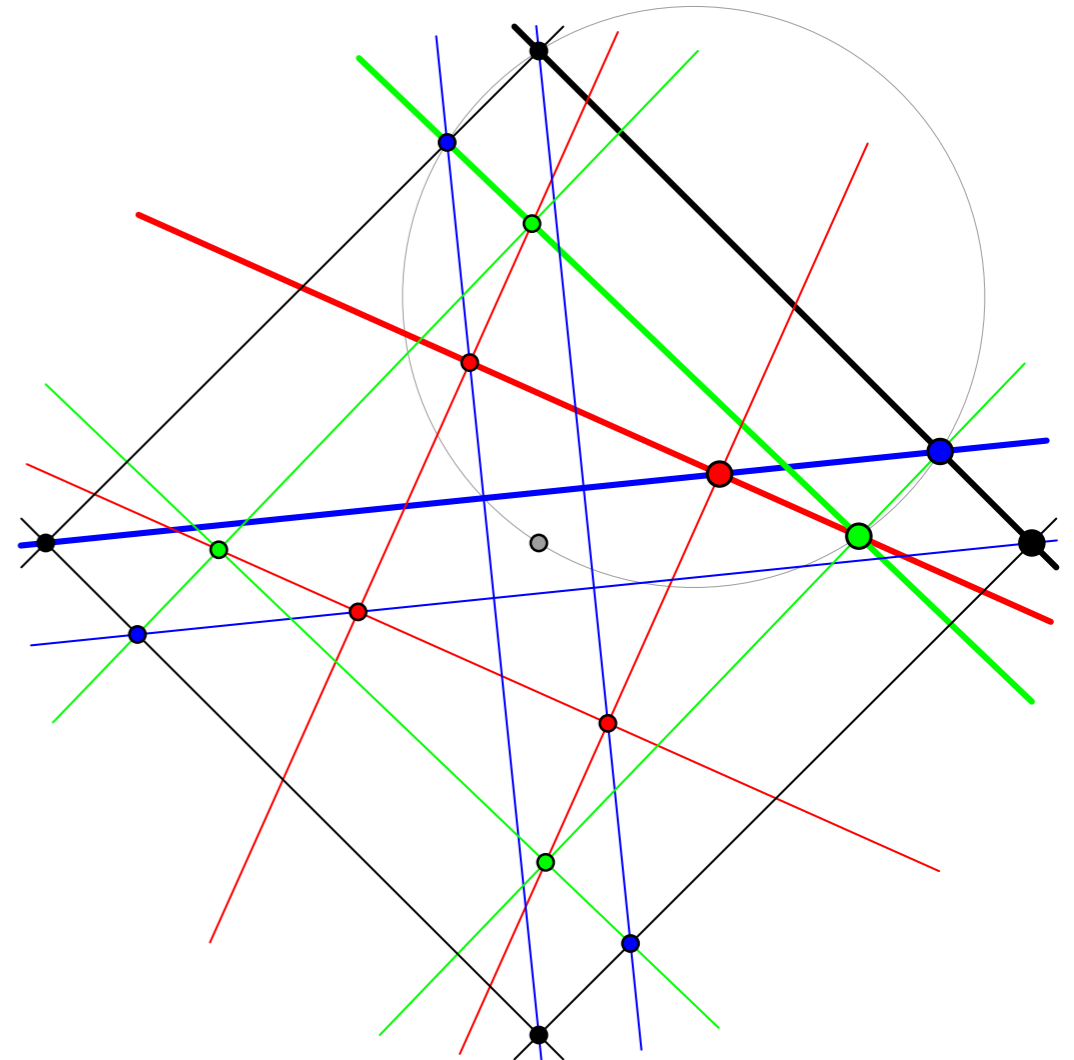
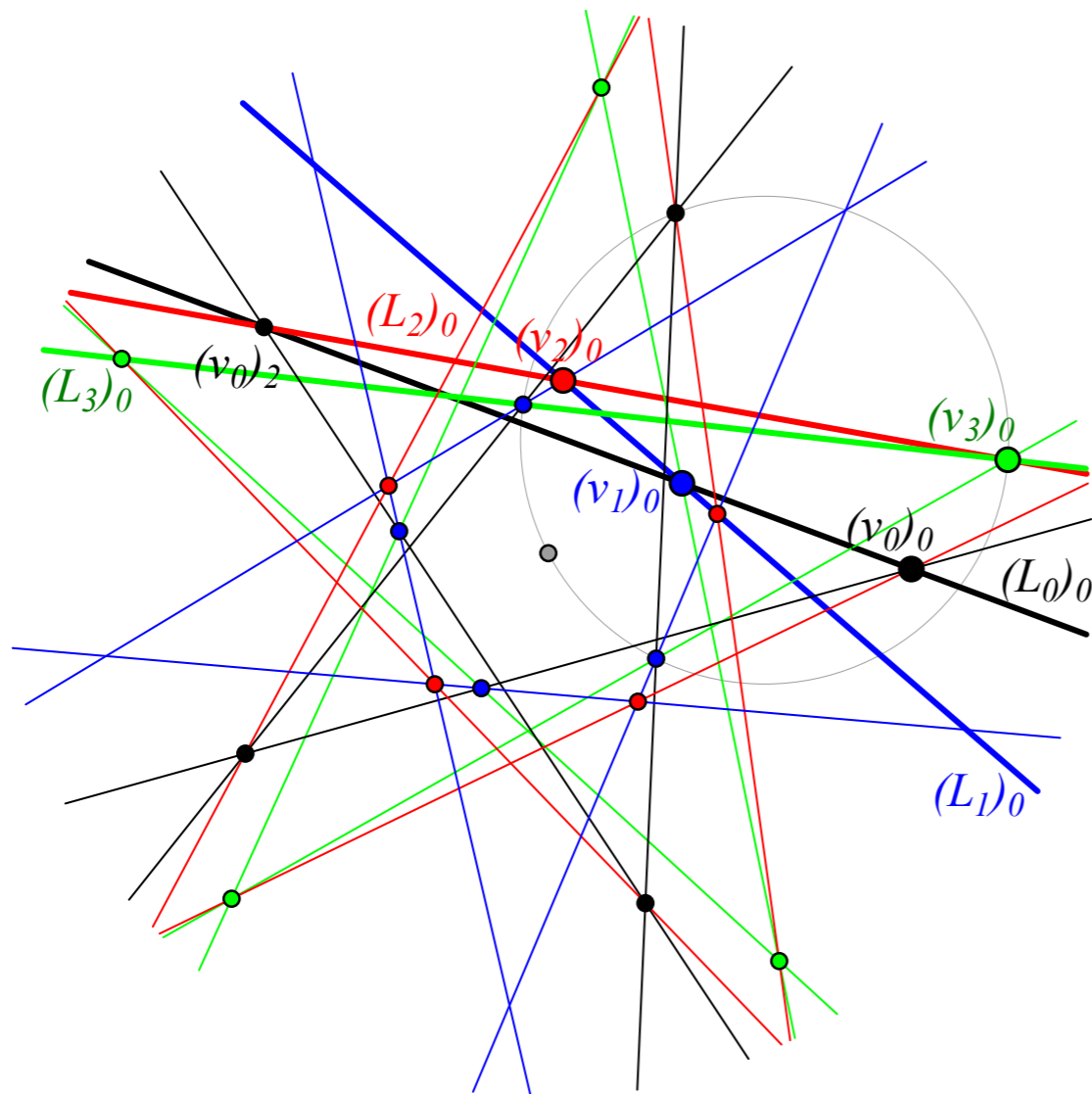
# MOVABLE 3-CONFIGURATIONS



$\mathbb{Z}_5$



$\mathbb{Z}_4$



# 4-CONFIGURATIONS

THE REAL CONFIGURATION  $(21_4)$

Grünbaum &  
Rigby, 1990

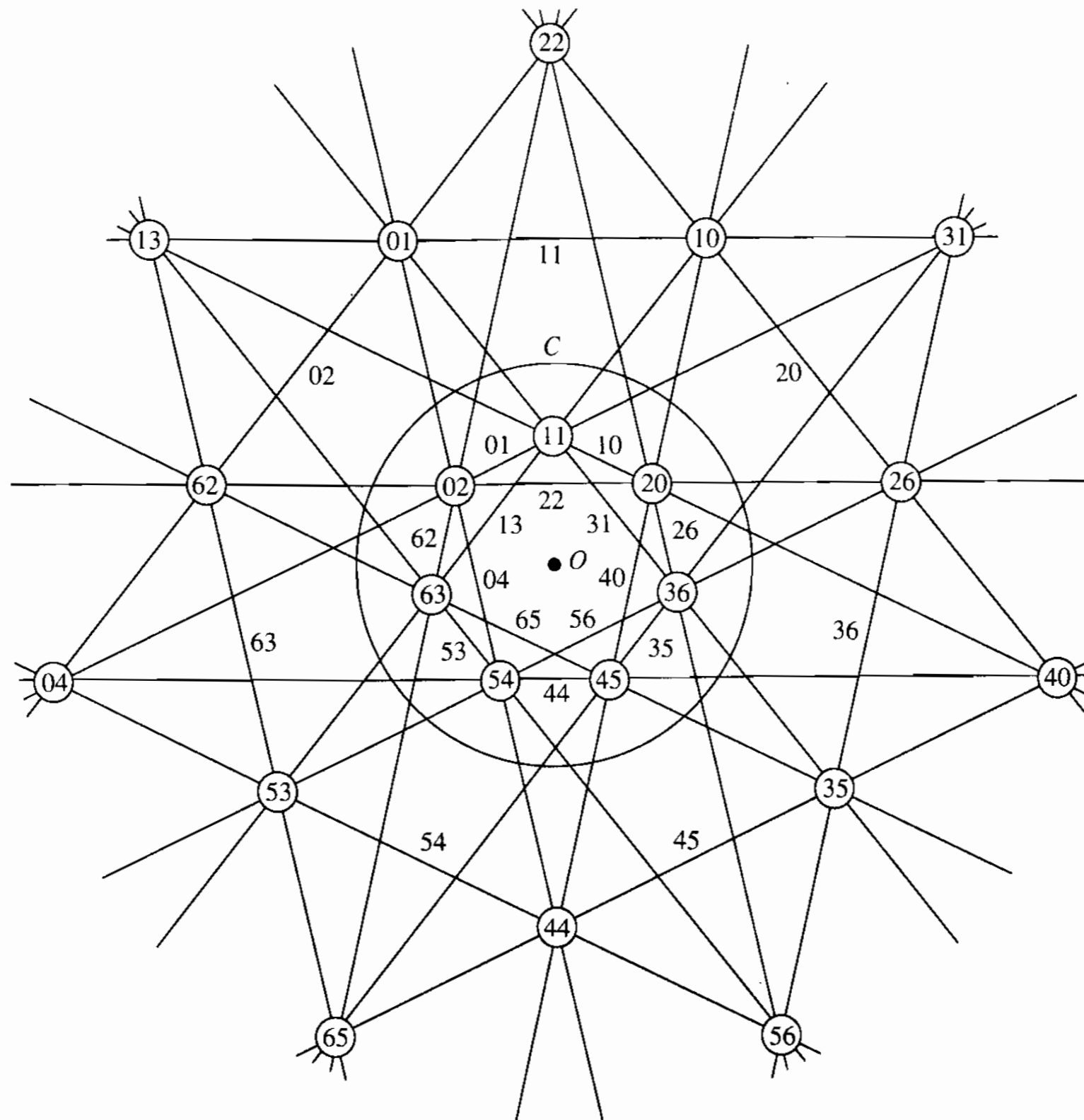
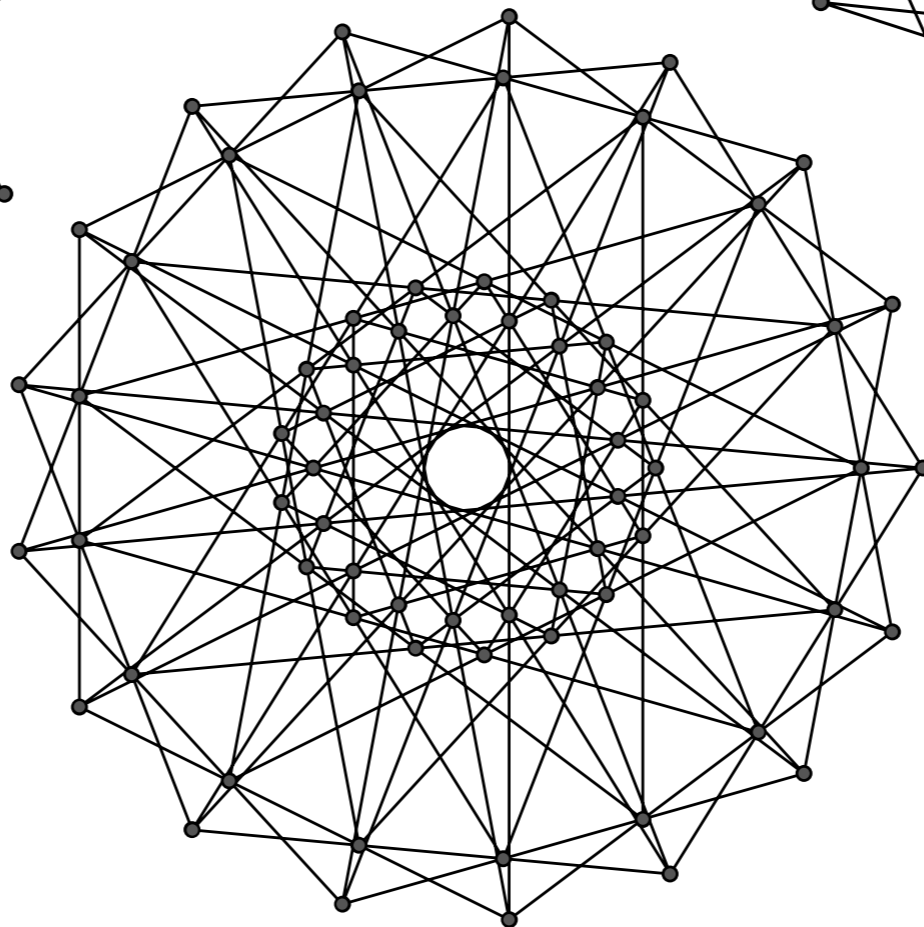
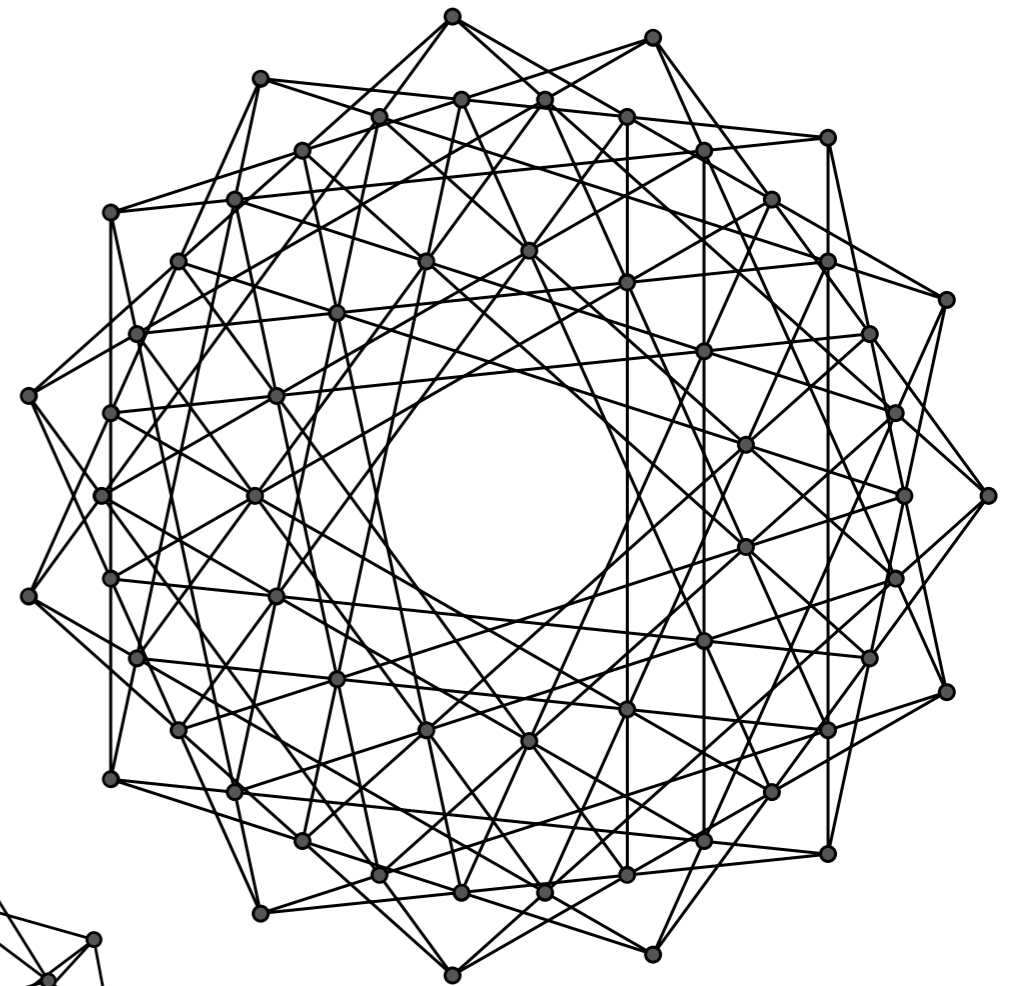
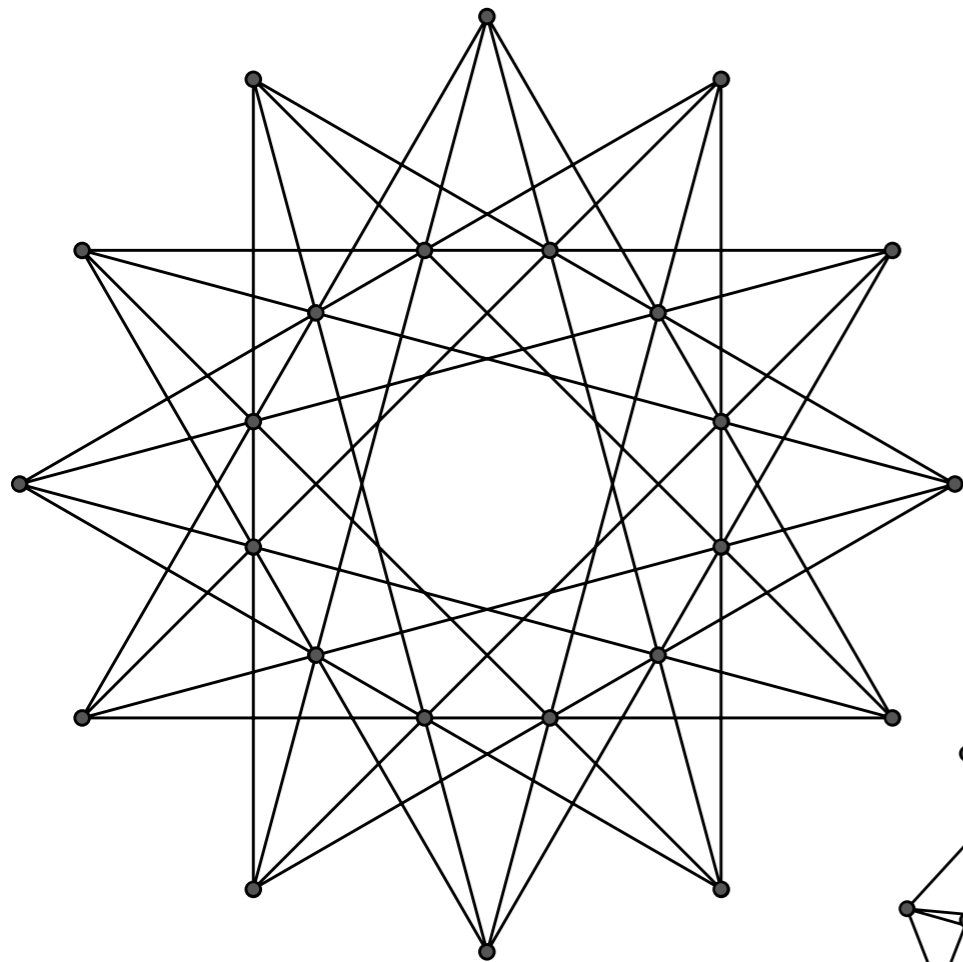


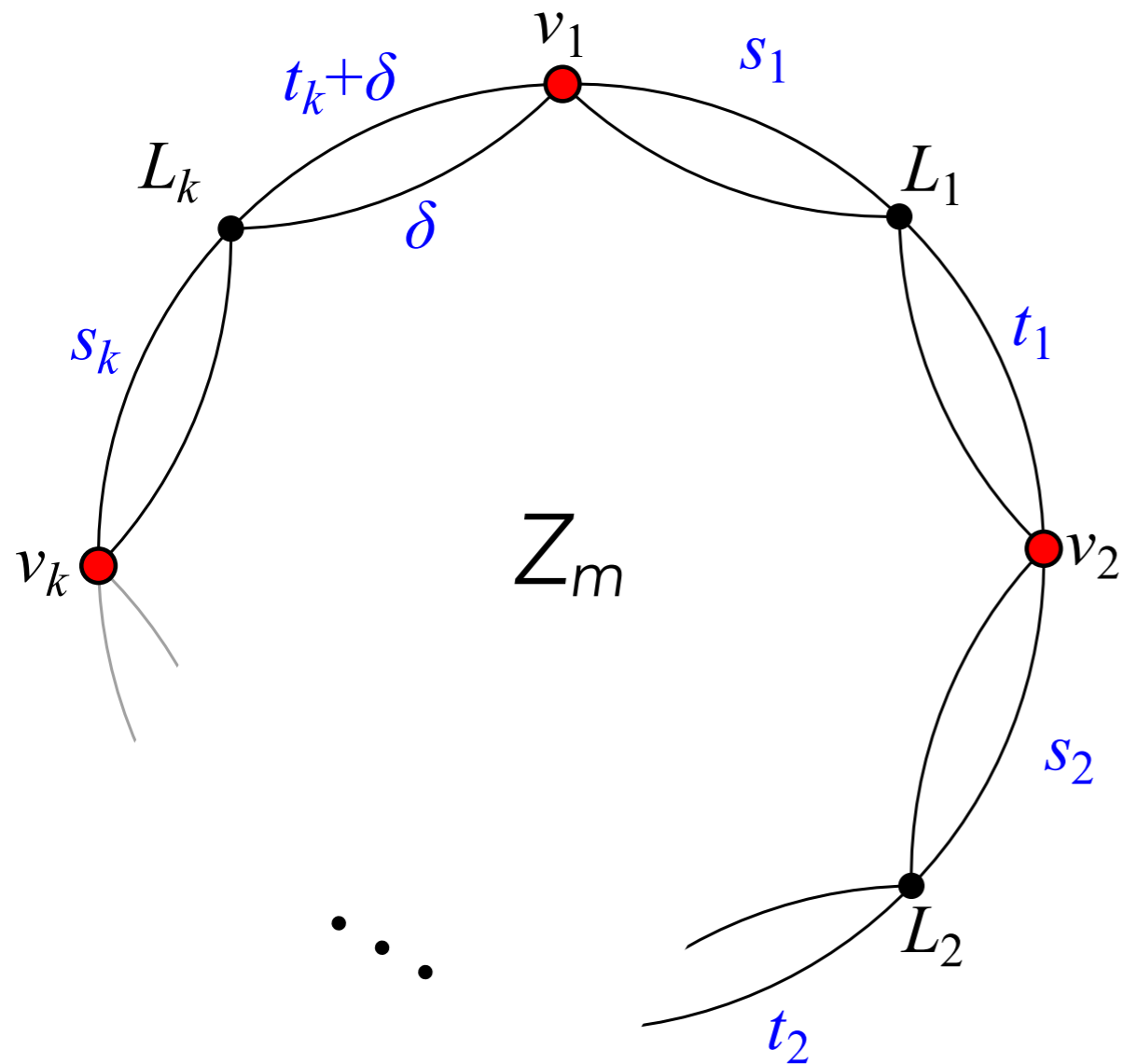
FIG. 1

# 4-CONFIGURATIONS



Boben & Pisanski, 2003; Grünbaum 2000s, 2009

# CELESTIAL 4-CONFIGURATIONS

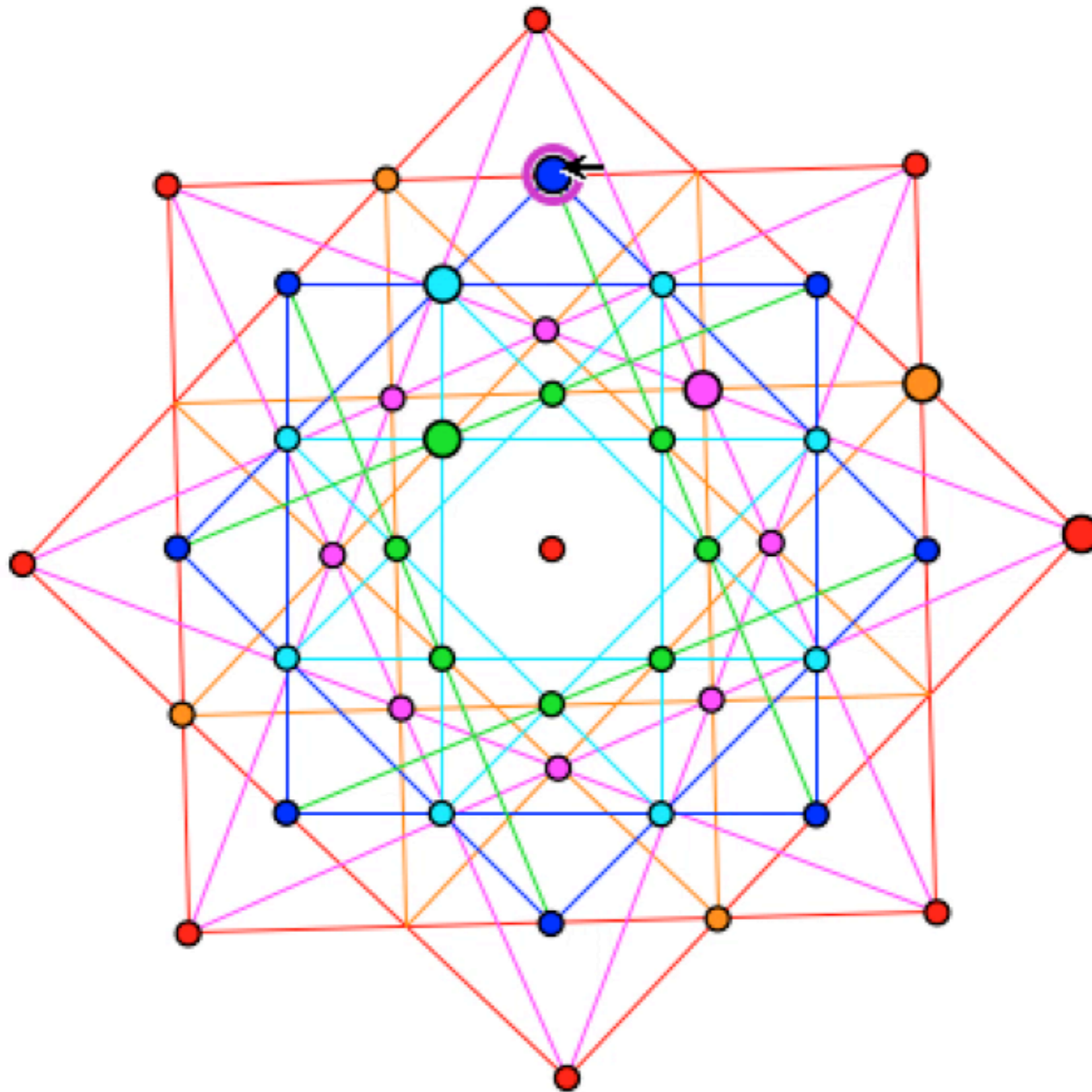


$$m\#(s_1, t_1; \dots; s_k, t_k)$$

$$2\delta = (s_1 - t_1) + \dots + (s_k - t_k)$$

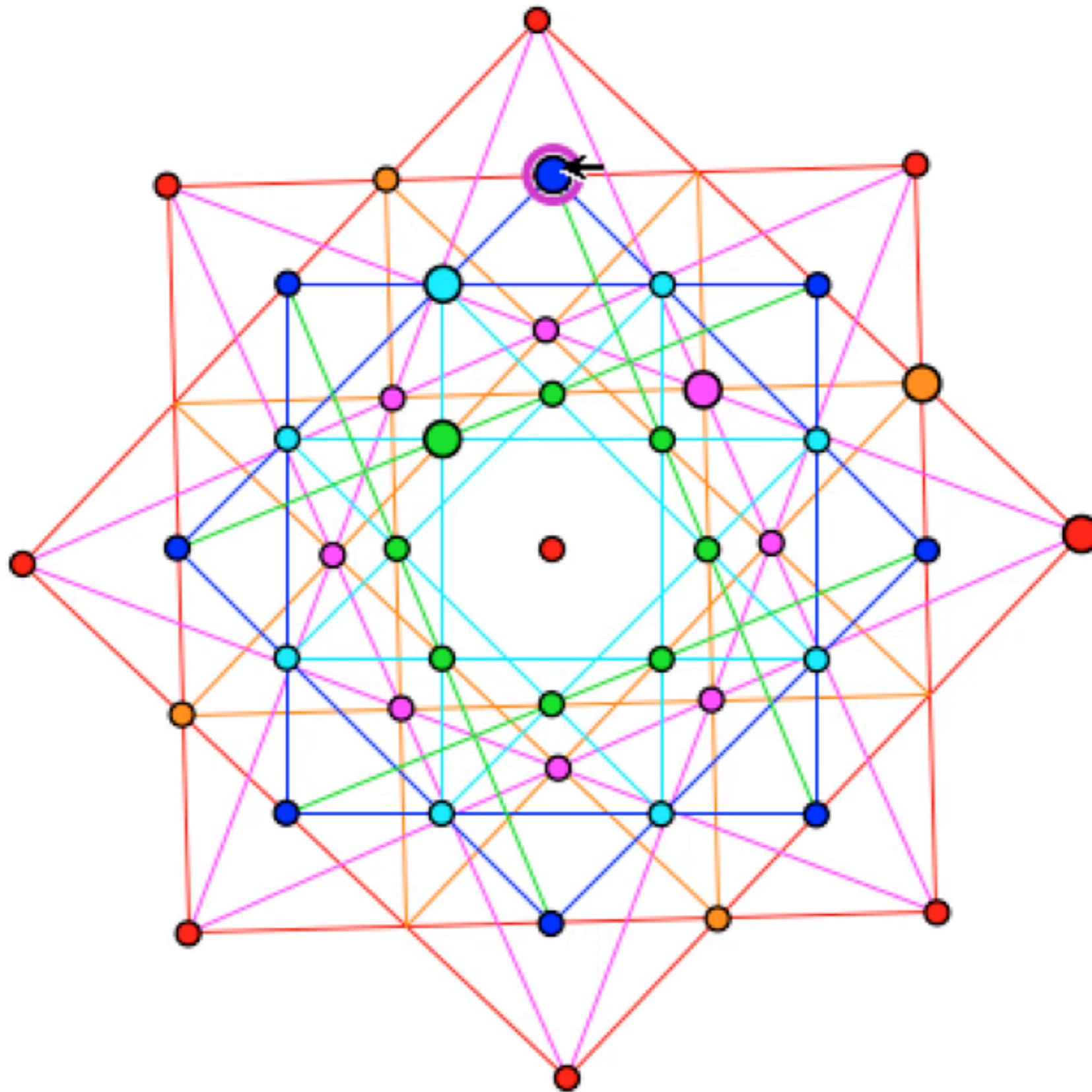
and 4 axioms

# MOVABLE 4-CONFIGURATIONS



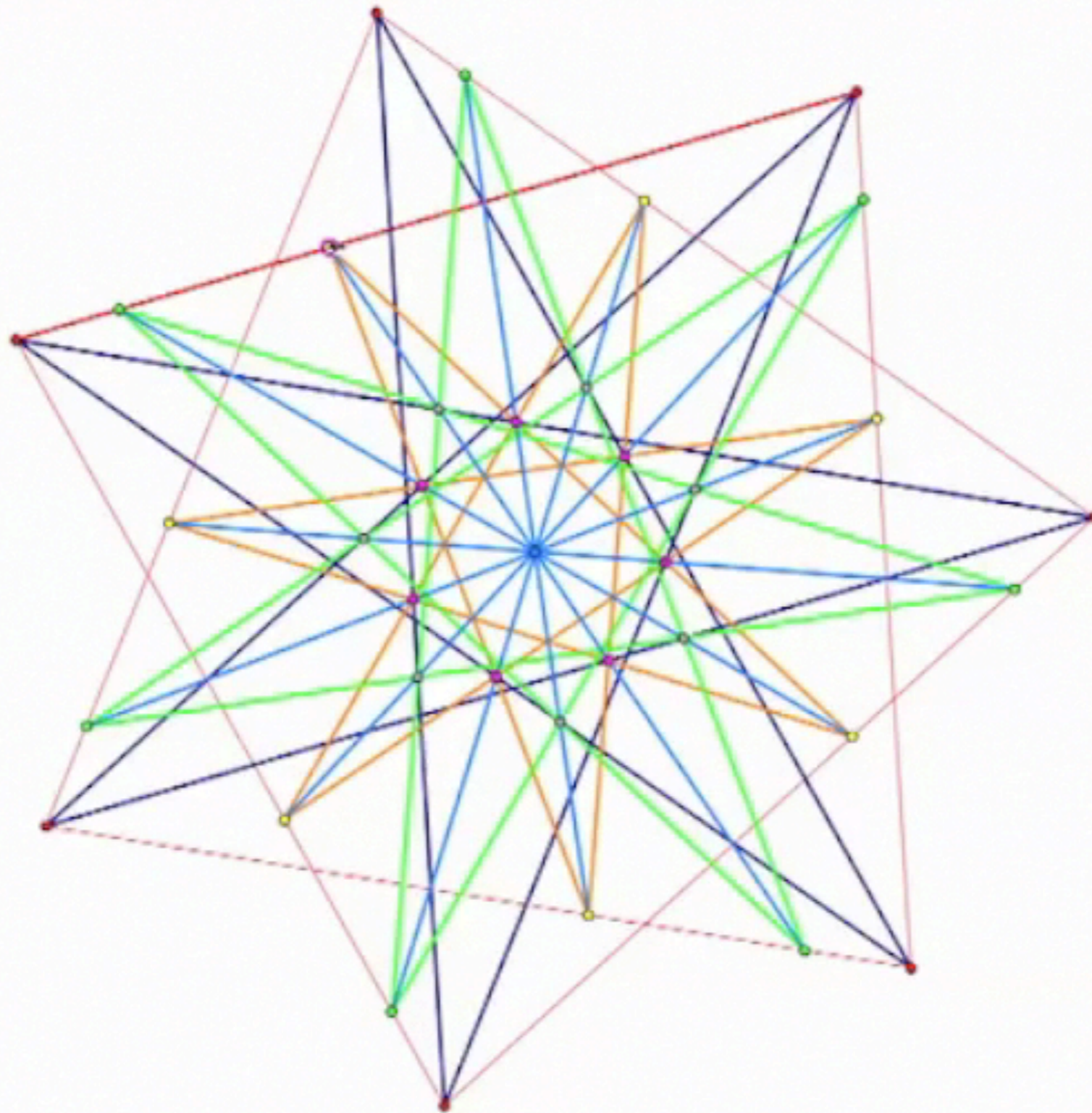
B. 2007

# MOVABLE 4-CONFIGURATIONS



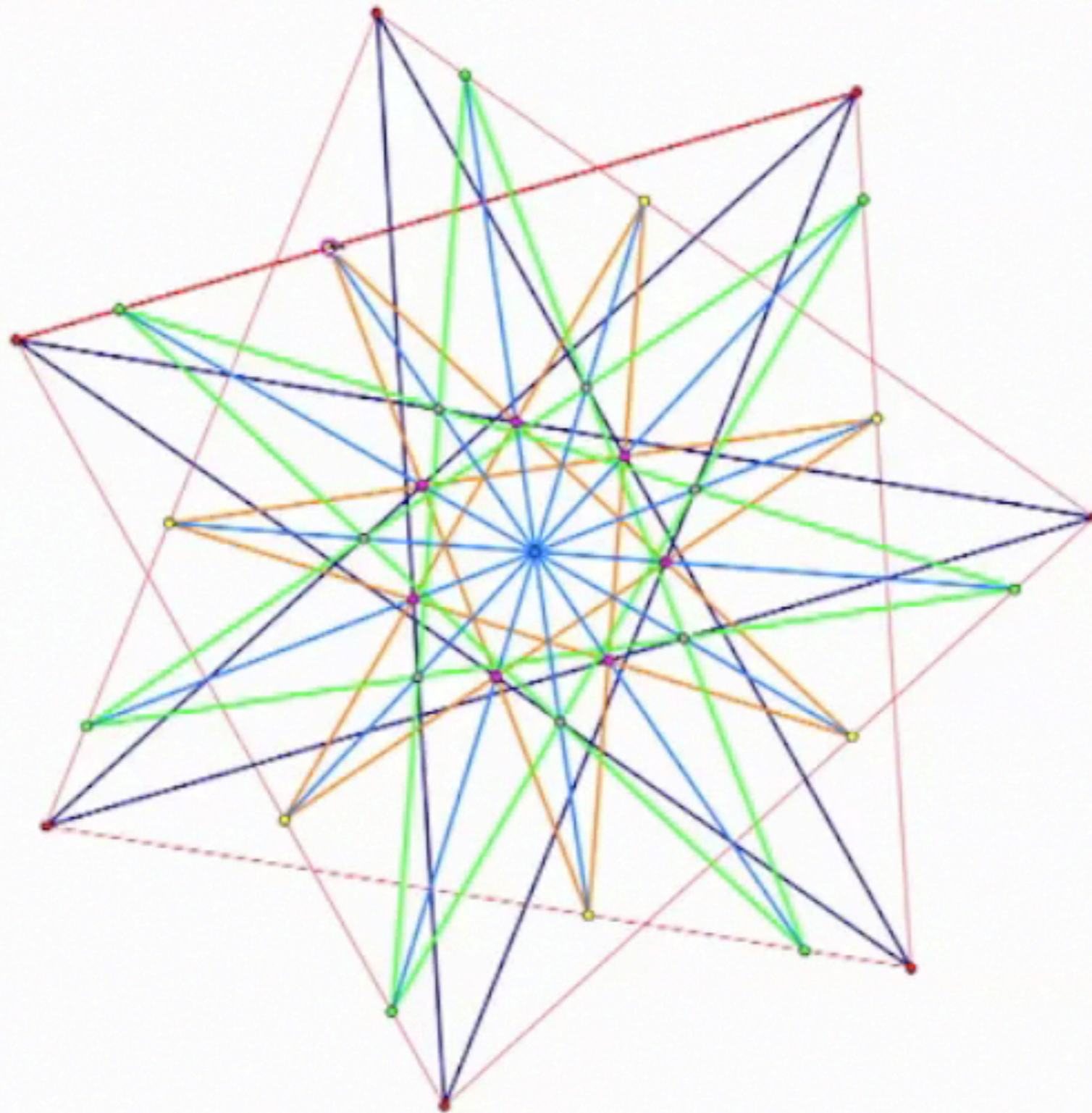
B. 2007

# MOVABLE 4-CONFIGURATIONS



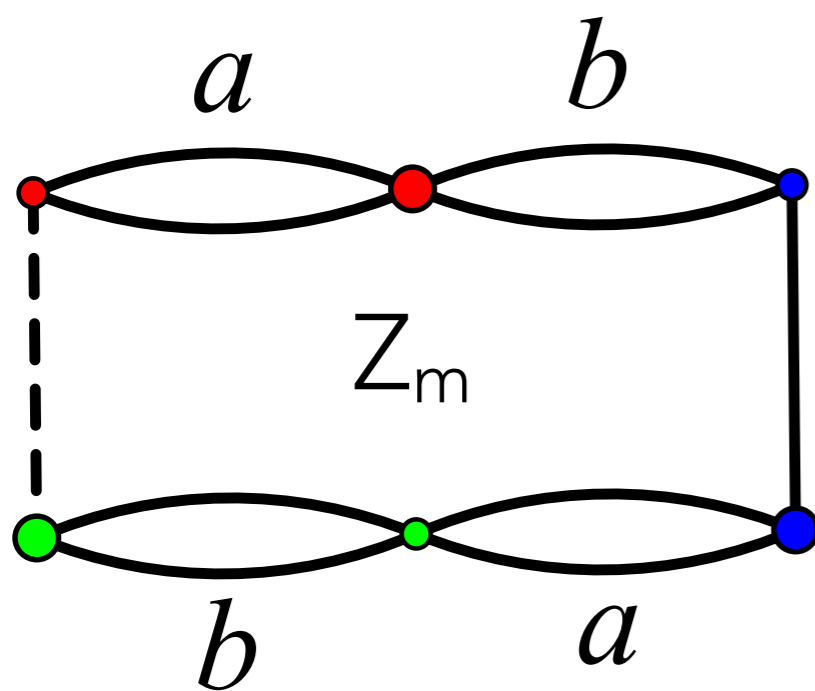
B. 2008

# MOVABLE 4-CONFIGURATIONS

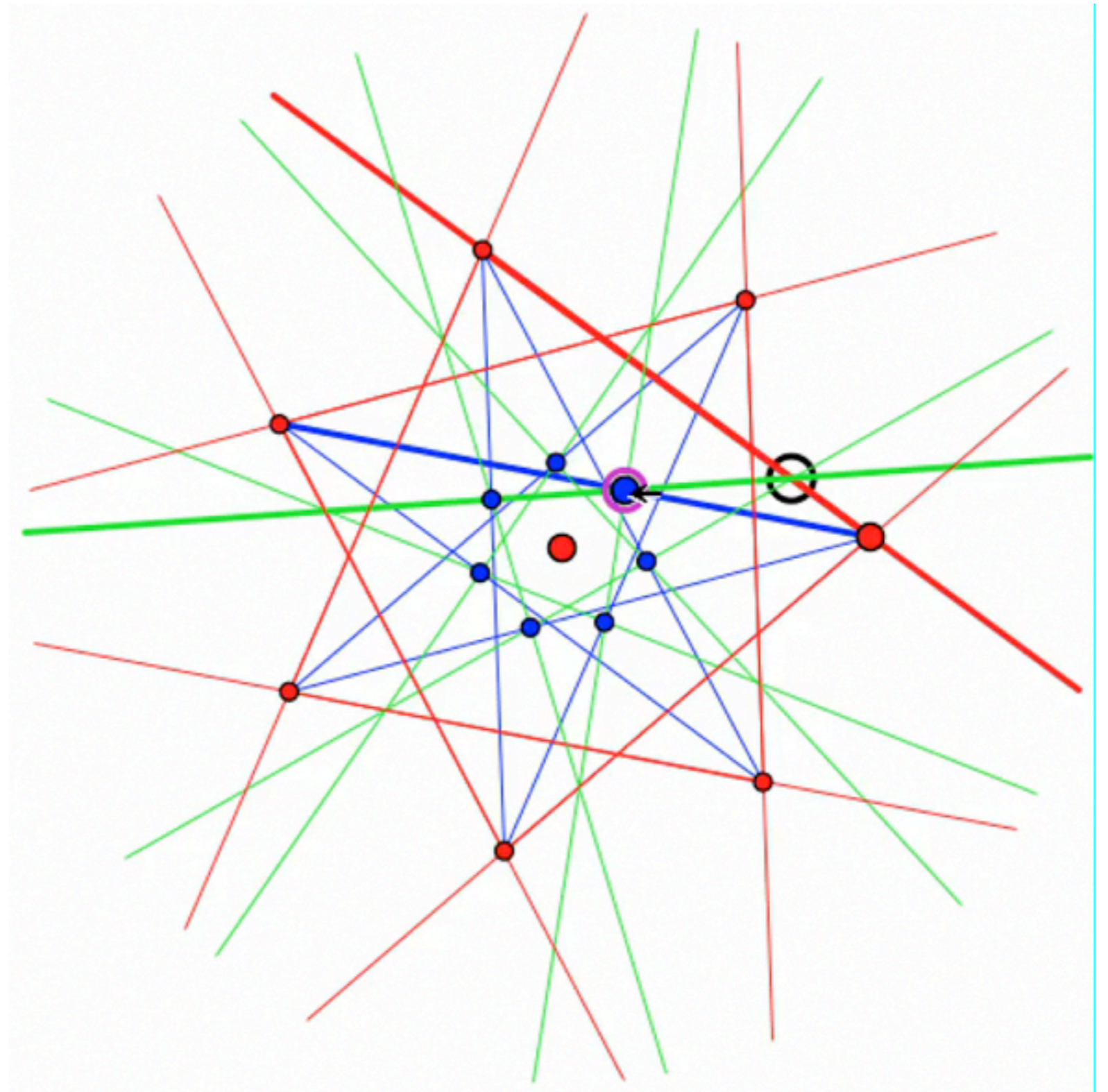


B. 2008

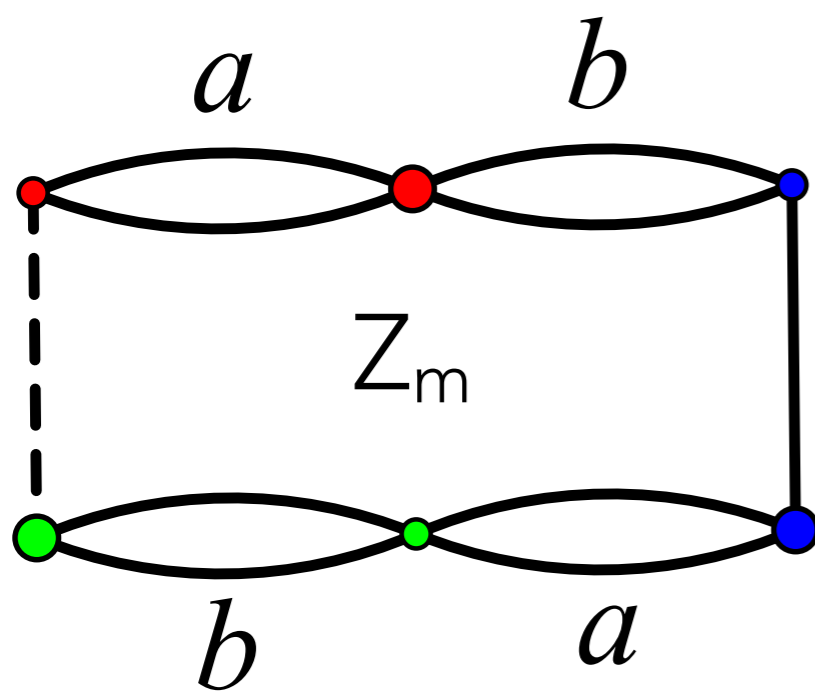
# CROSSING SPANS LEMMA



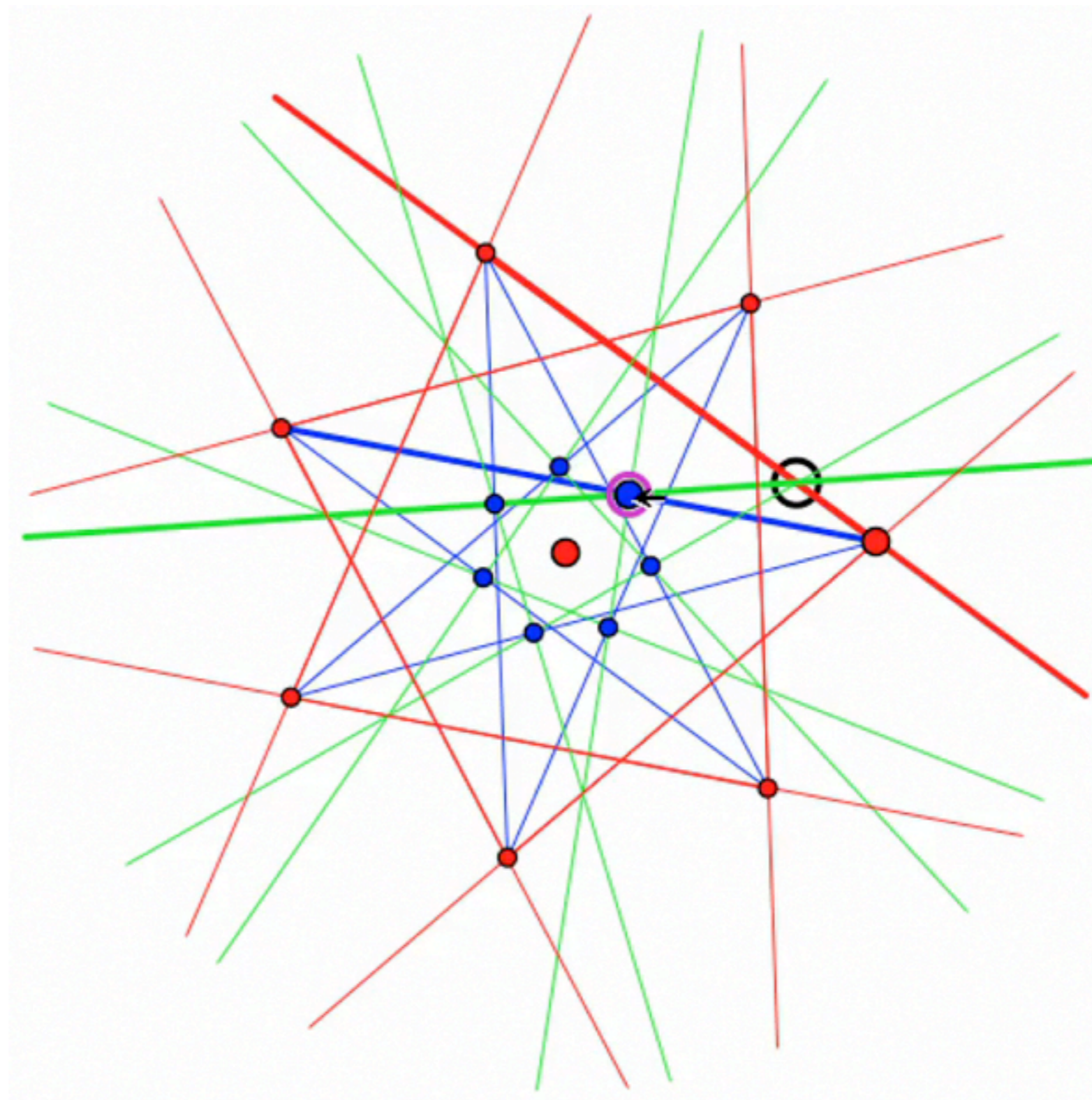
$$m=7, a=2, b=3$$



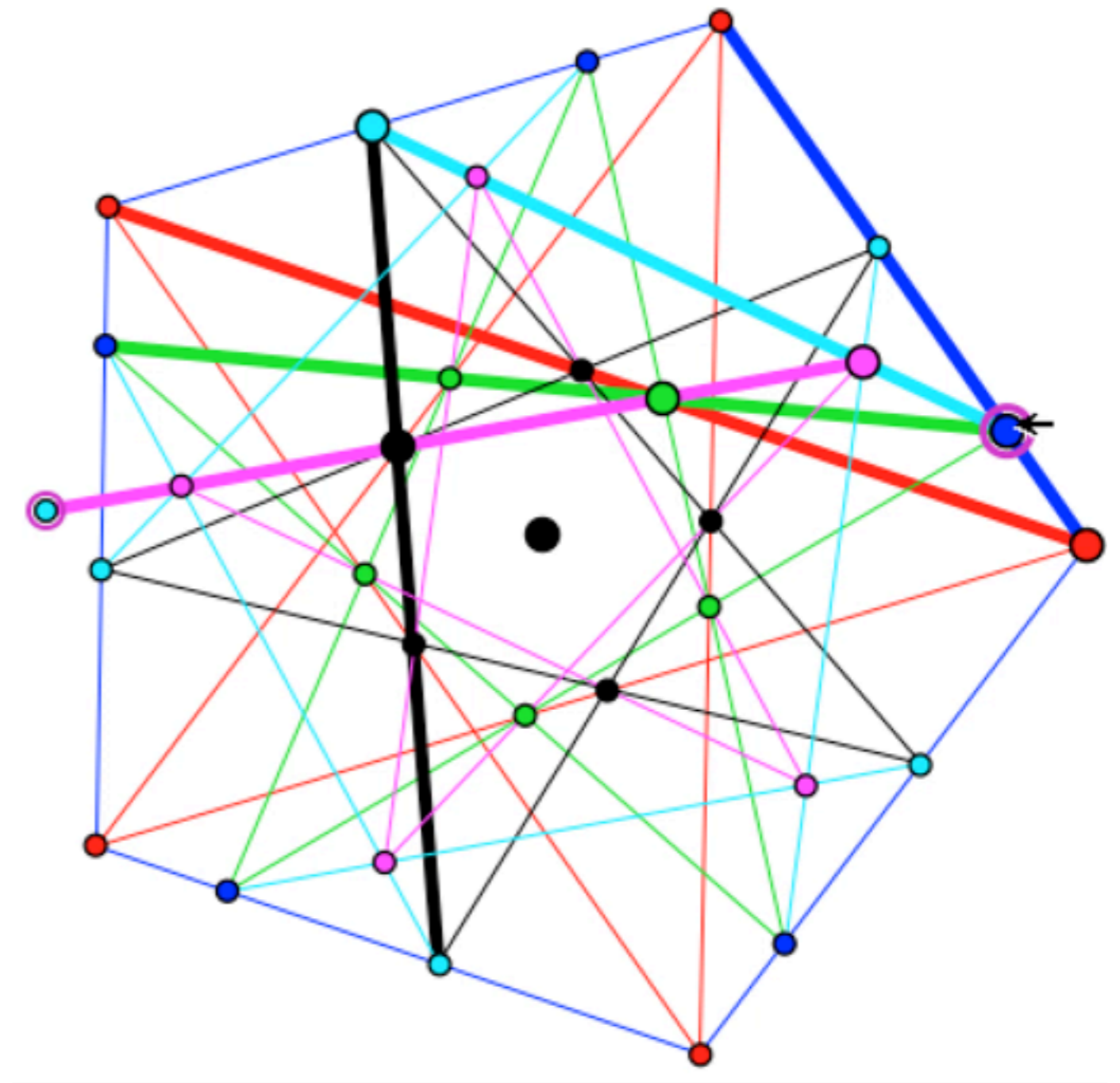
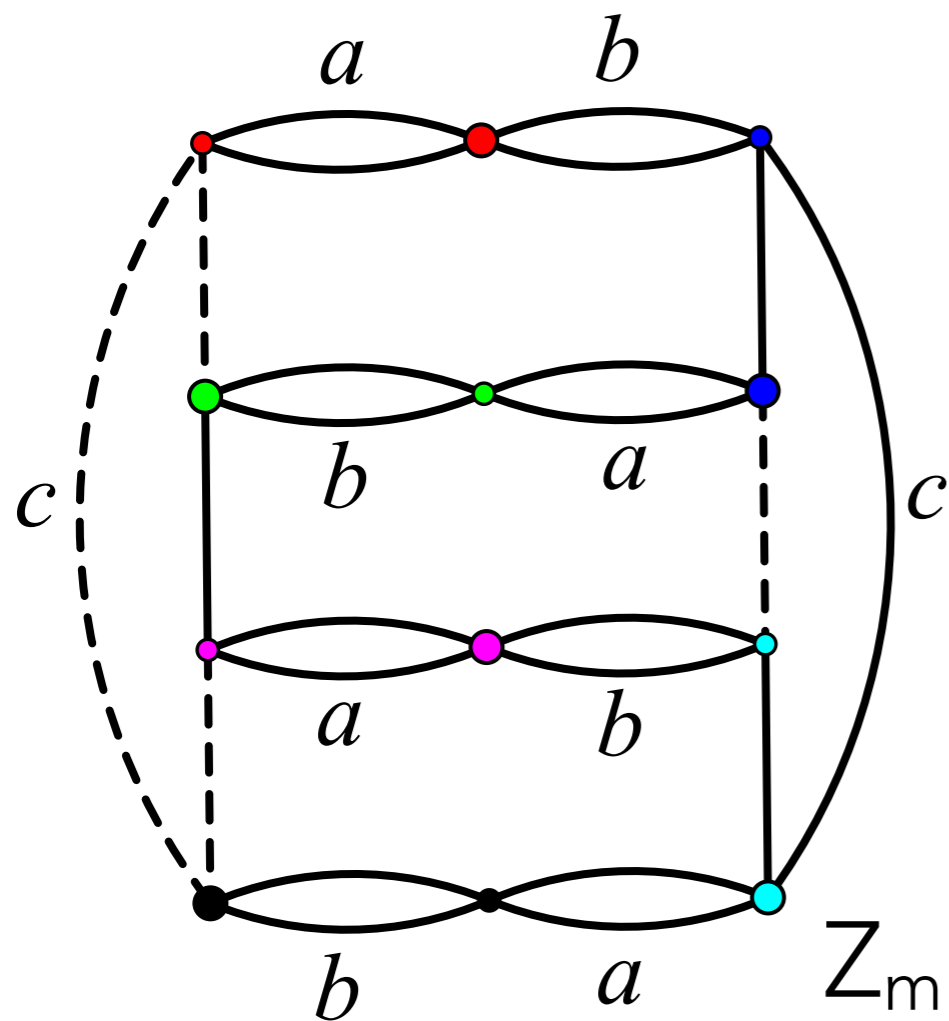
# CROSSING SPANS LEMMA



$$m=7, a=2, b=3$$



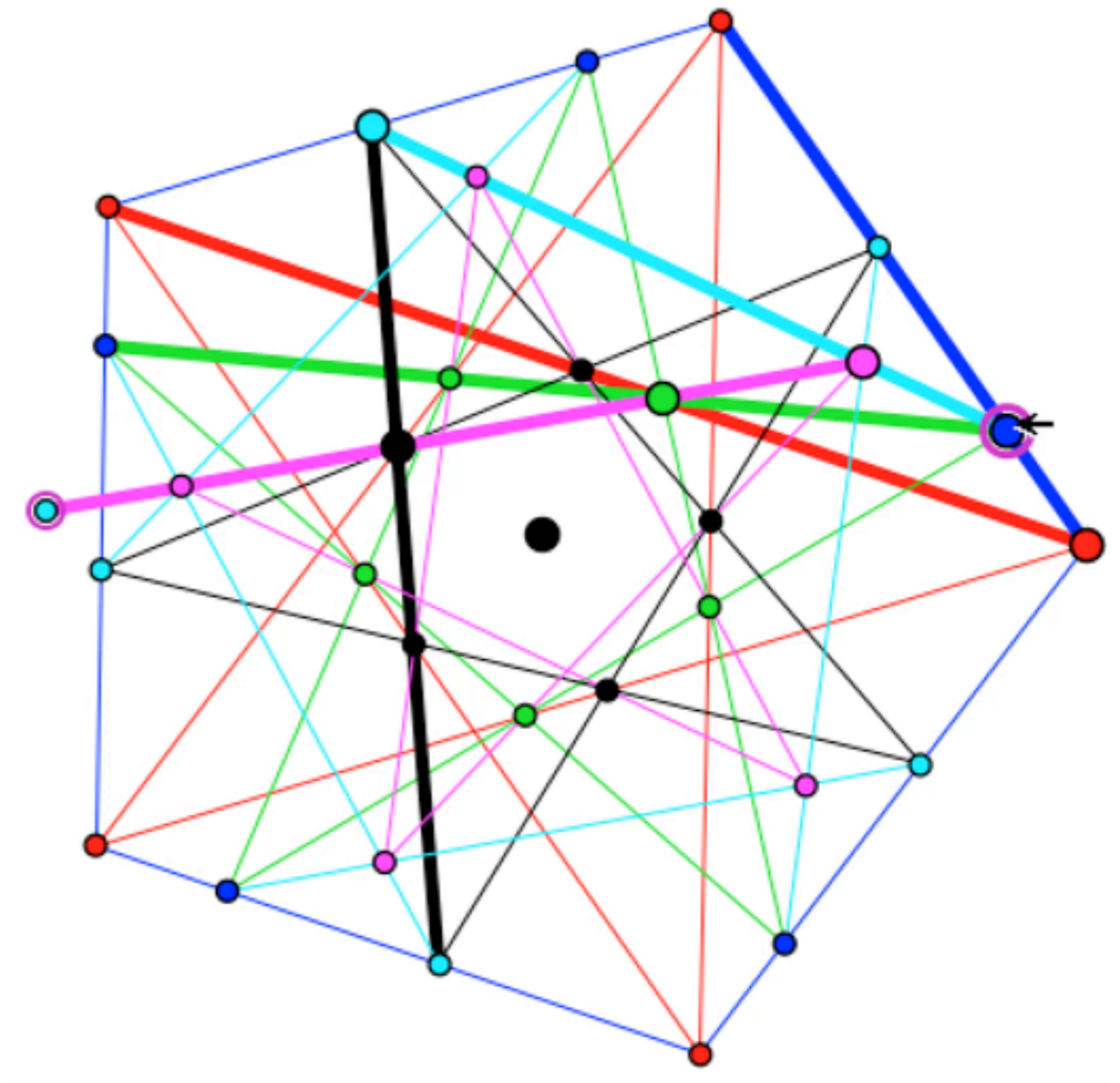
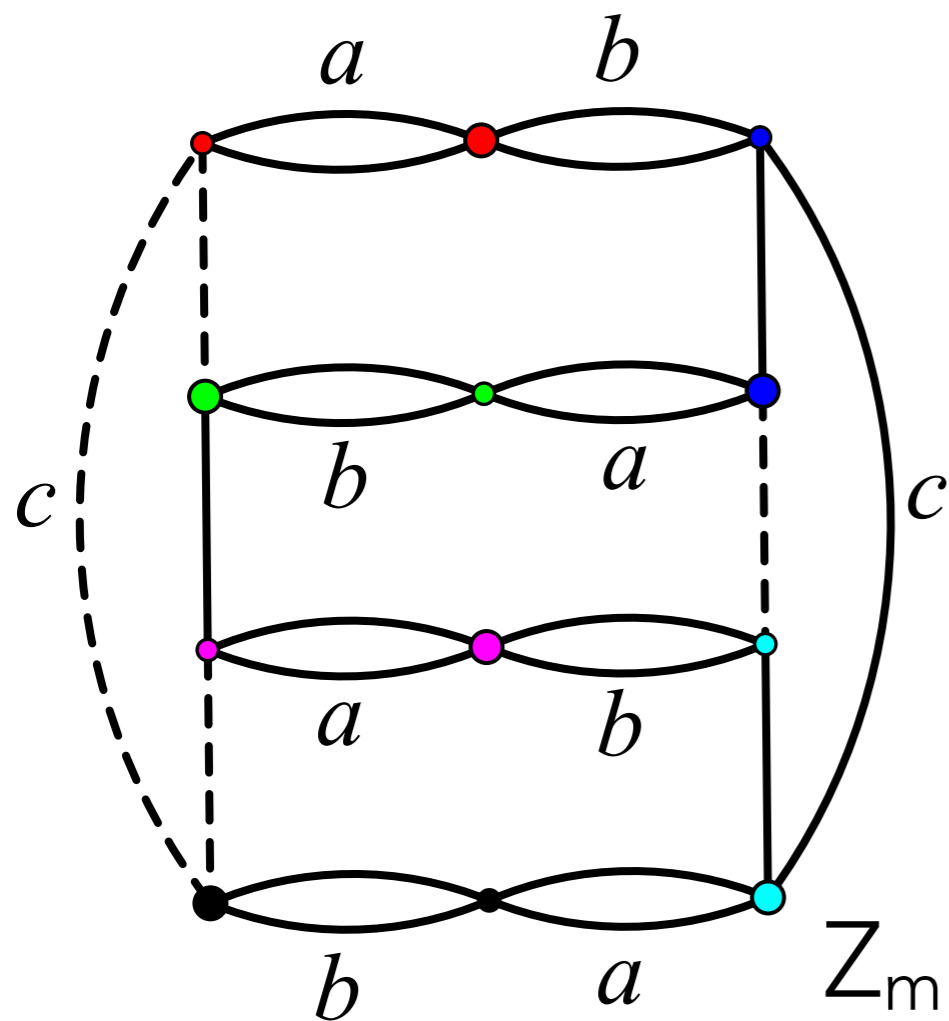
# MOVABLE 4-CONFIGURATIONS



$$m=5, a=2, b=1, c=1$$

B., J. Faudree, T. Pisanski, in review

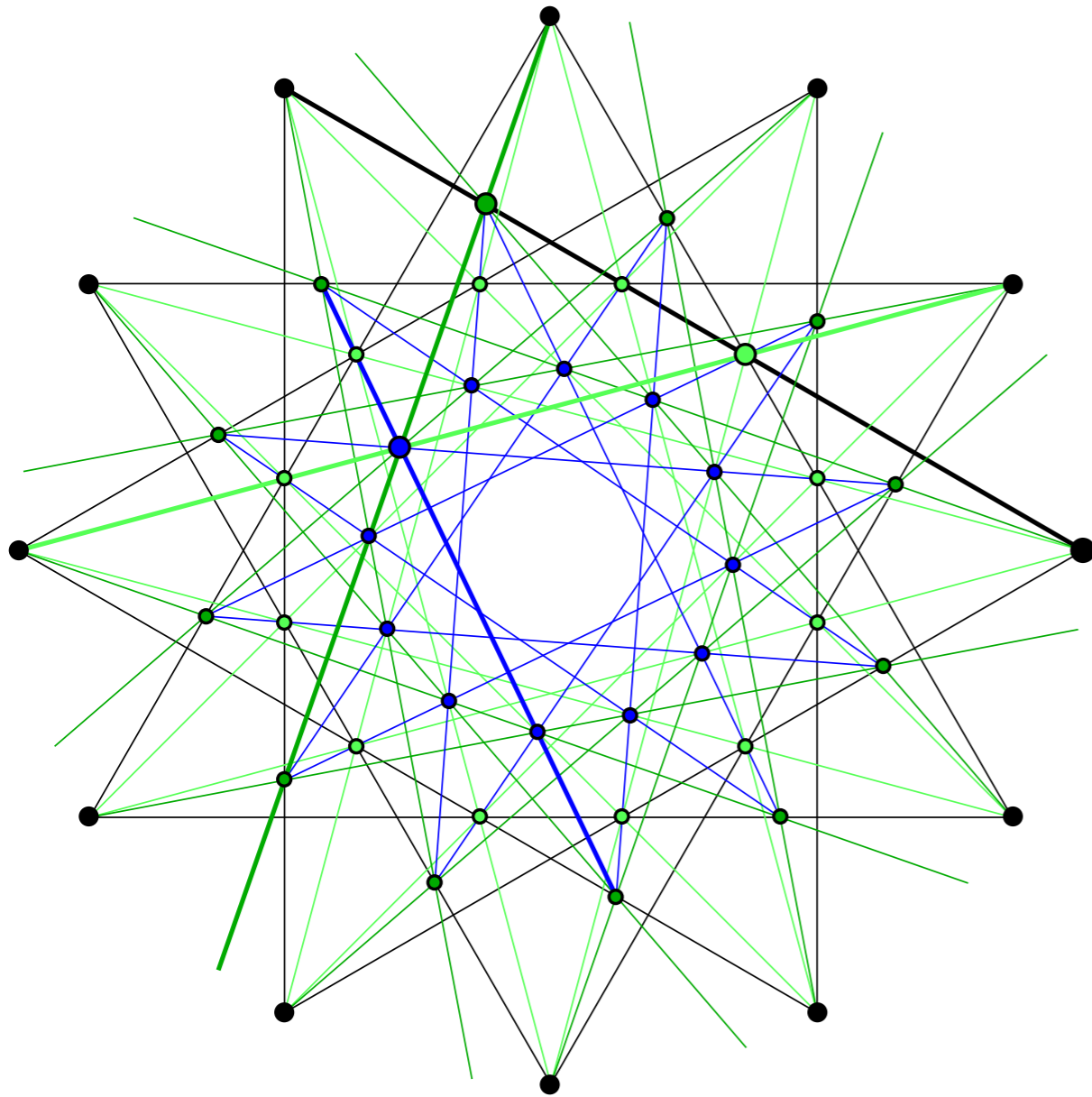
# MOVABLE 4-CONFIGURATIONS



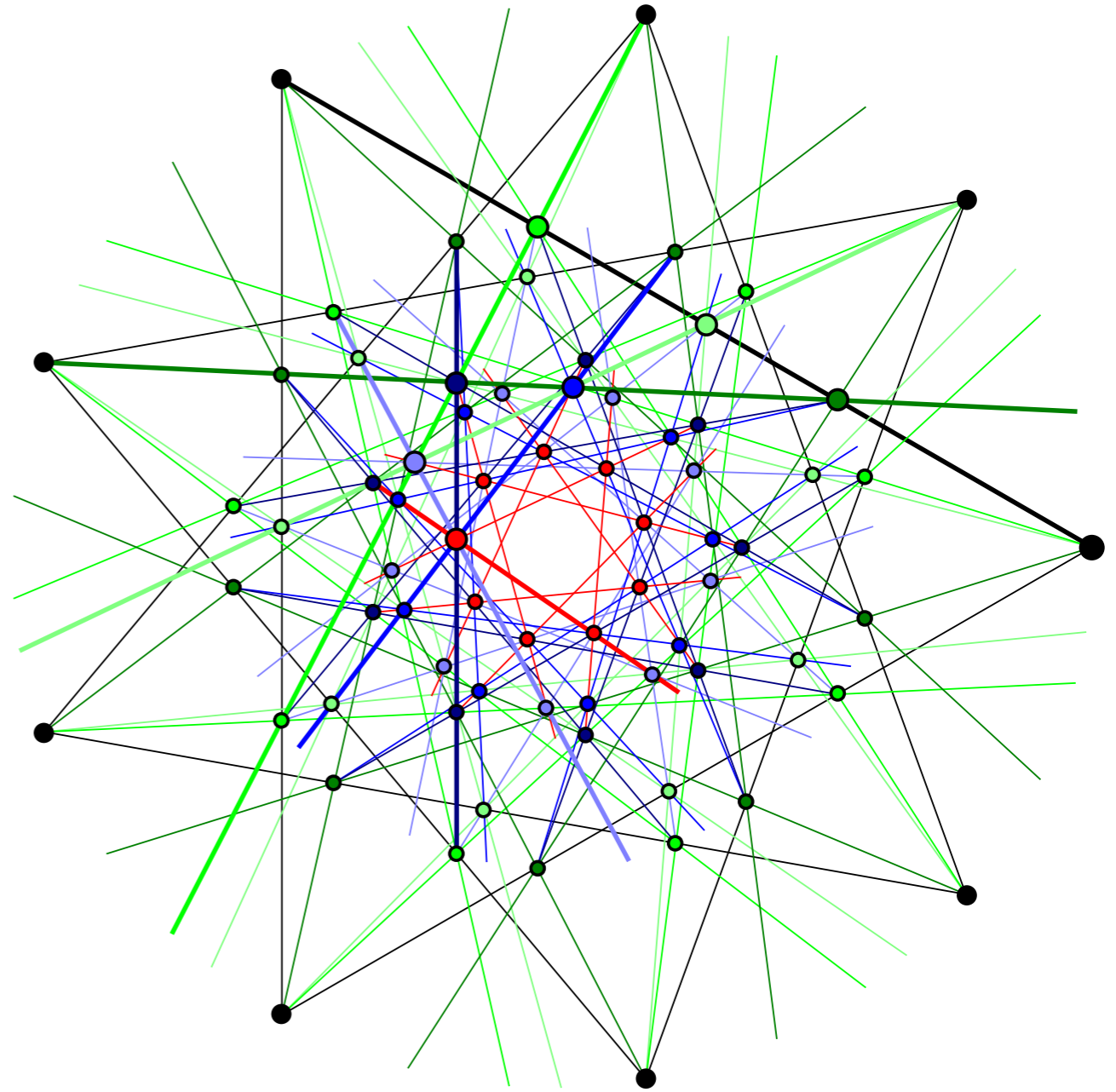
$$m=5, a=2, b=1, c=1$$

B., J. Faudree, T. Pisanski, in review

# 5-CONFIGURATIONS



B. & Ng, 2010

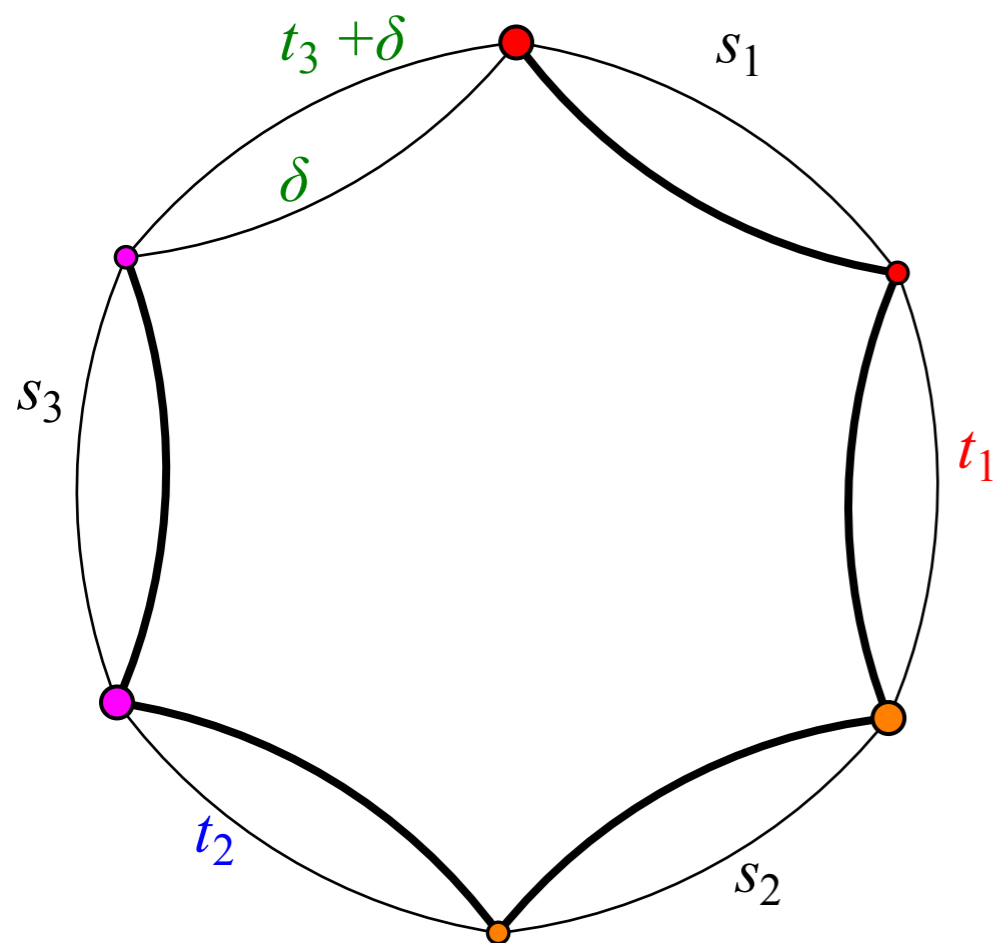


B. & J. Faudree, 2013

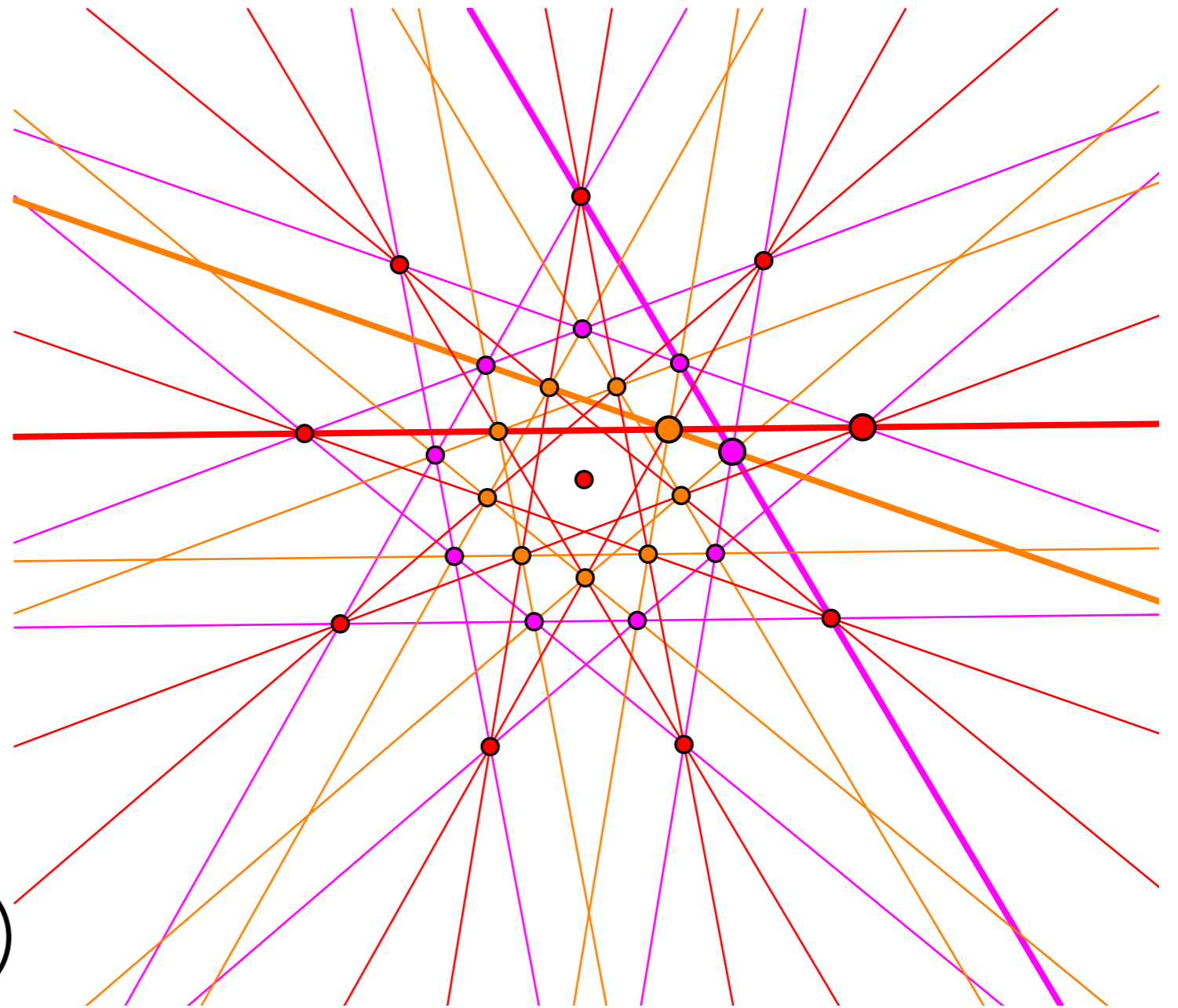
Static!

# MOVABLE 5-CONFIGURATIONS

Joint with Lander VerHoef



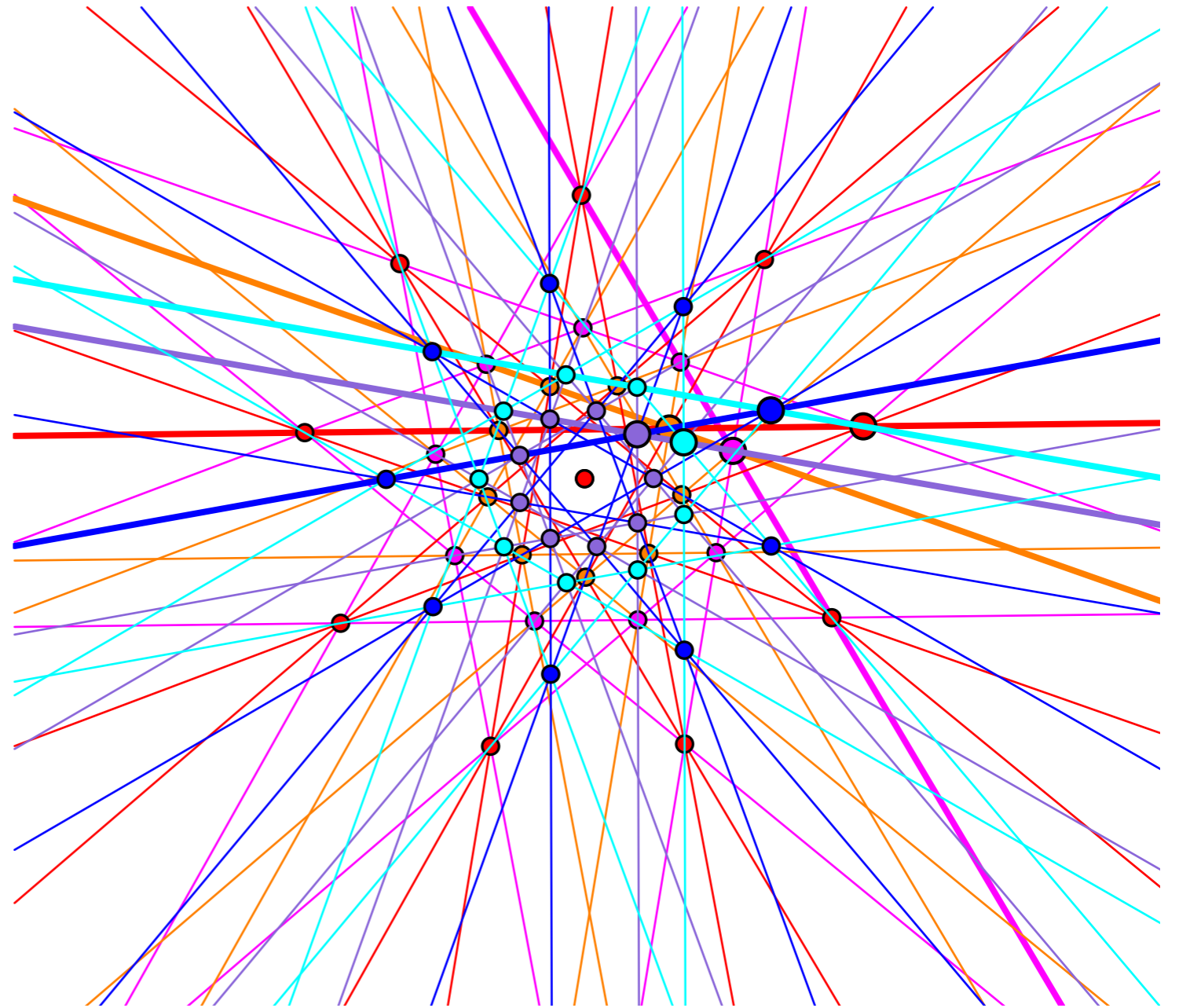
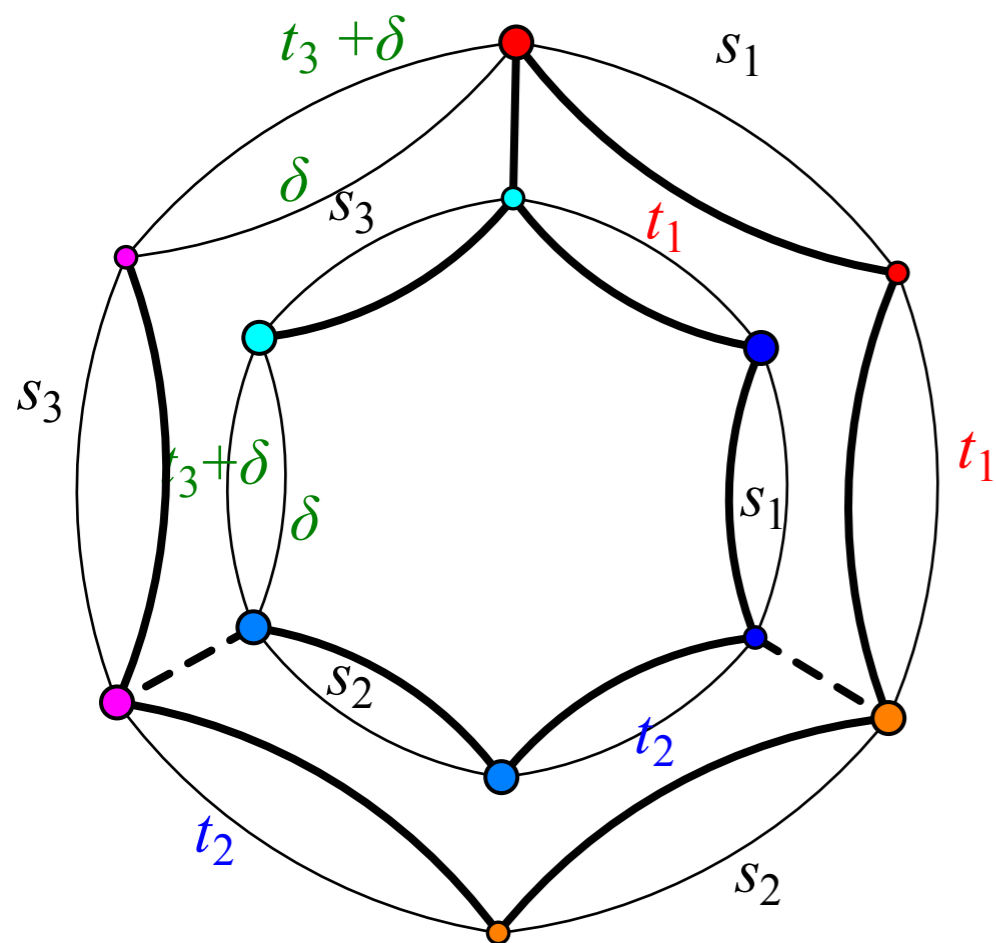
$(27_4)$



Celestial Configuration  $m\#(s_1, t_1; s_2, t_2; s_3, t_3); S \cap T = \emptyset$

# MOVABLE 5-CONFIGURATIONS

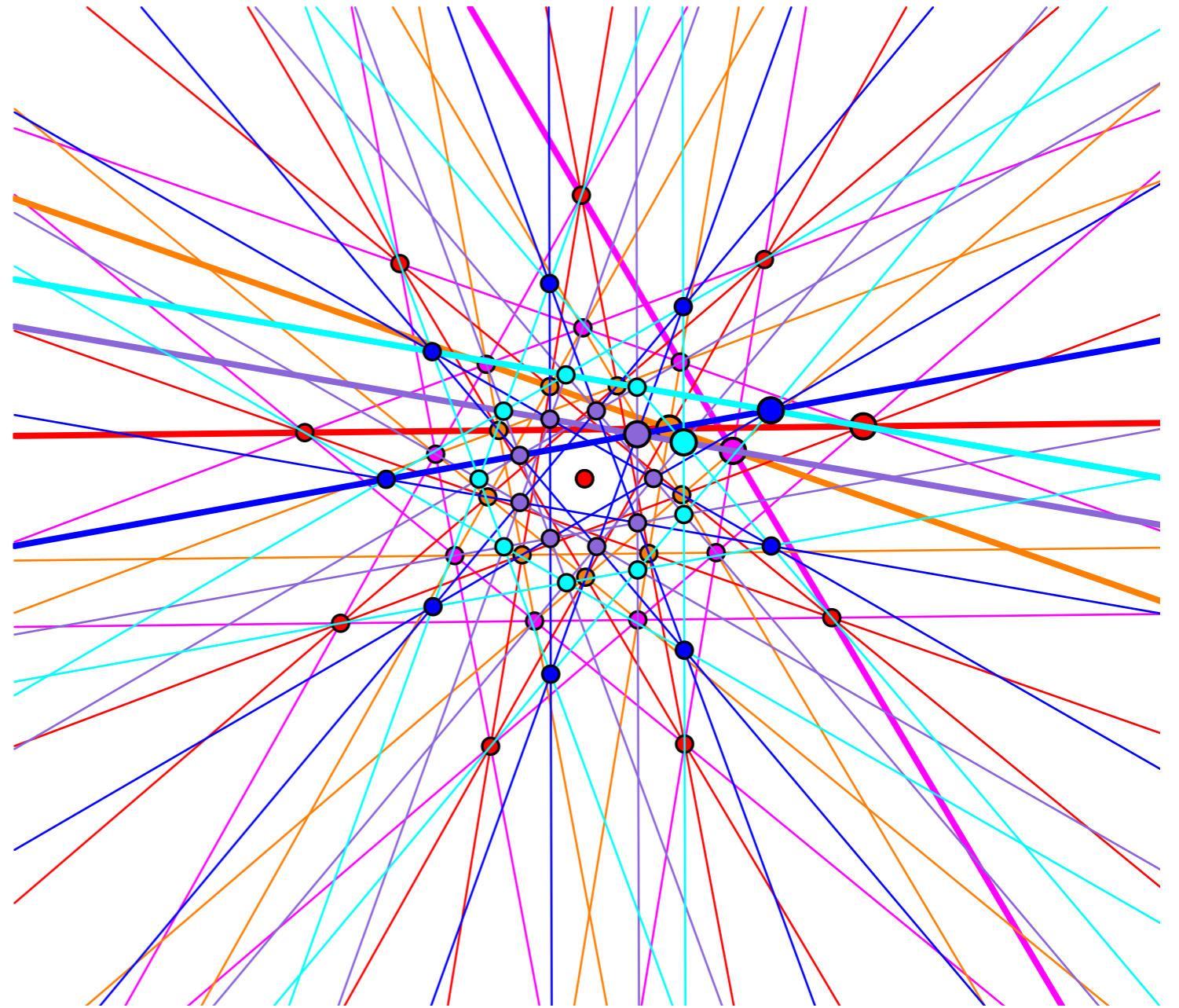
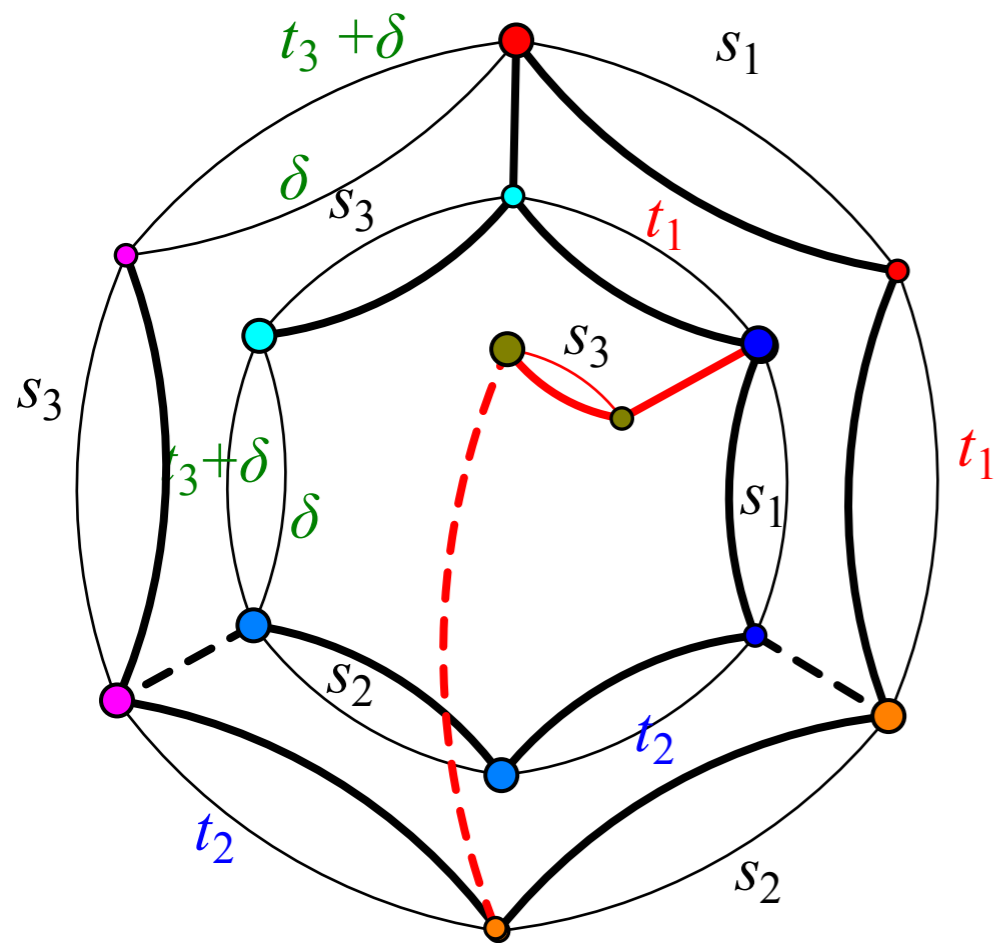
Joint with Lander VerHoef



Celestial Configuration  $m\#(s_1, t_1; s_2, t_2; s_3, t_3); S \cap T = \emptyset$

# MOVABLE 5-CONFIGURATIONS

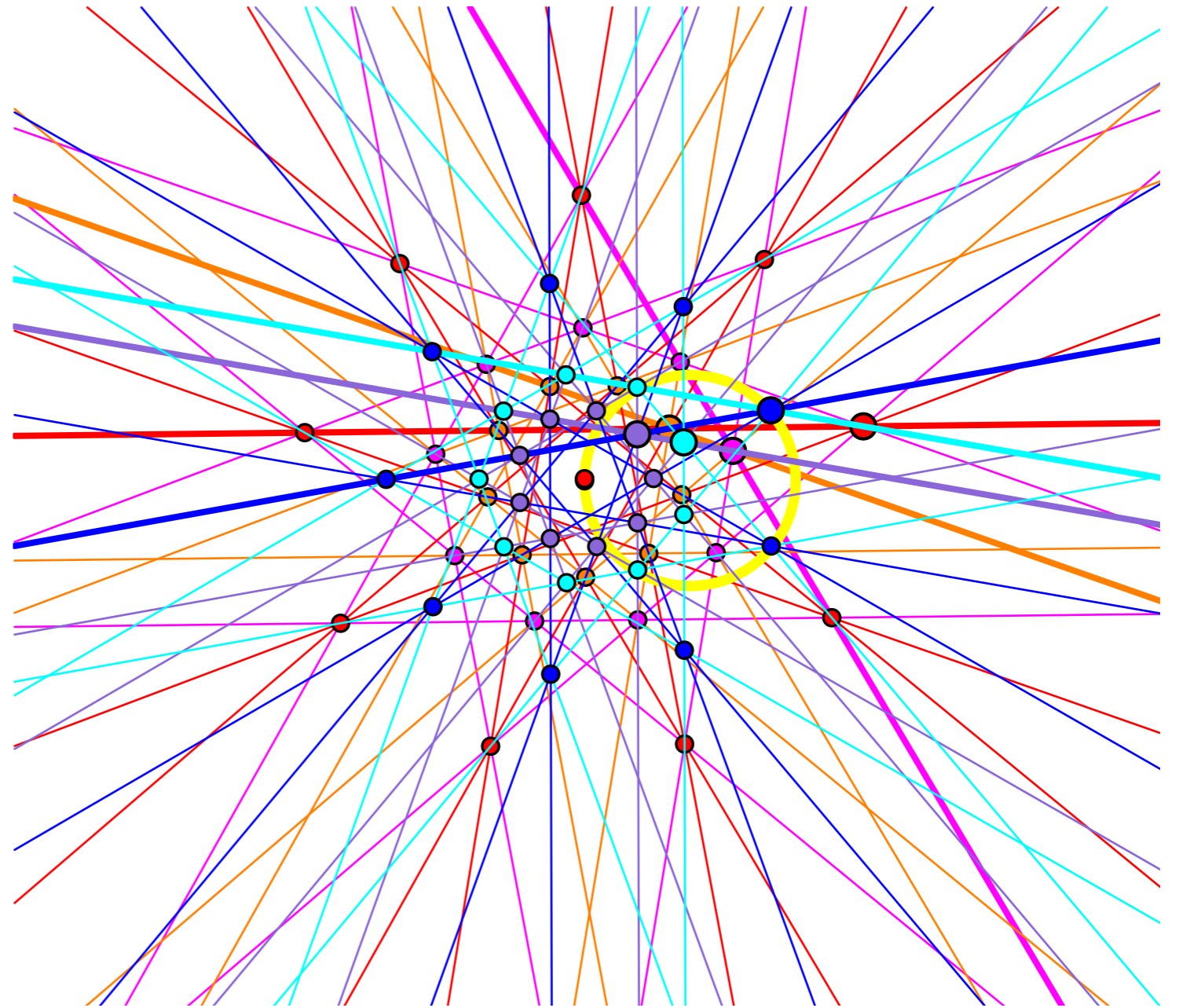
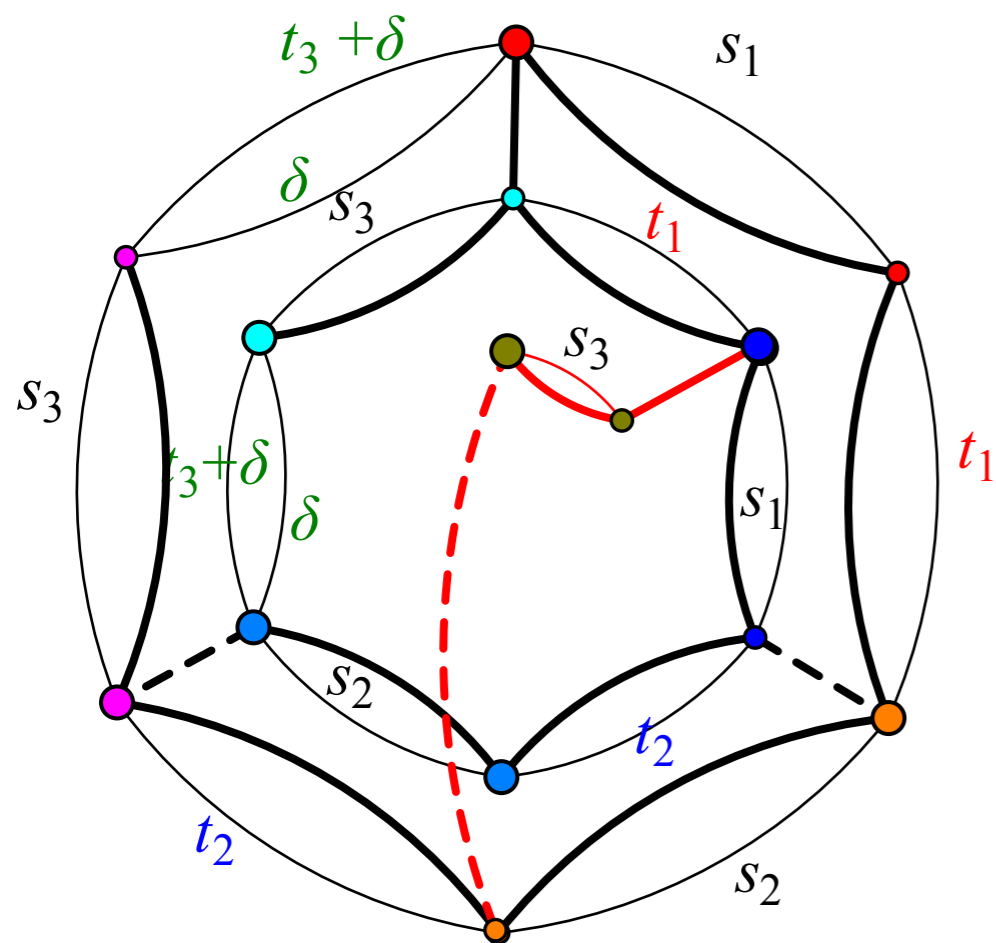
Joint with Lander VerHoef



Celestial Configuration  $m\#(s_1, t_1; s_2, t_2; s_3, t_3); S \cap T = \emptyset$

# MOVABLE 5-CONFIGURATIONS

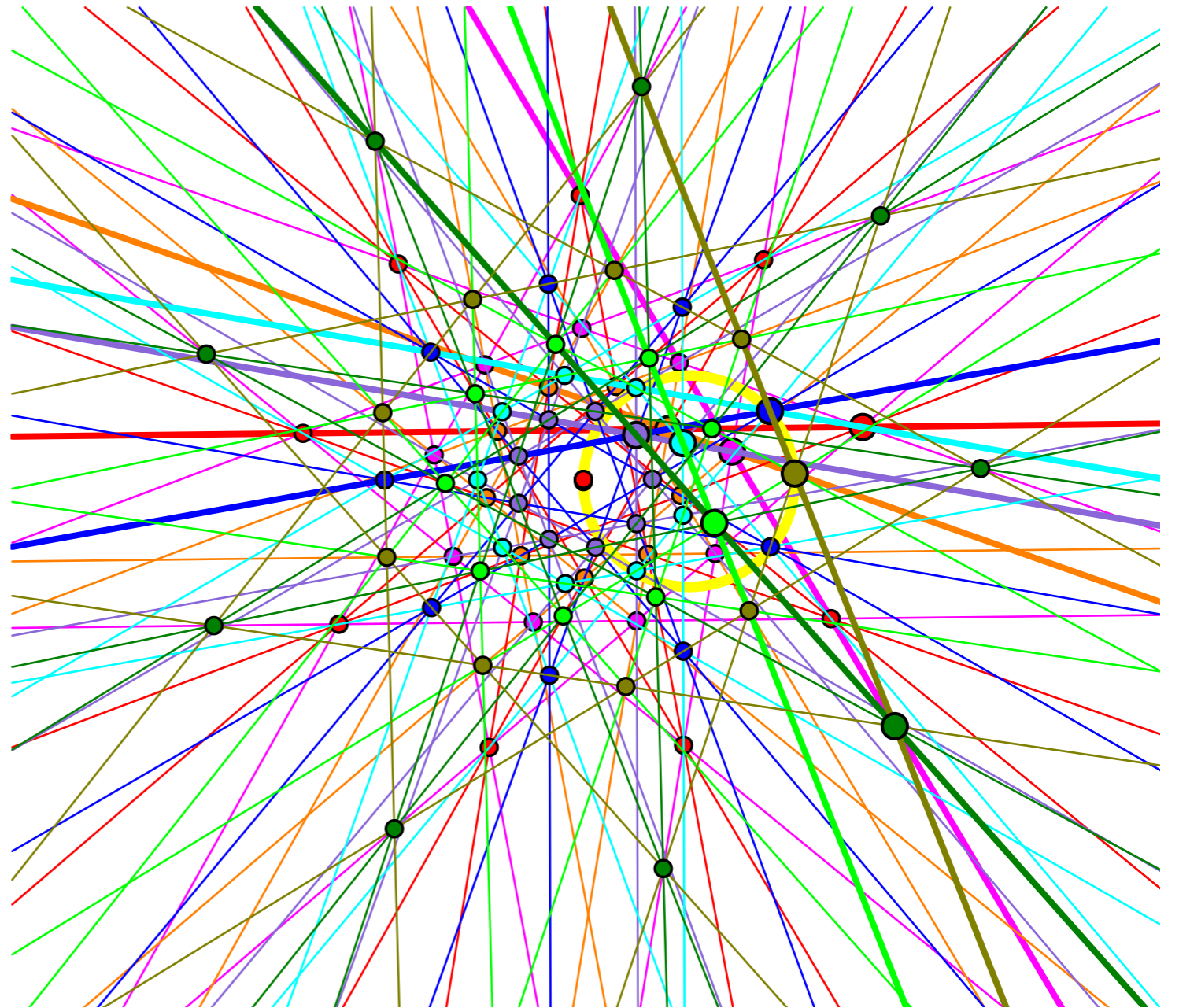
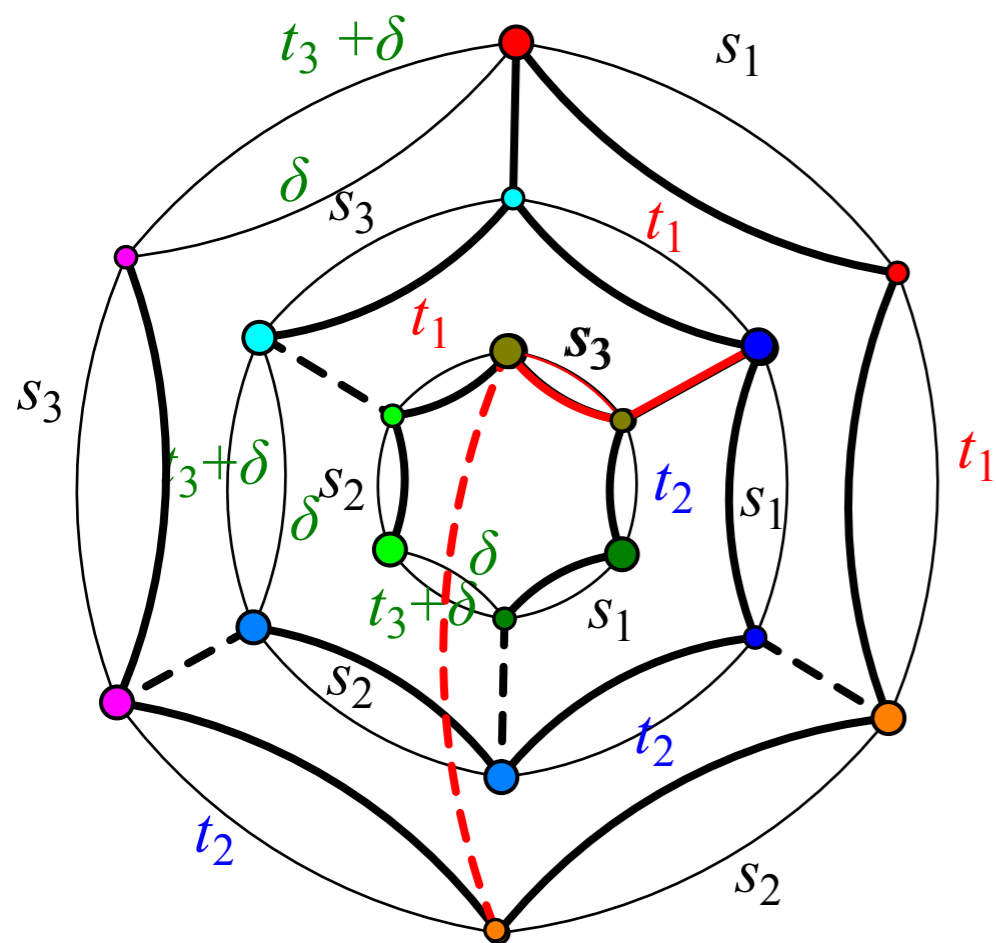
Joint with Lander VerHoef



Celestial Configuration  $m\#(s_1, t_1; s_2, t_2; s_3, t_3); S \cap T = \emptyset$

# MOVABLE 5-CONFIGURATIONS

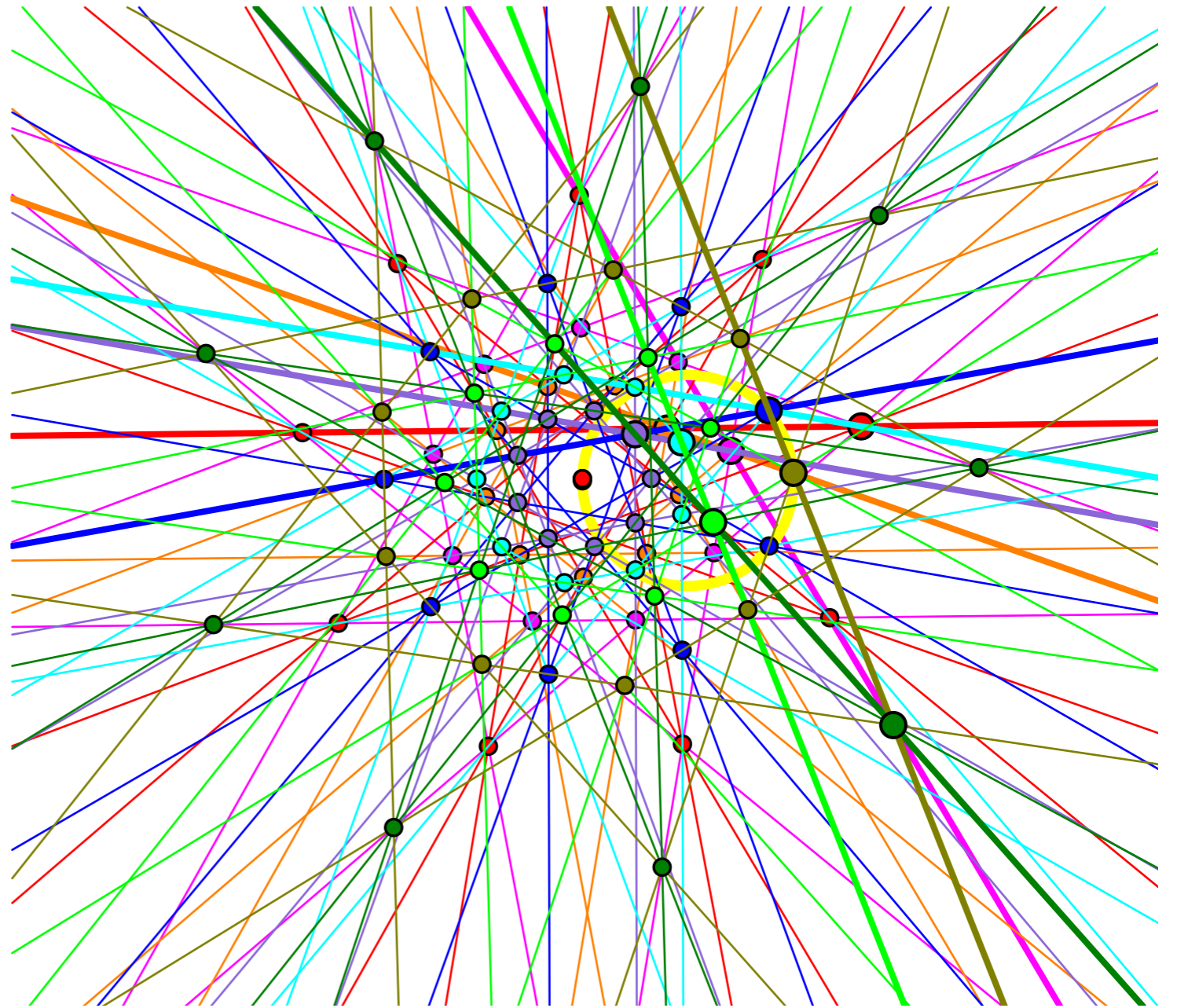
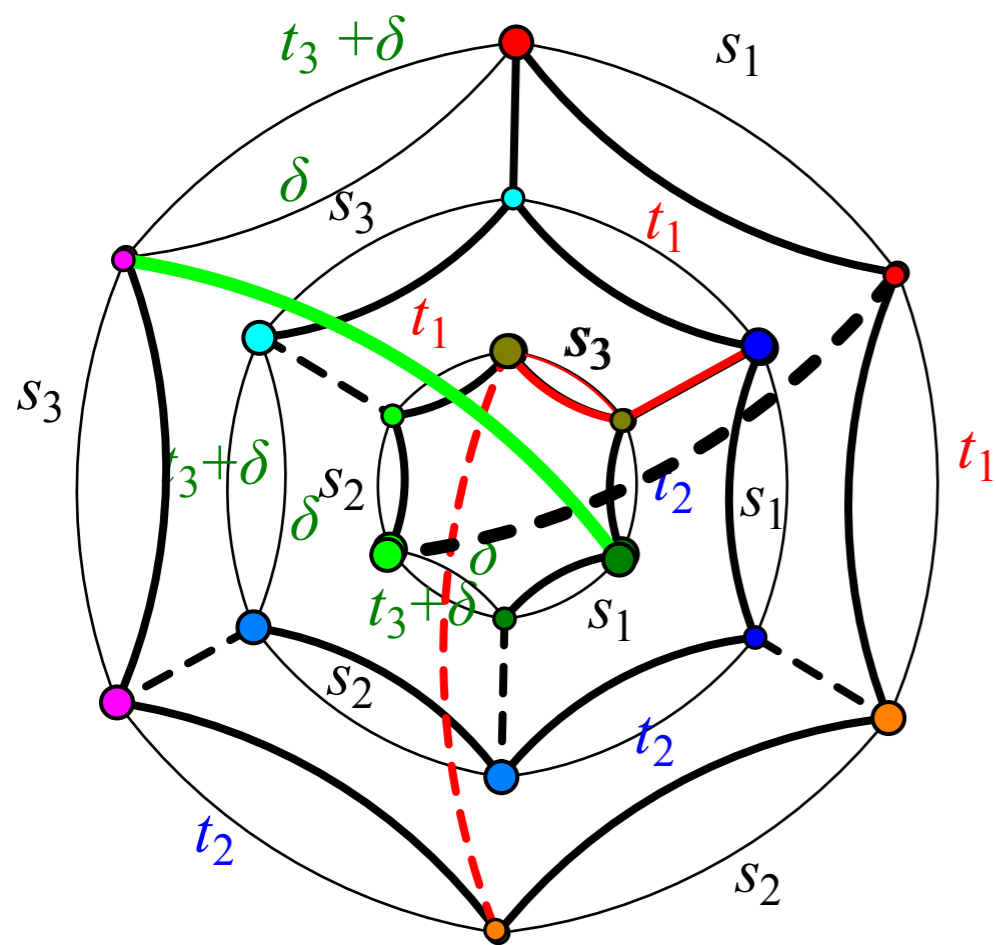
Joint with Lander VerHoef



Celestial Configuration  $m\#(s_1, t_1; s_2, t_2; s_3, t_3); S \cap T = \emptyset$

# MOVABLE 5-CONFIGURATIONS

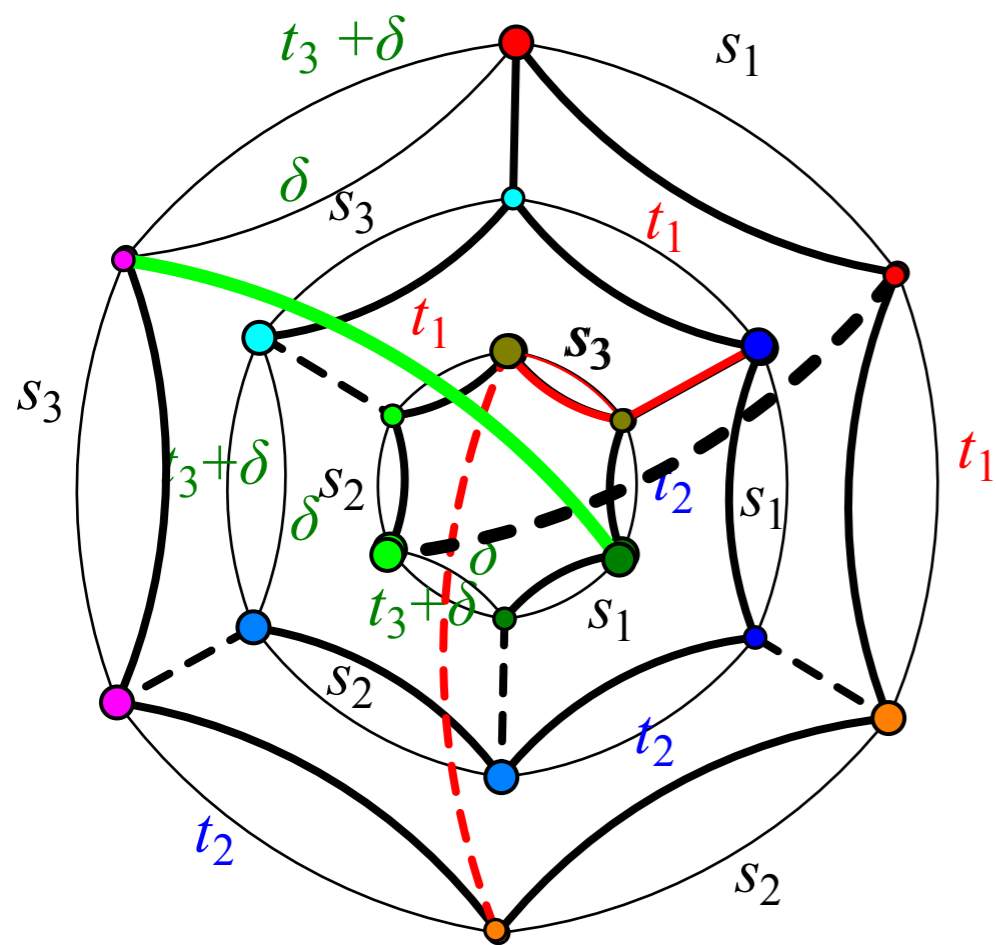
Joint with Lander VerHoef



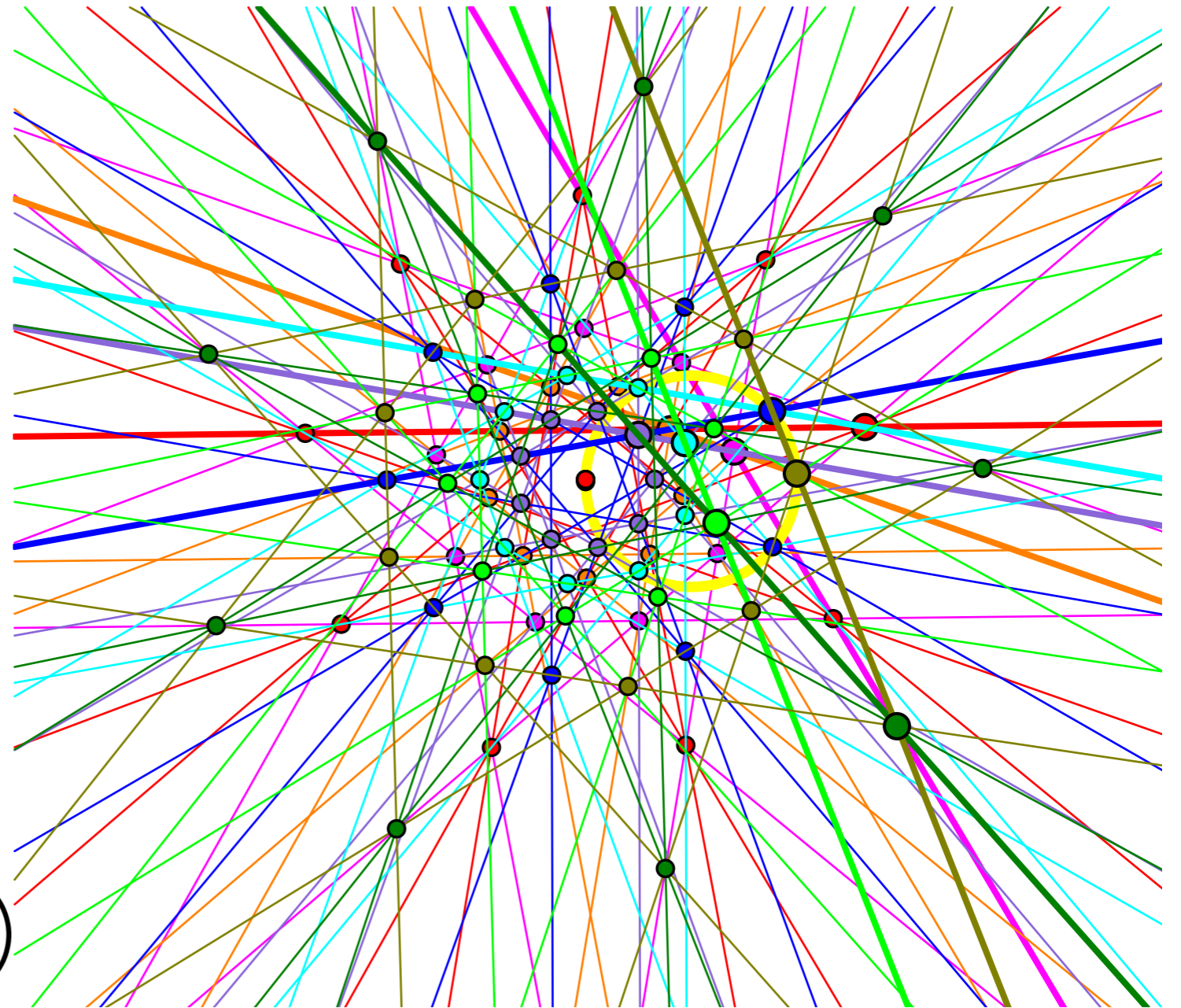
Celestial Configuration  $m\#(s_1, t_1; s_2, t_2; s_3, t_3); S \cap T = \emptyset$

# MOVABLE 5-CONFIGURATIONS

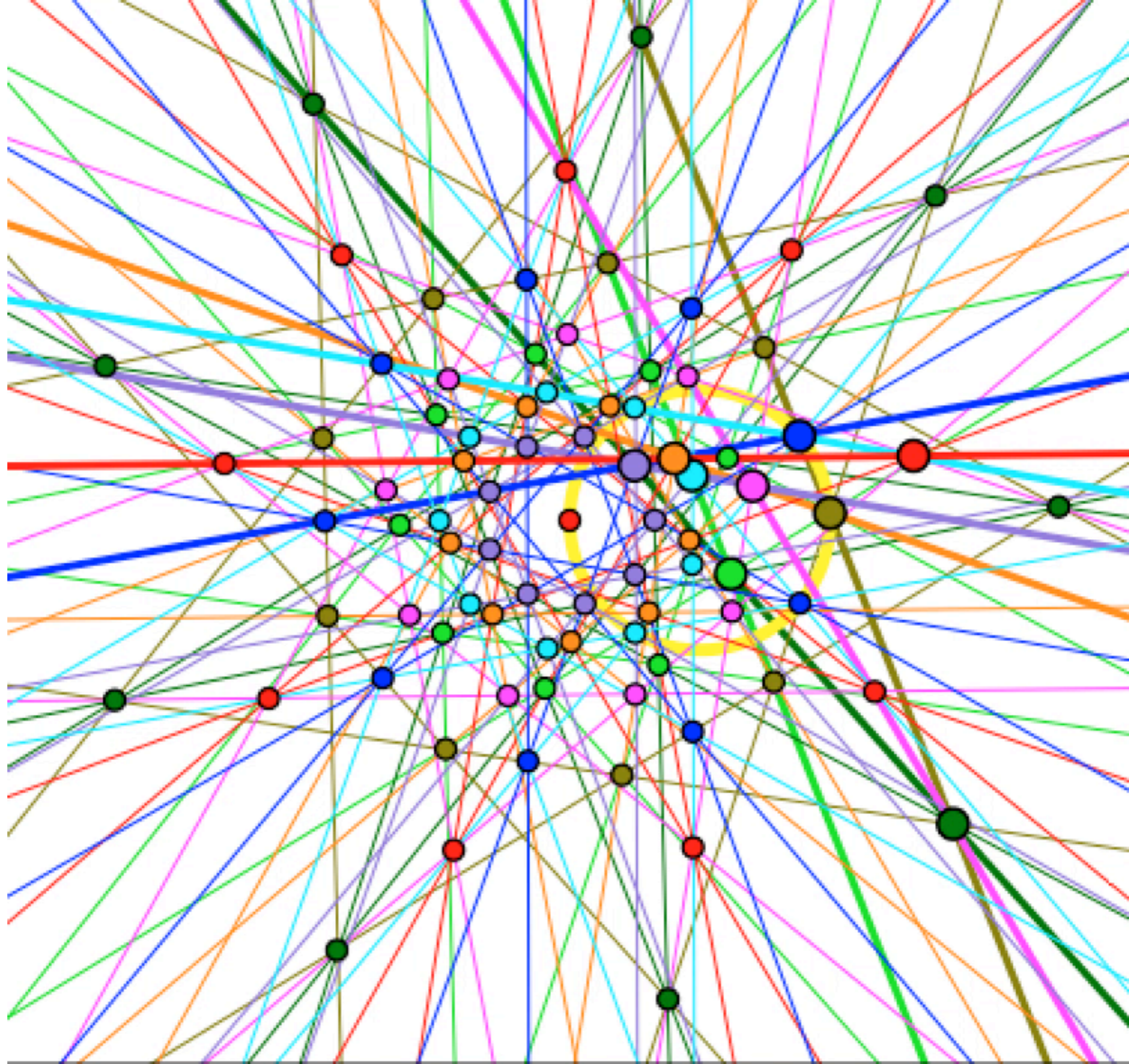
Joint with Lander VerHoef

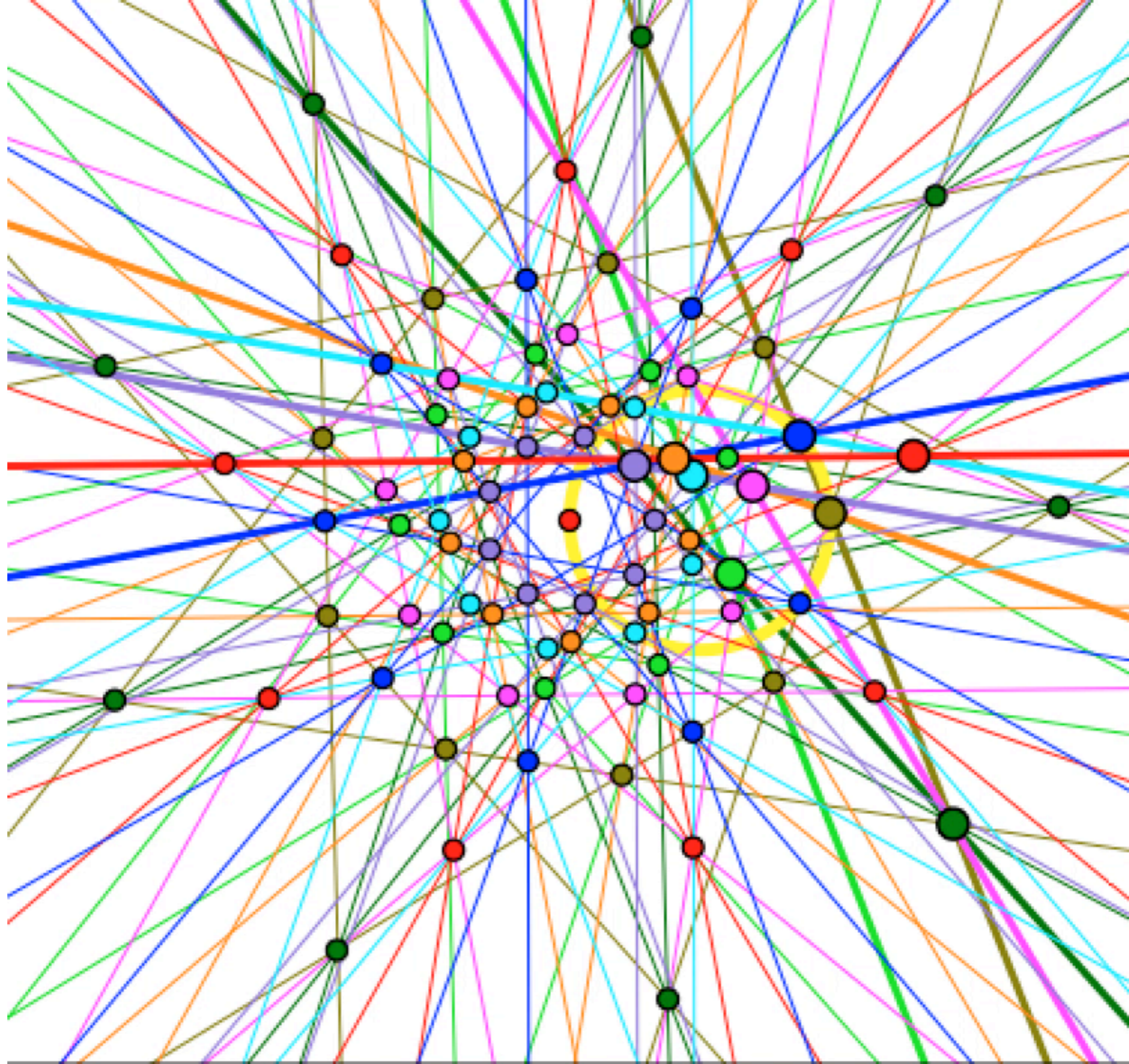


(81<sub>5</sub>)

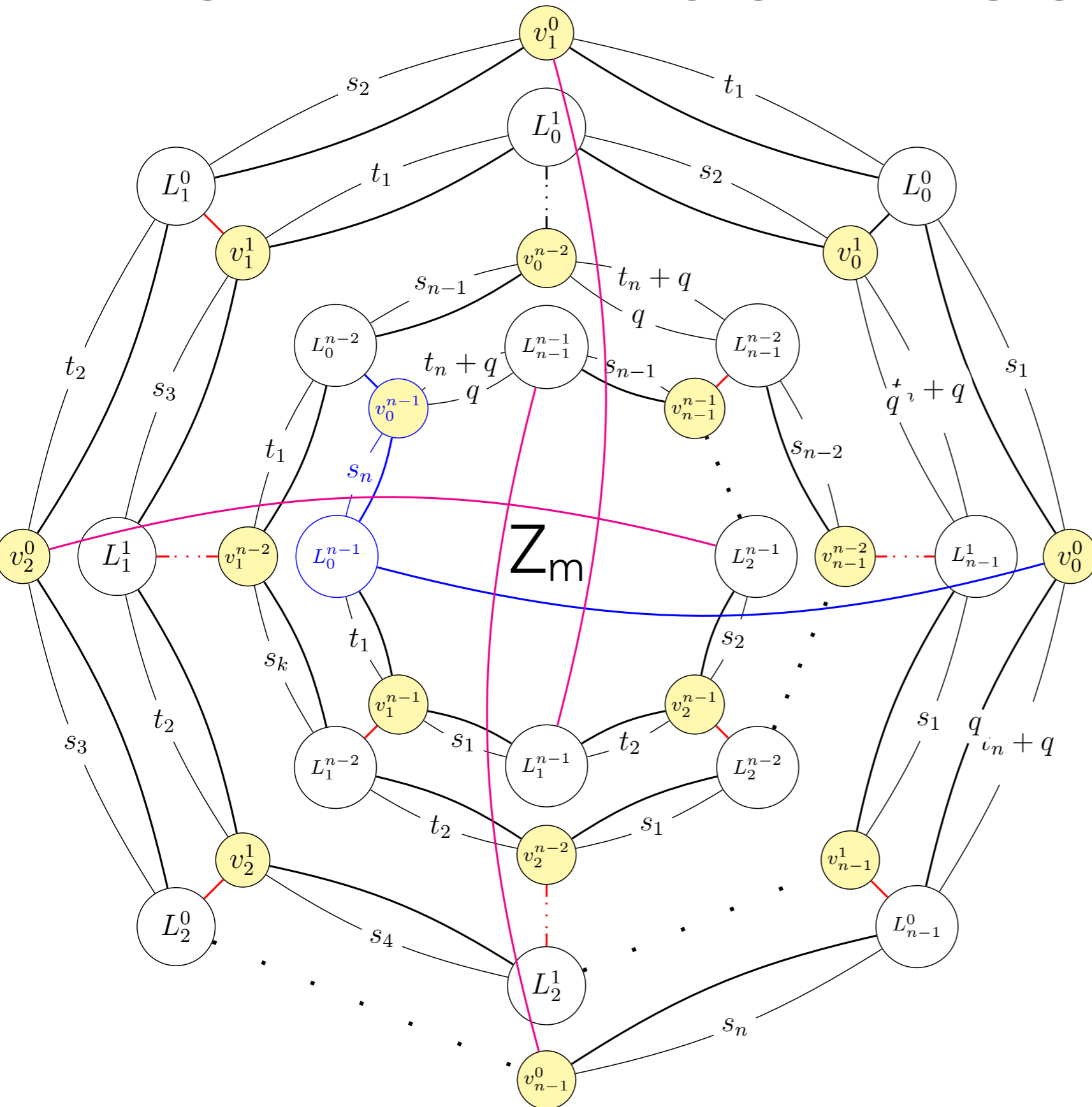


Celestial Configuration  $m\#(s_1, t_1; s_2, t_2; s_3, t_3); S \cap T = \emptyset$





# MOVABLE 5-CONFIGURATION

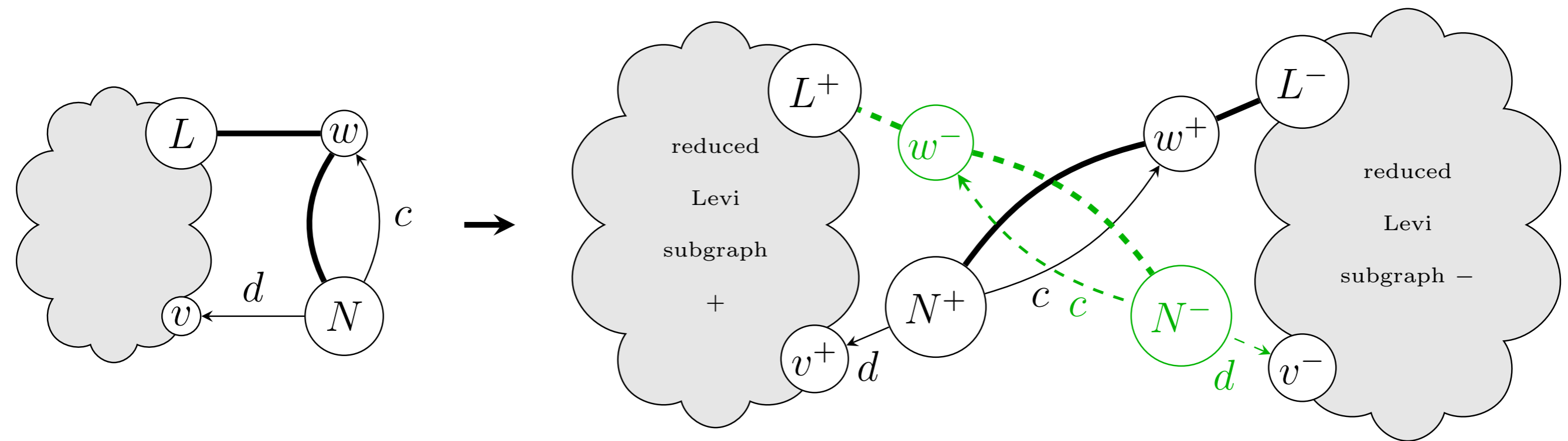


$k$ -celestial 4-configuration ( $mk_4$ )

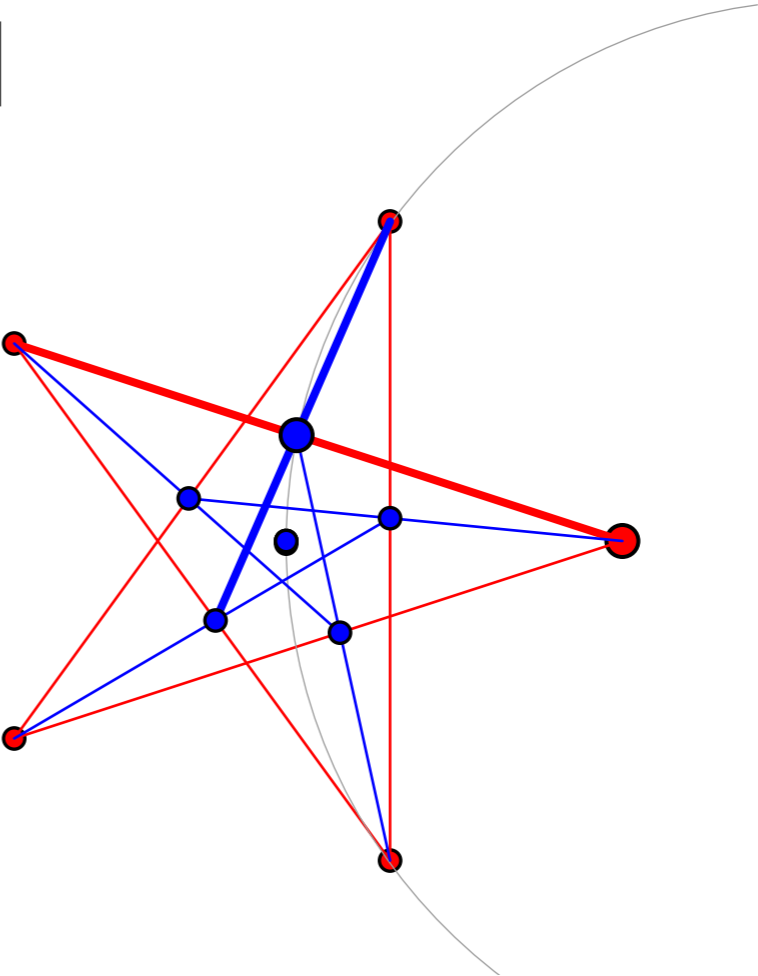
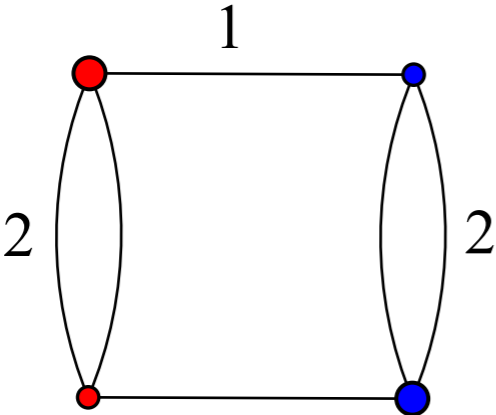


$k$  rings;  $k-2$   
degrees of  
freedom  
( $(mk^2)_5$ )

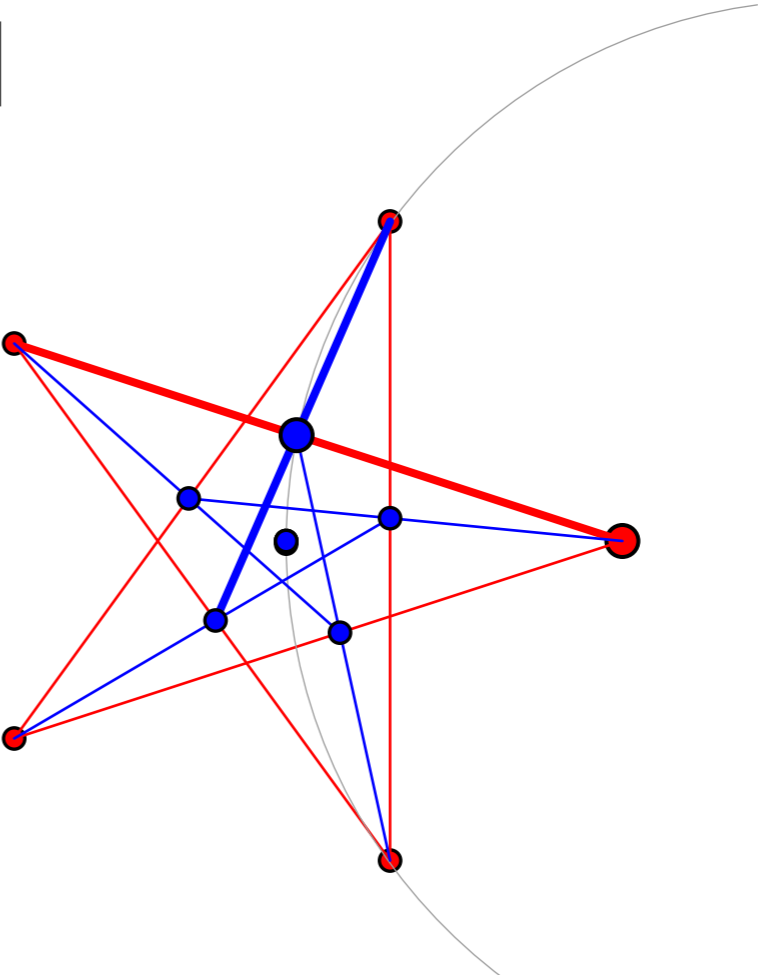
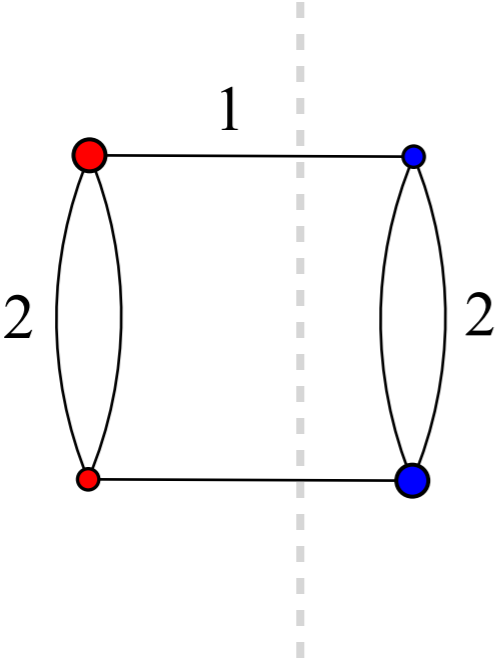
# DIHEDRALIZATION



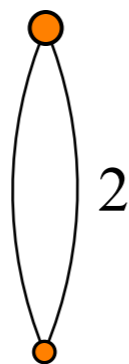
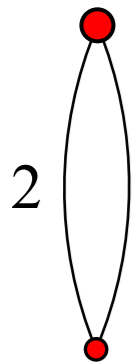
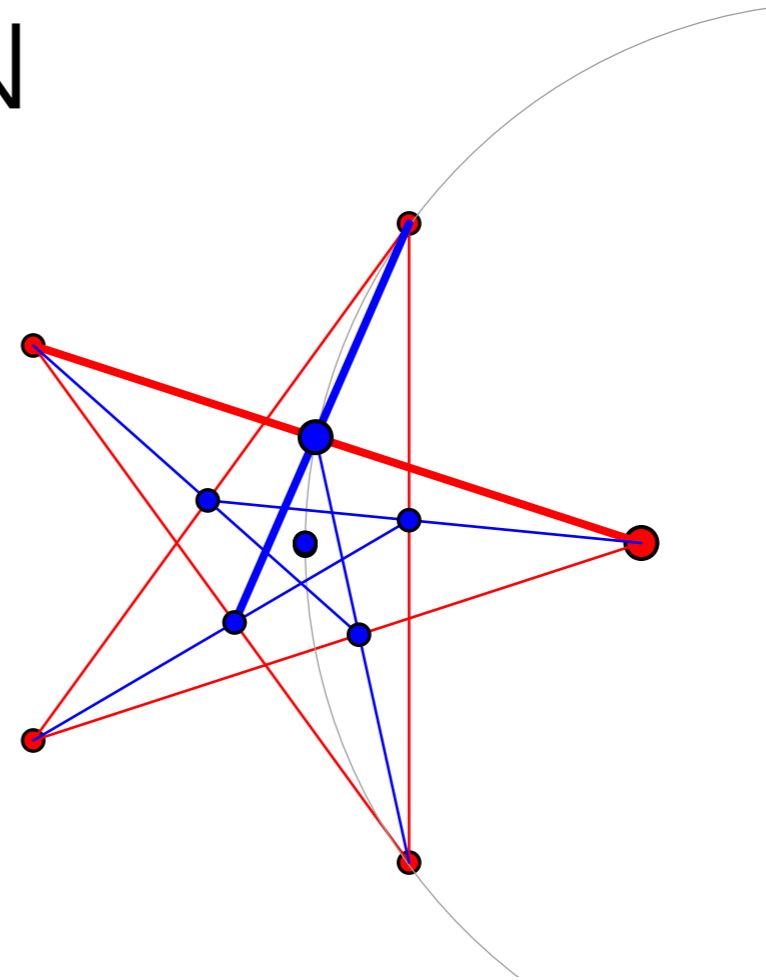
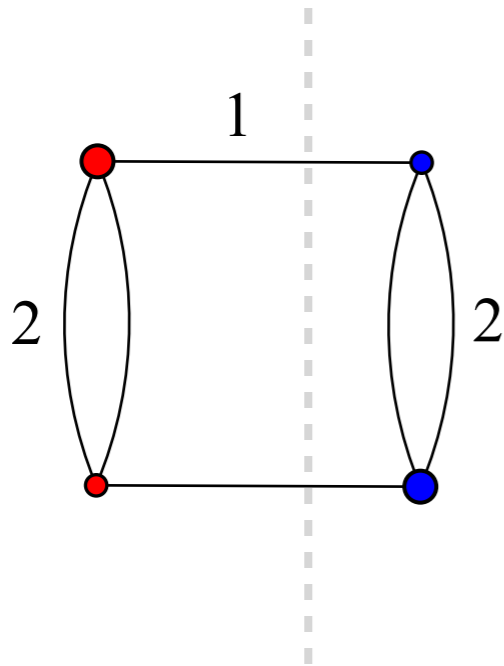
# DIHEDRALIZATION



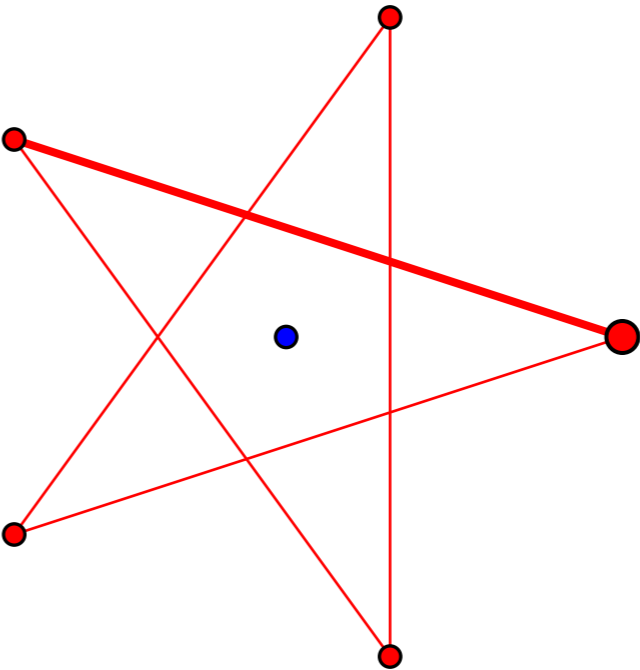
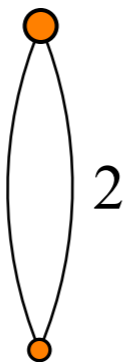
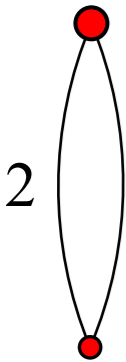
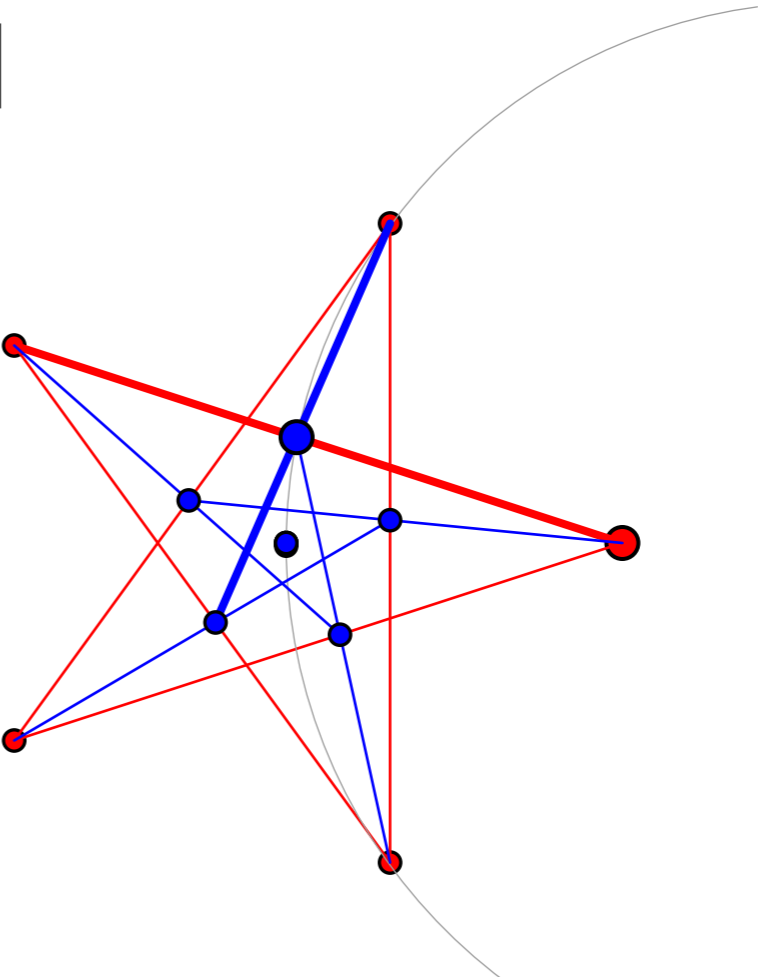
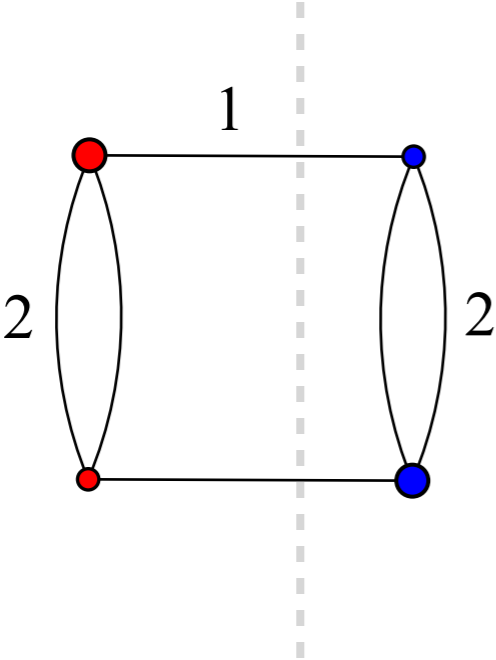
# DIHEDRALIZATION



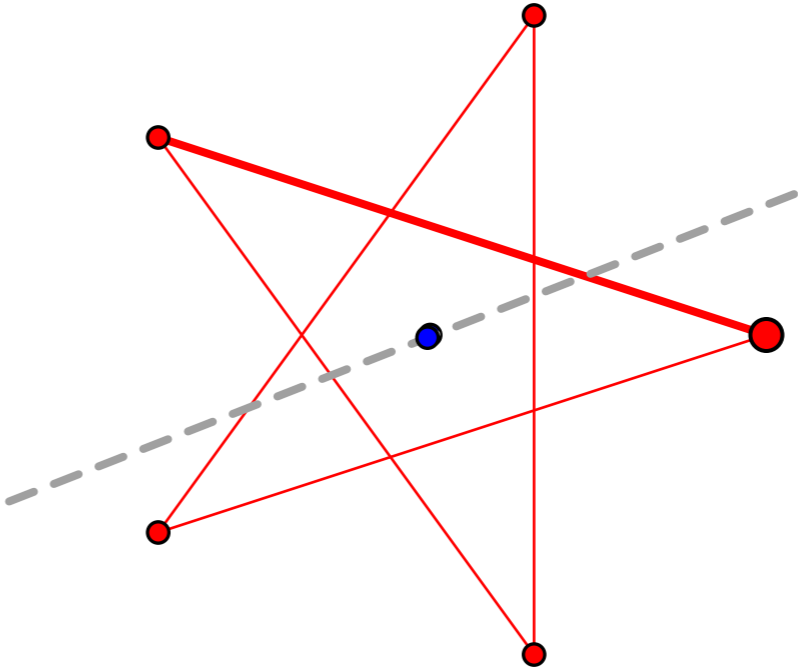
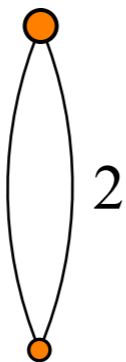
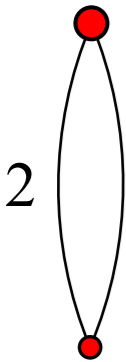
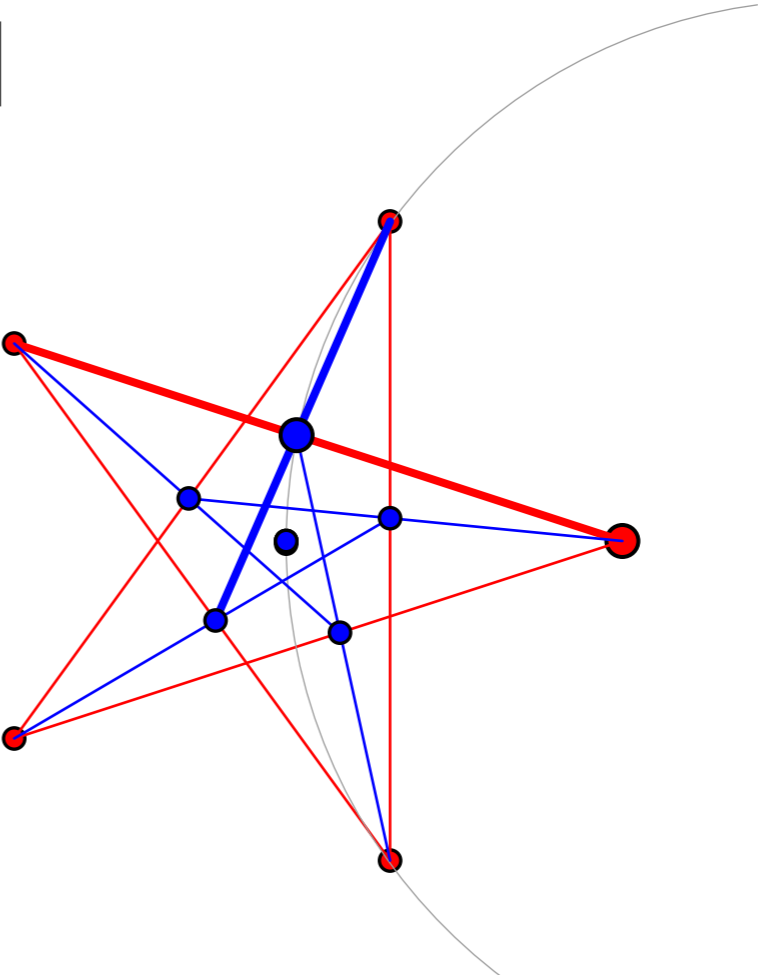
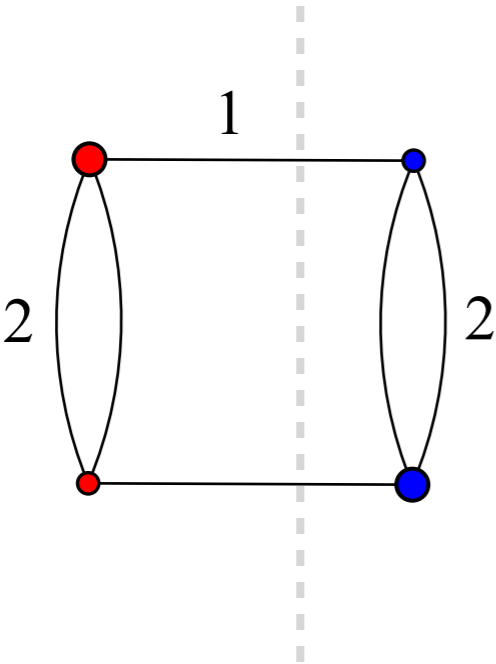
# DIHEDRALIZATION



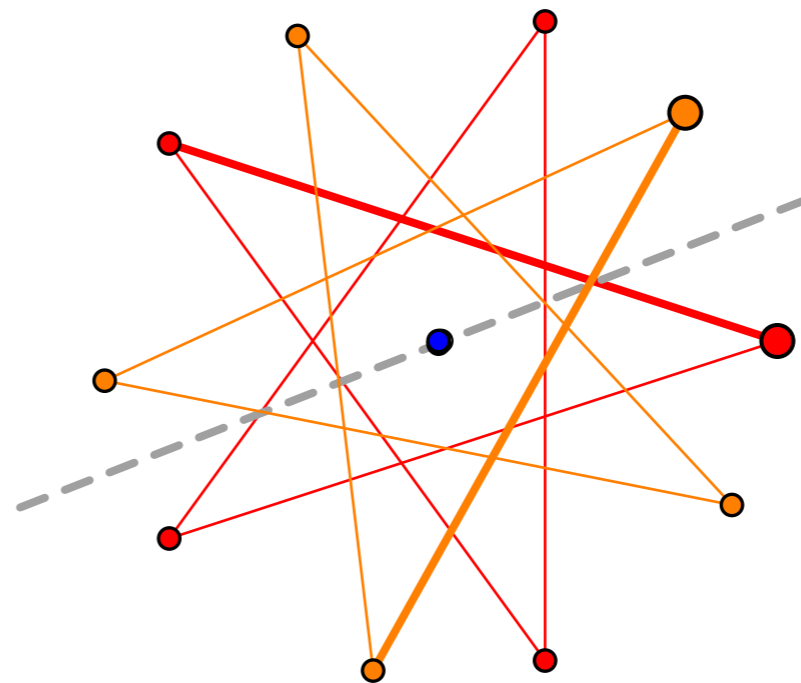
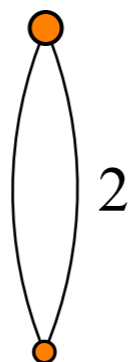
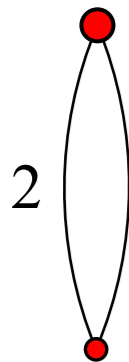
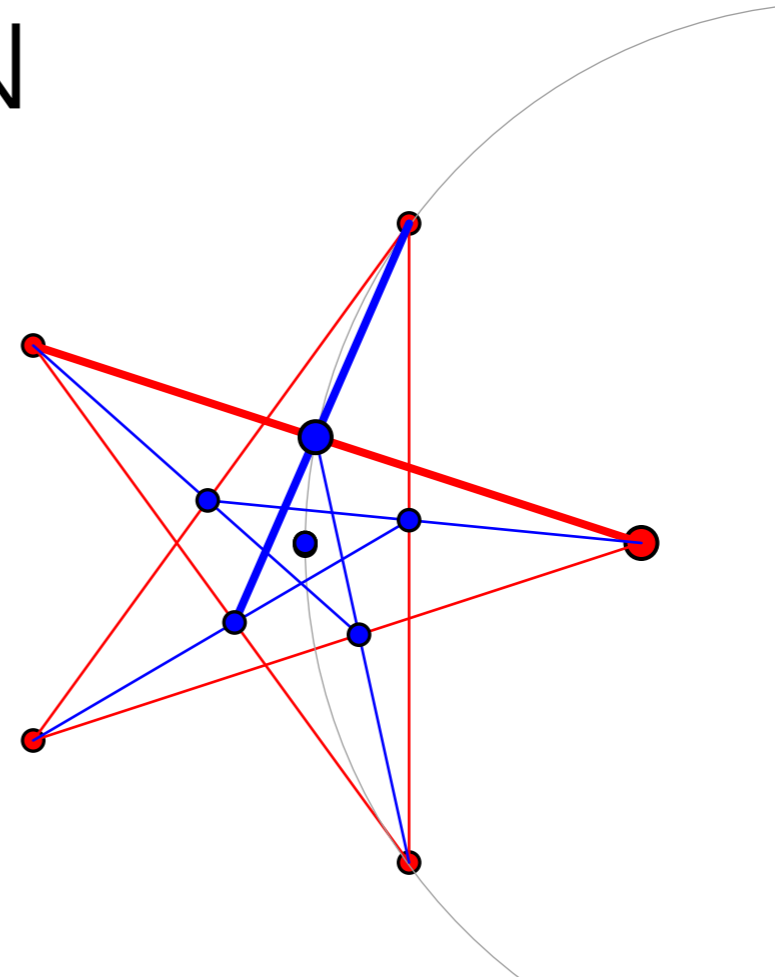
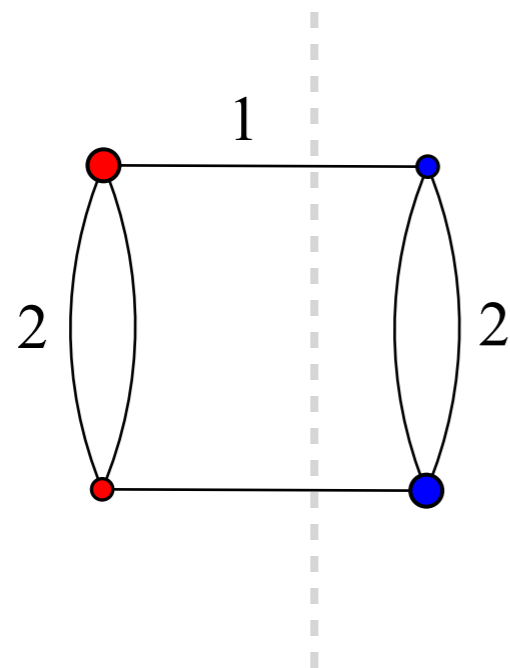
# DIHEDRALIZATION



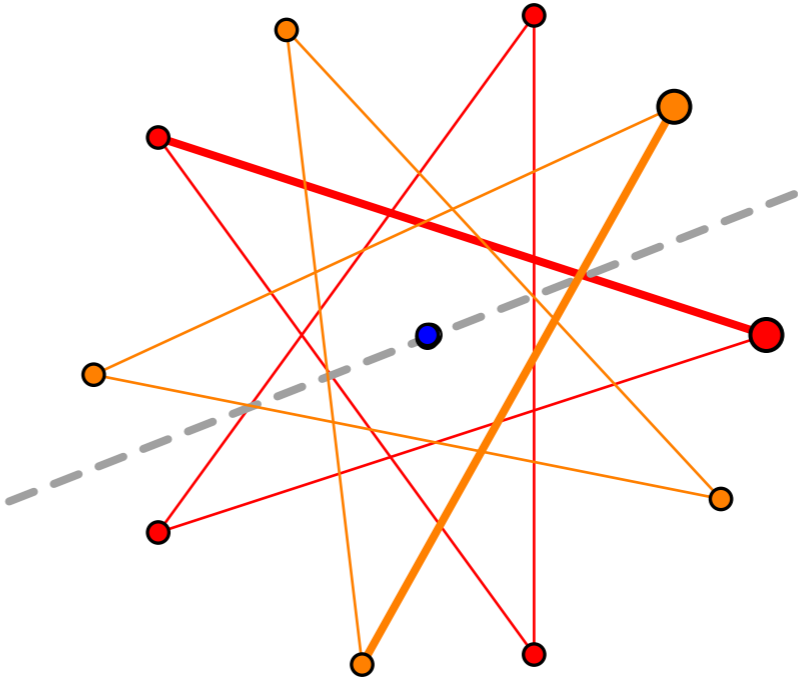
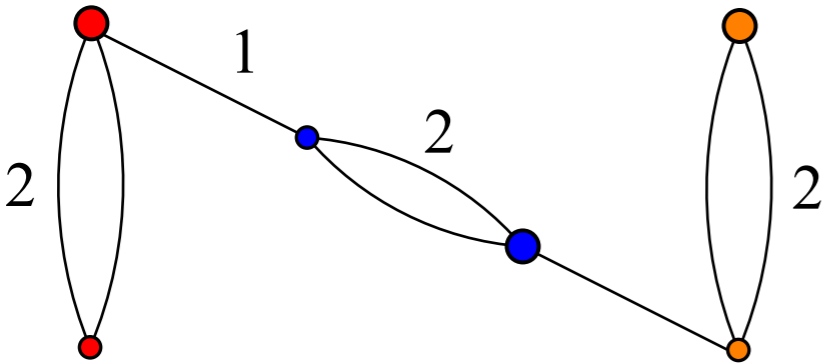
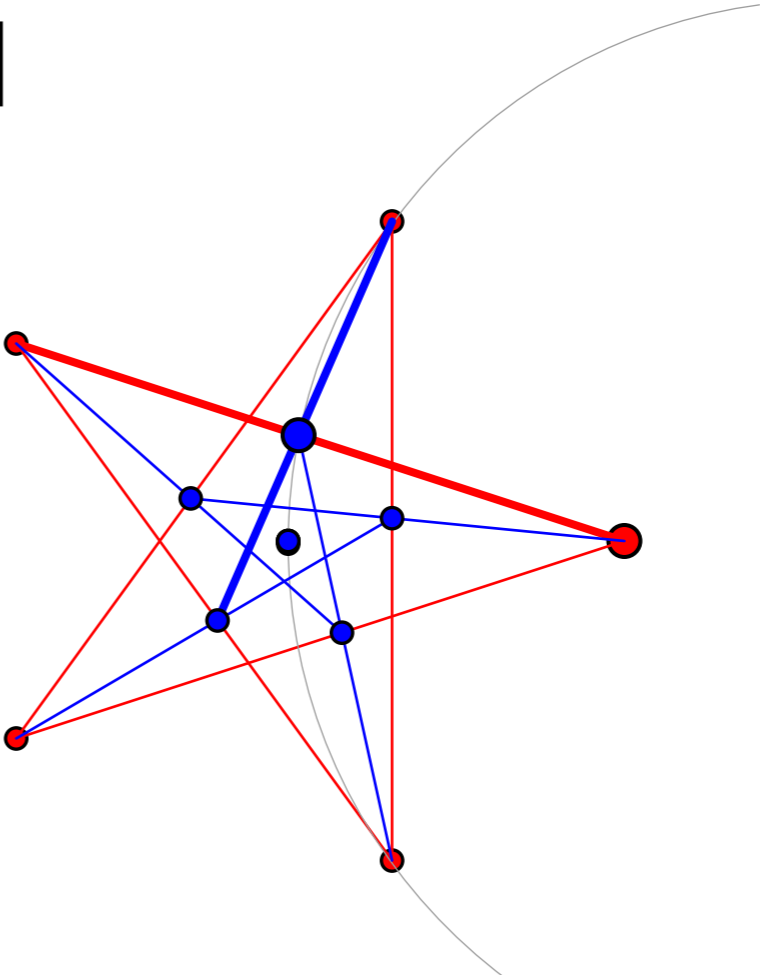
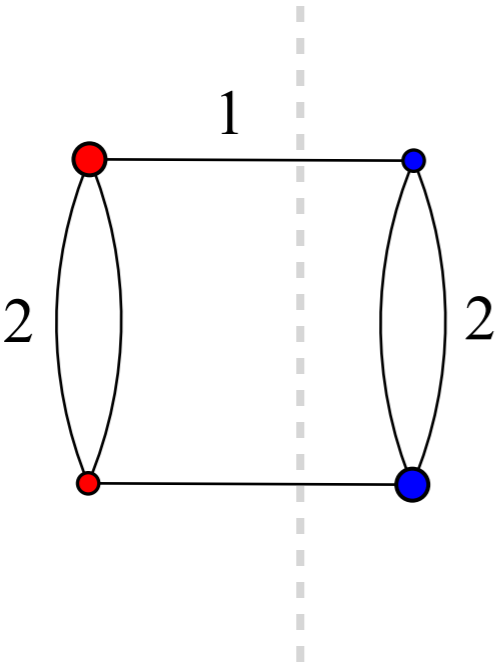
# DIHEDRALIZATION



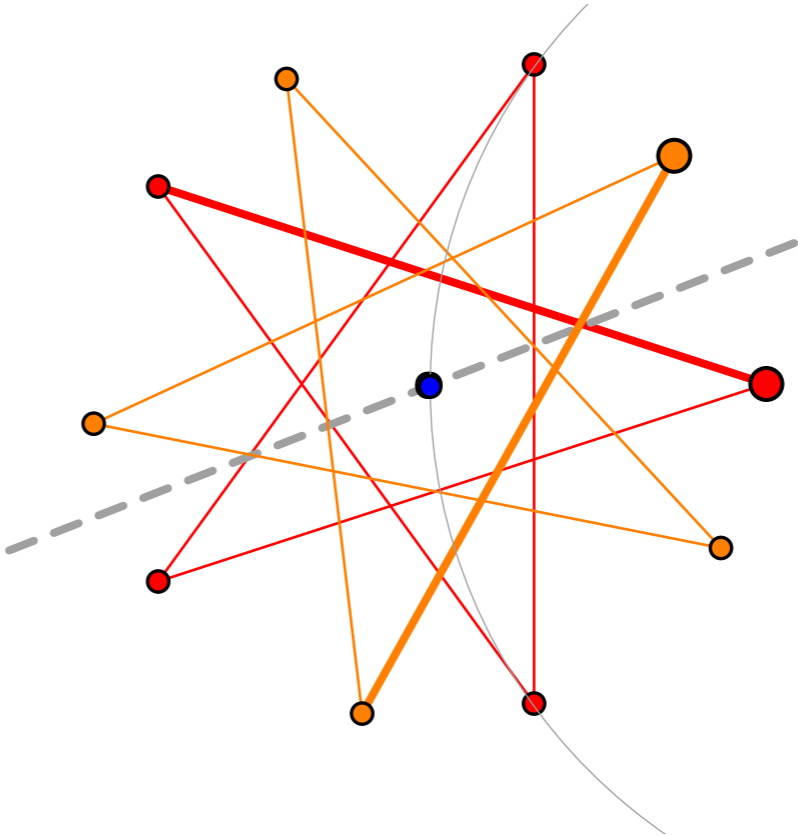
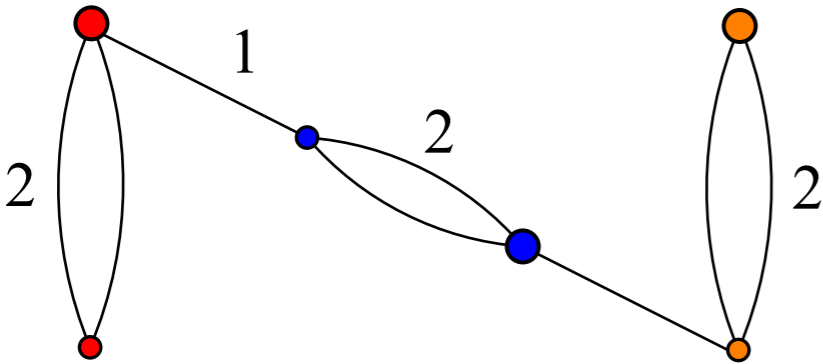
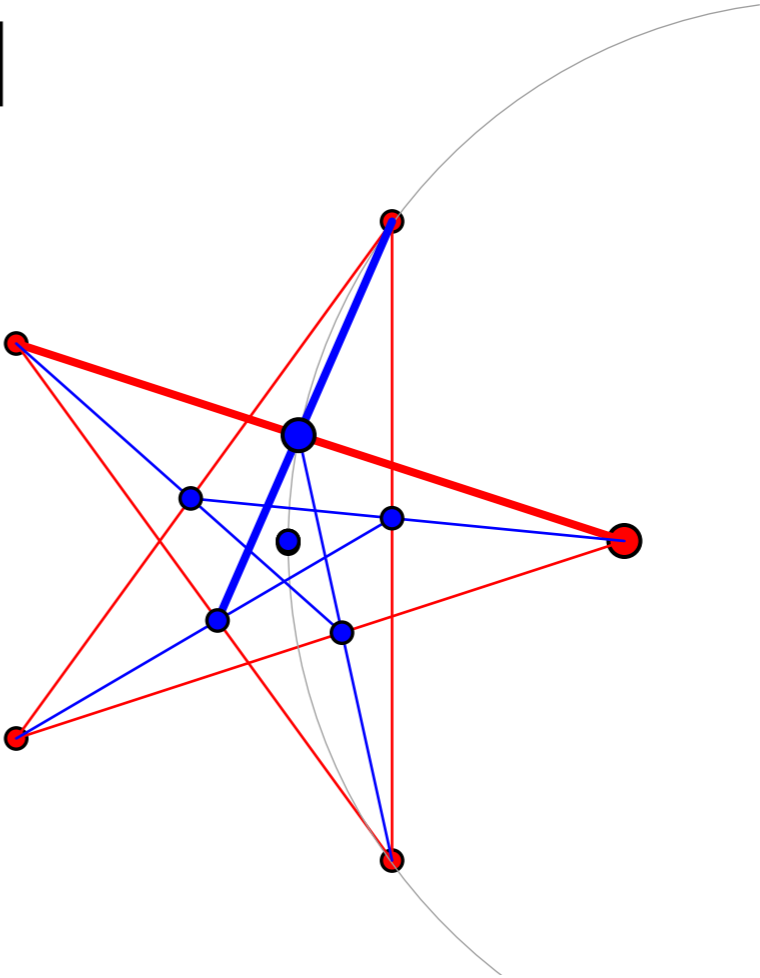
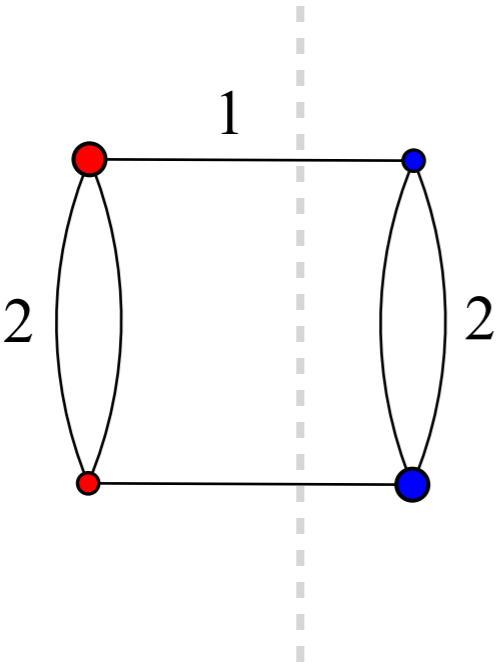
# DIHEDRALIZATION



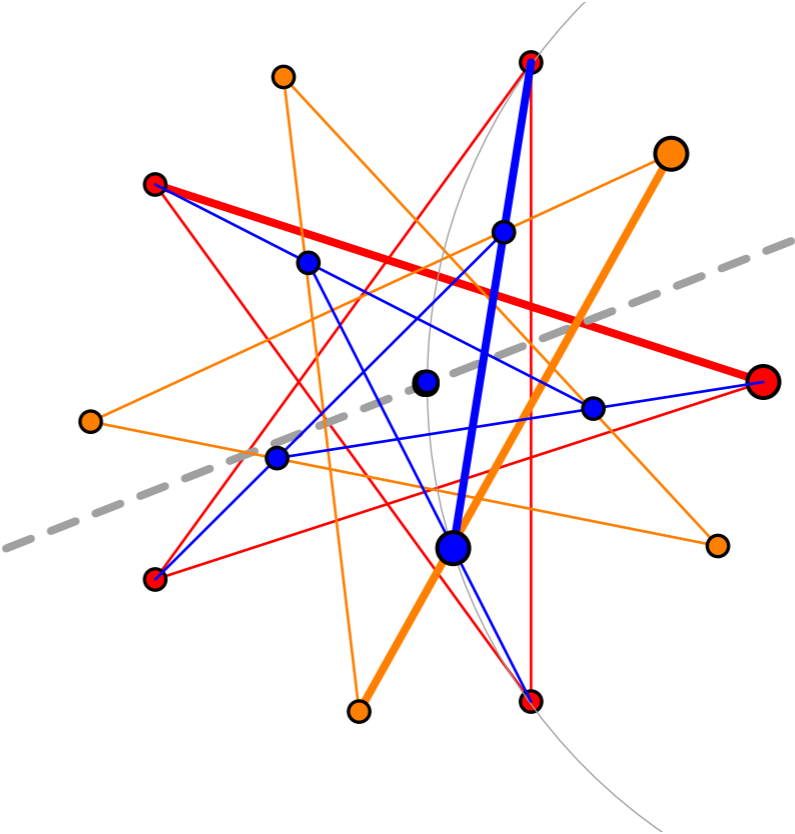
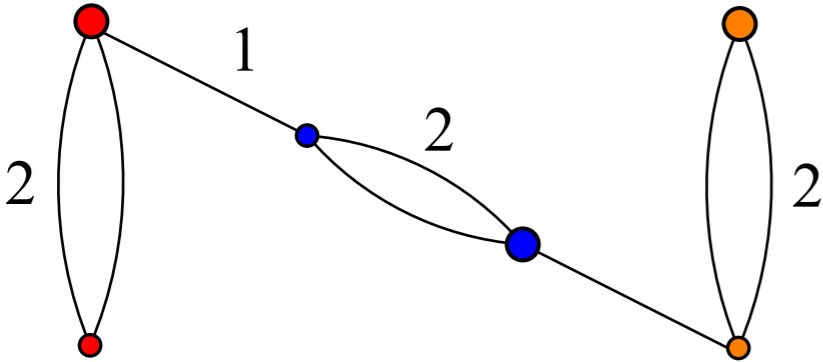
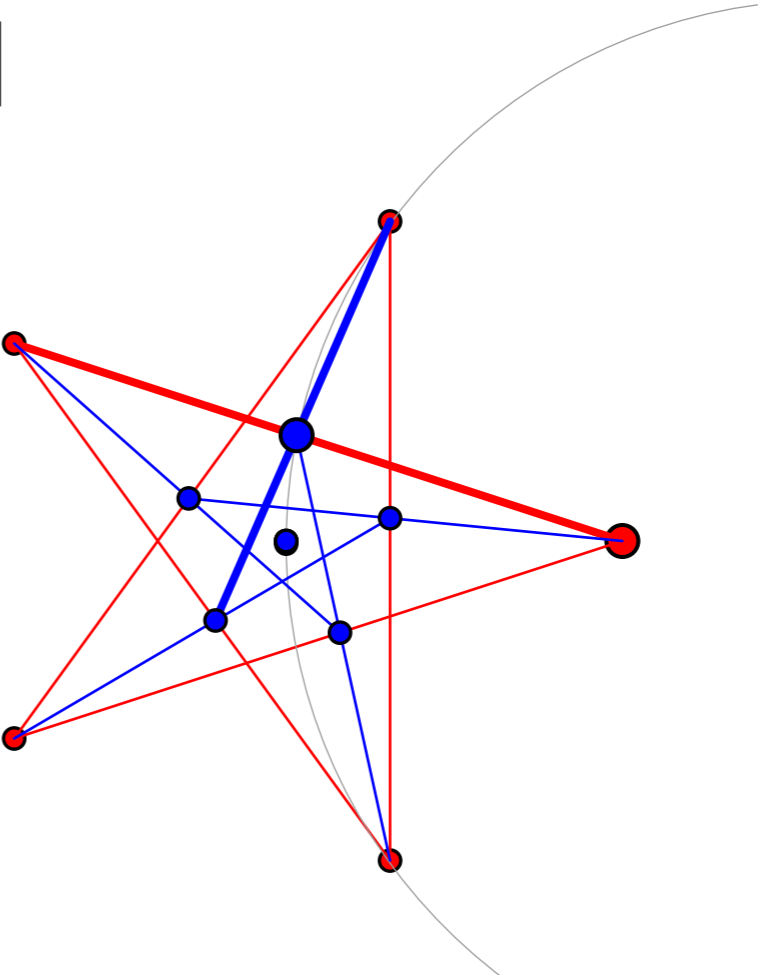
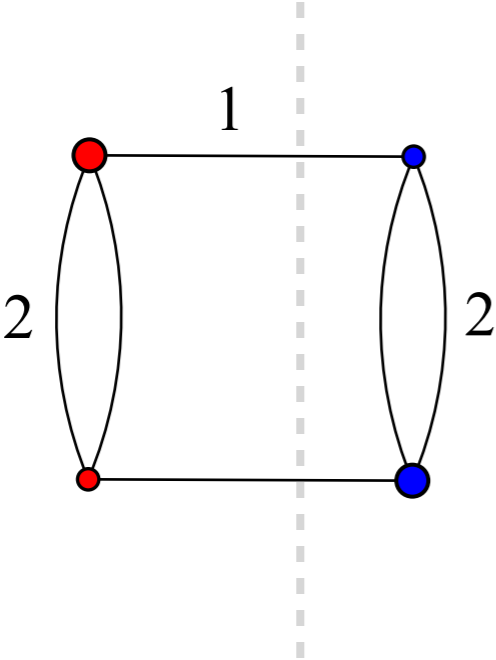
# DIHEDRALIZATION



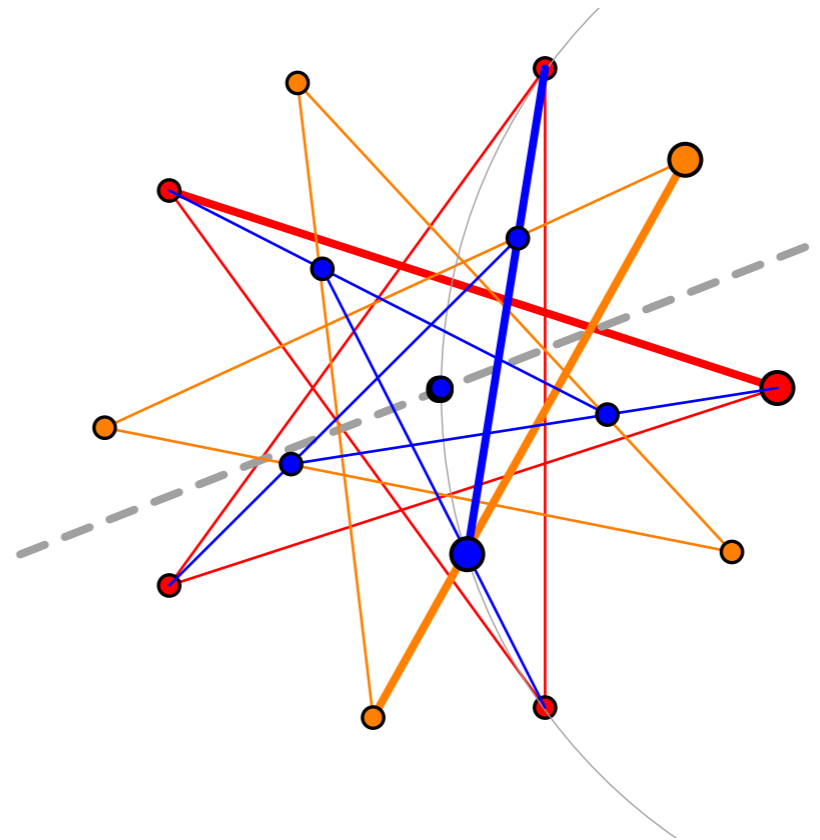
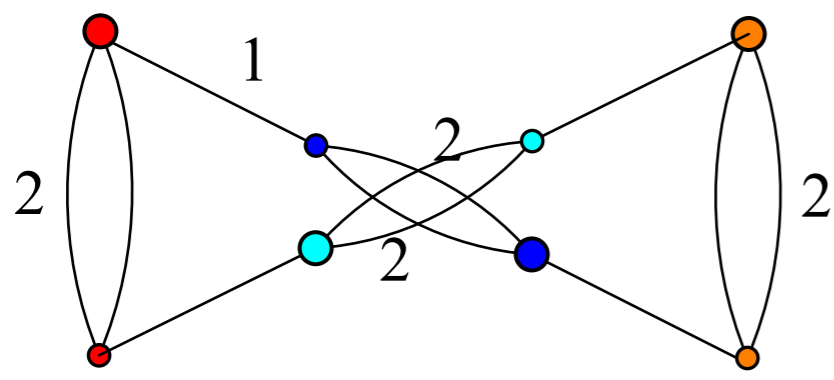
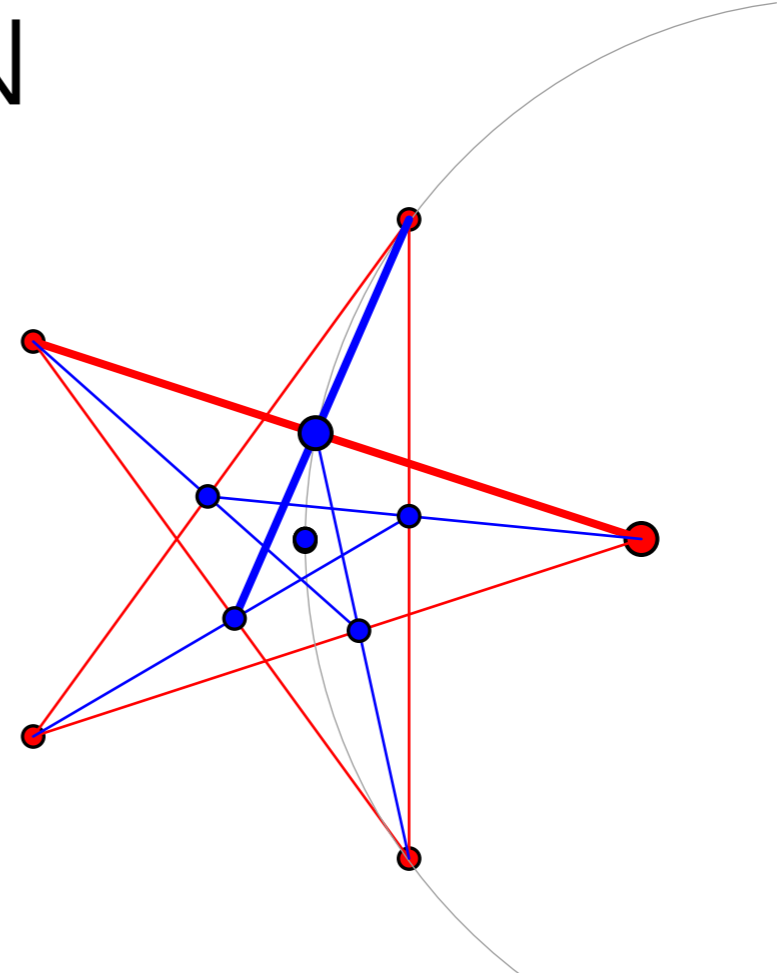
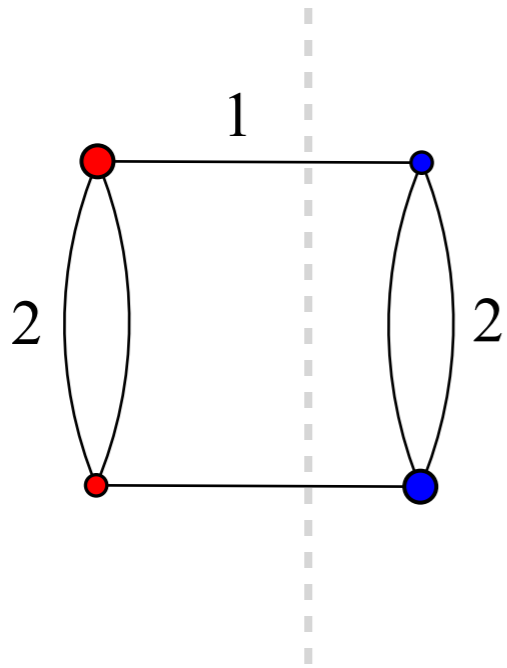
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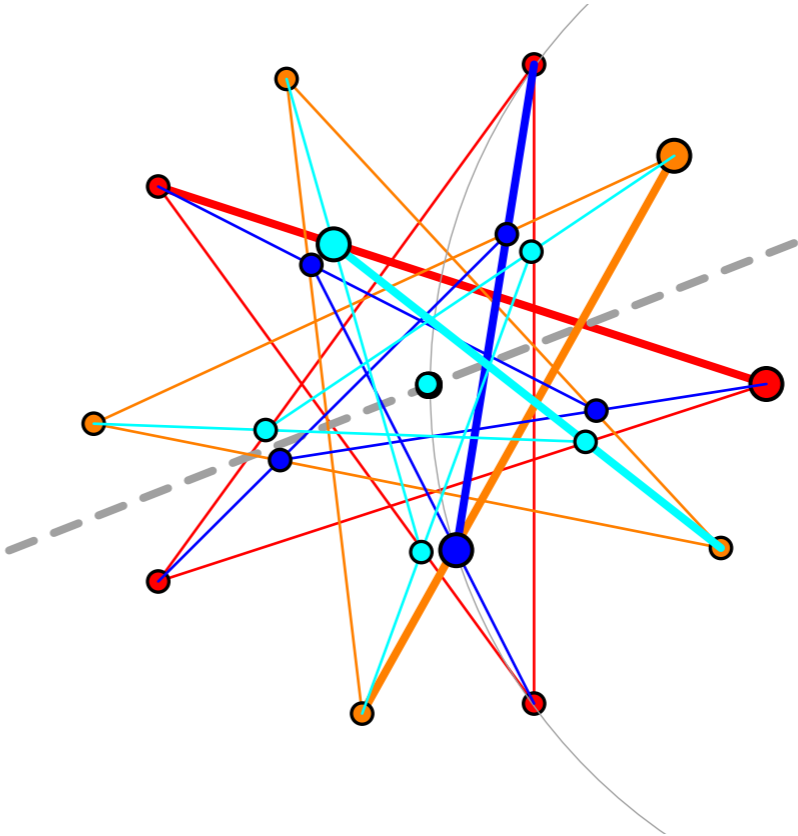
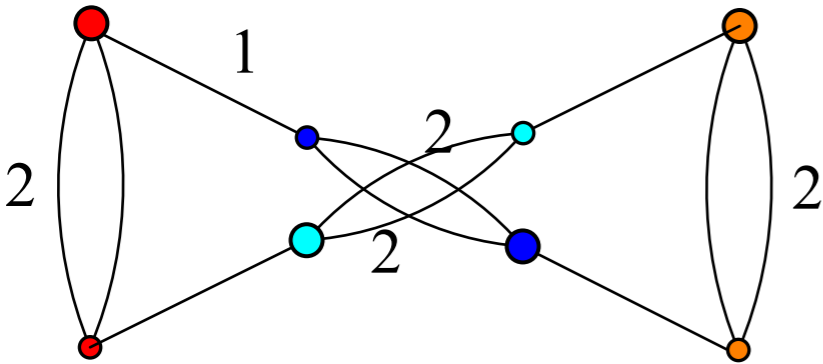
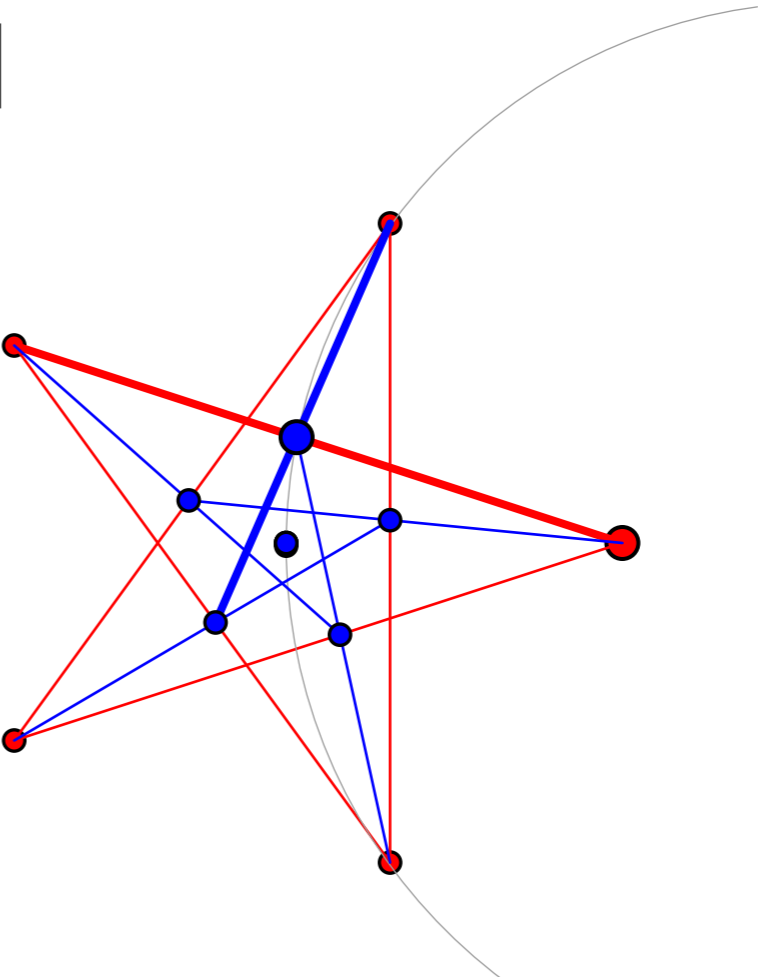
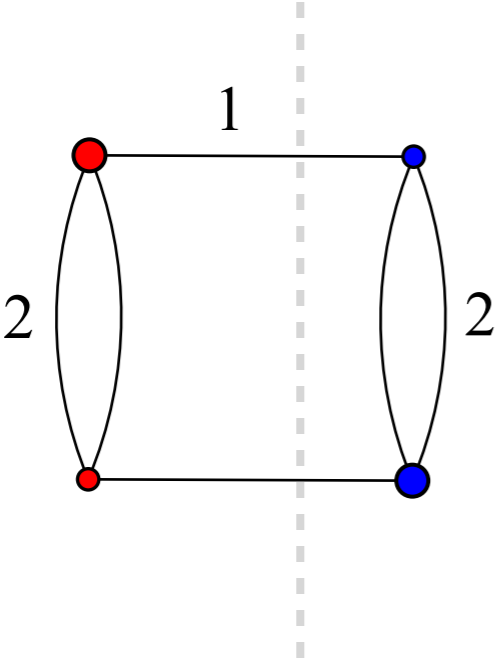
# DIHEDRALIZATION



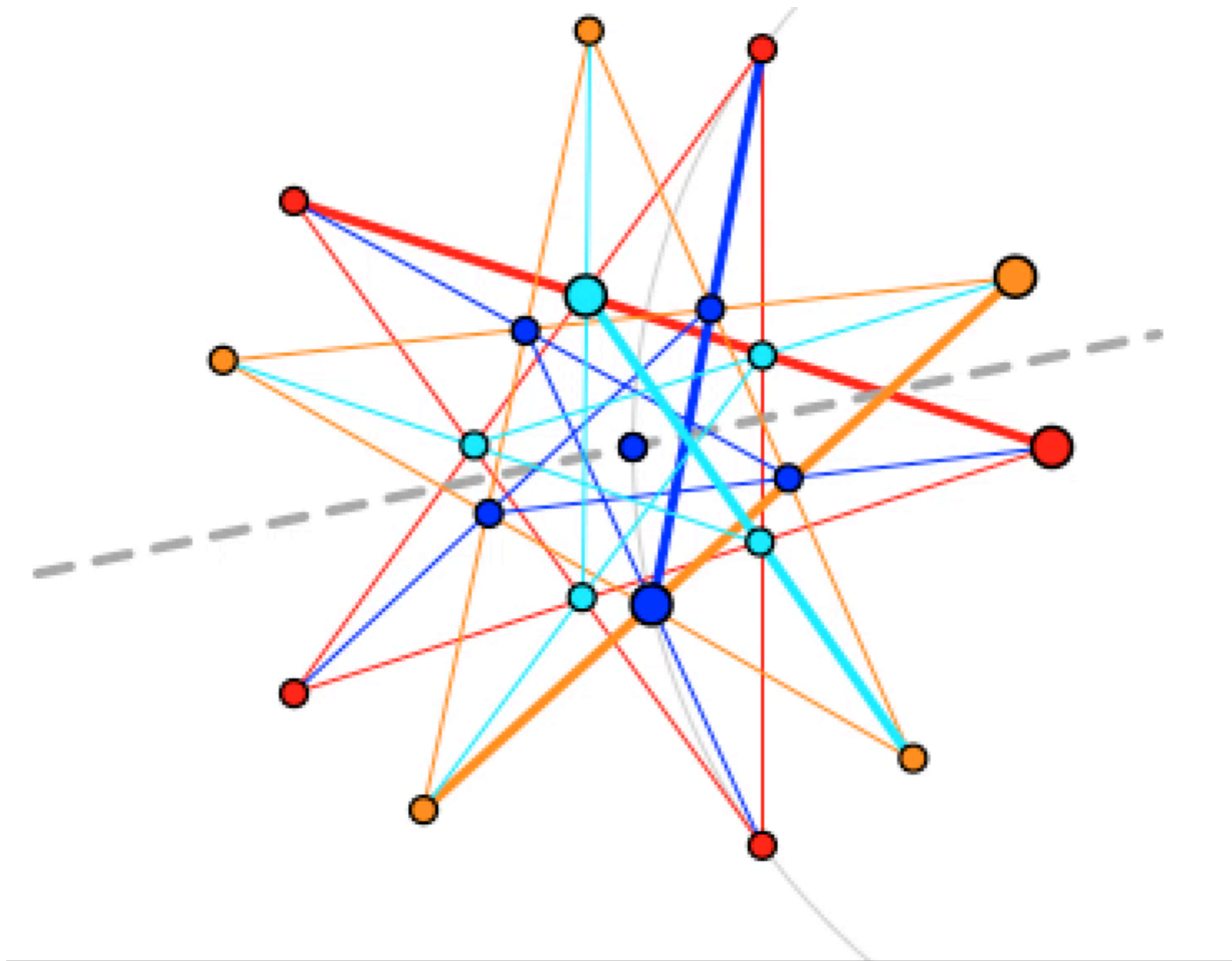
# DIHEDRALIZATION



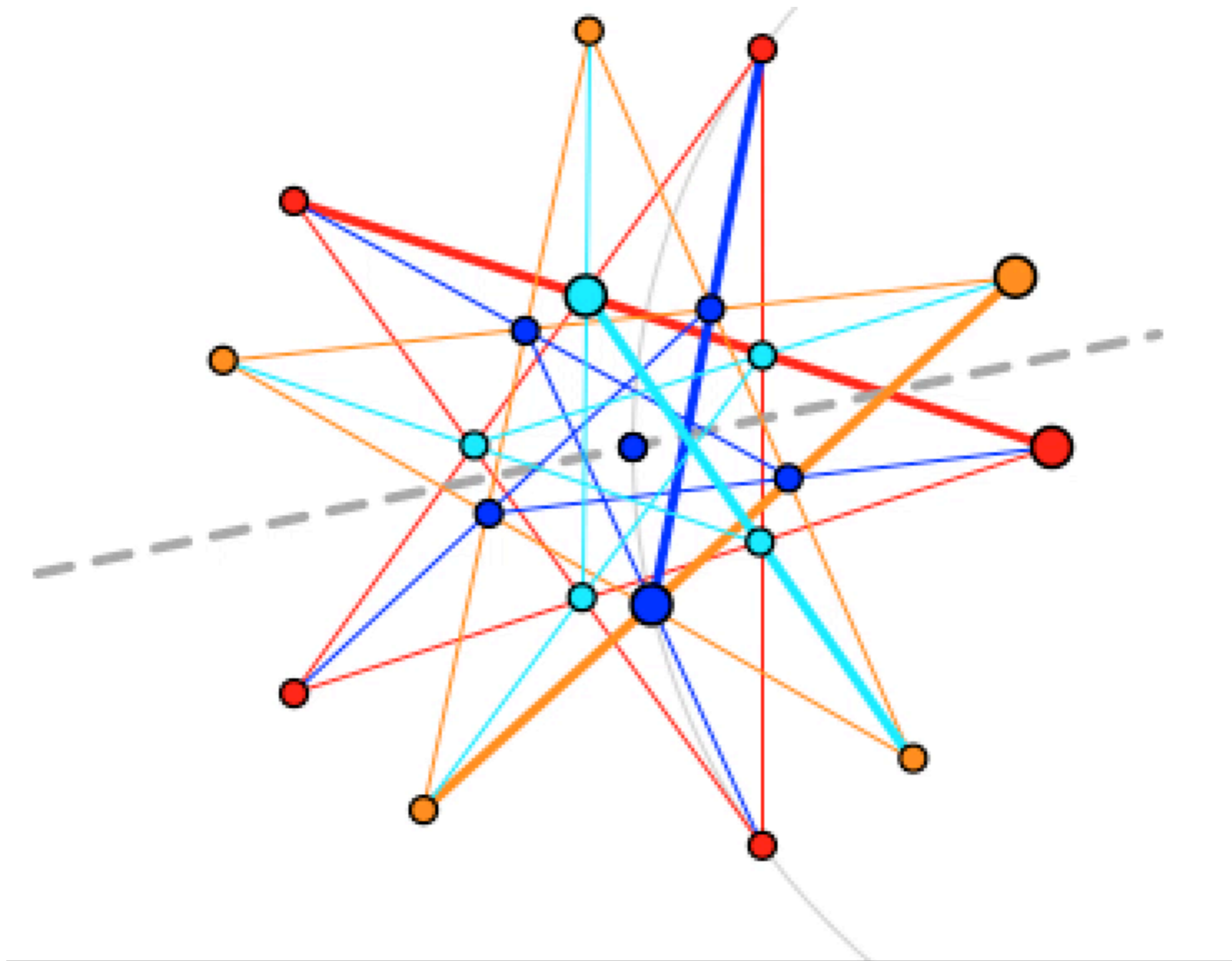
# DIHEDRALIZATION



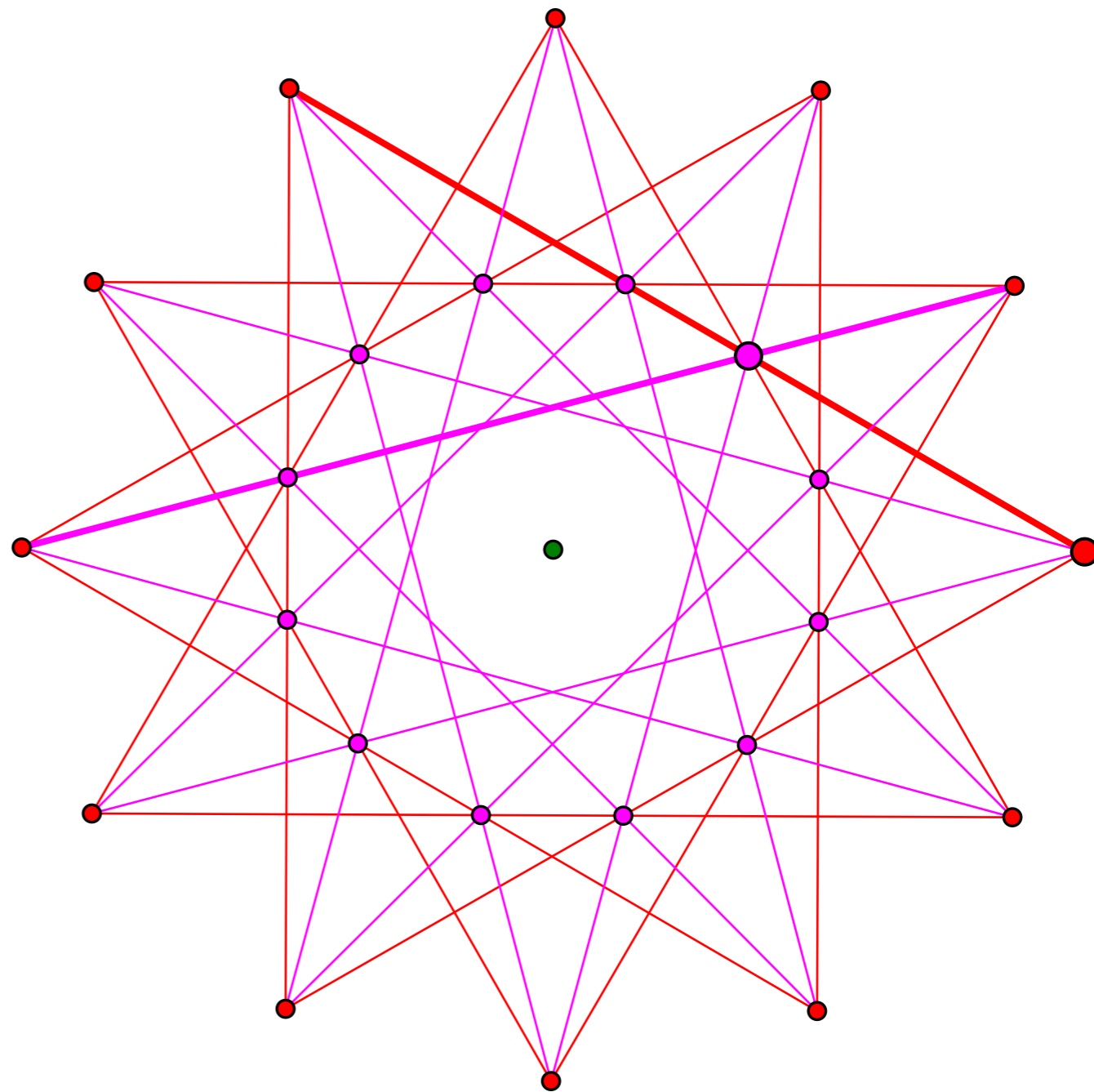
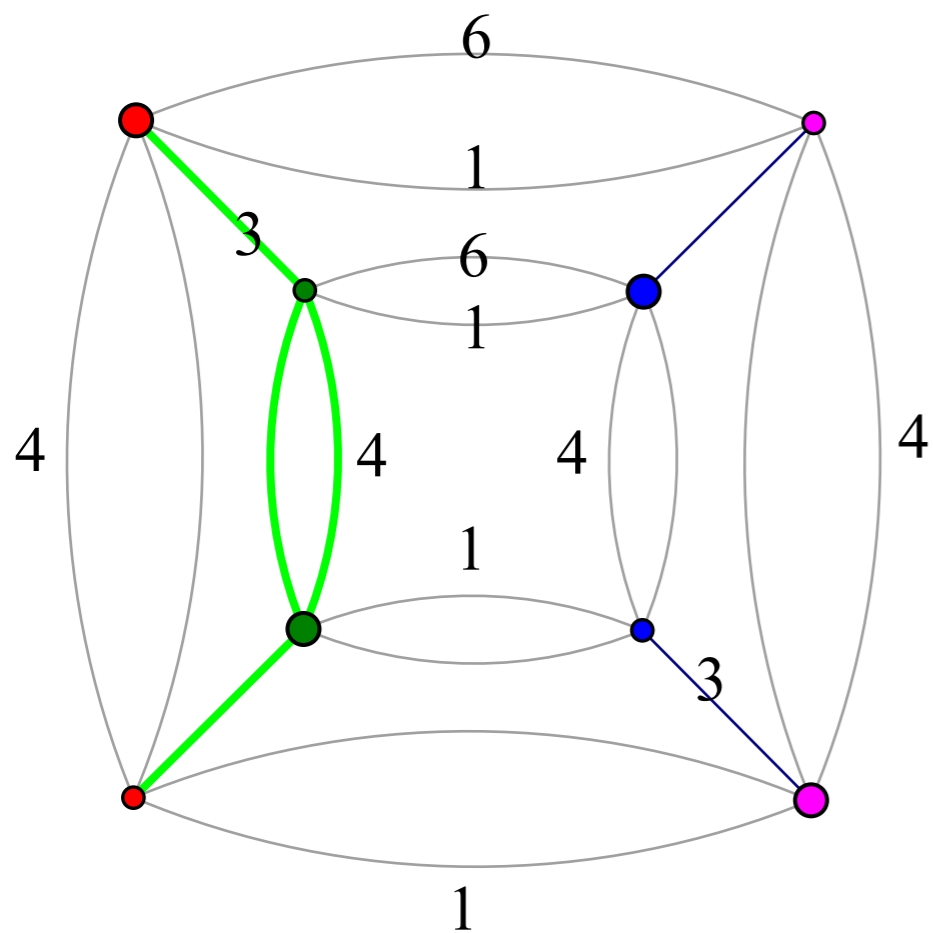
# DIHEDRALIZATION



# DIHEDRALIZATION

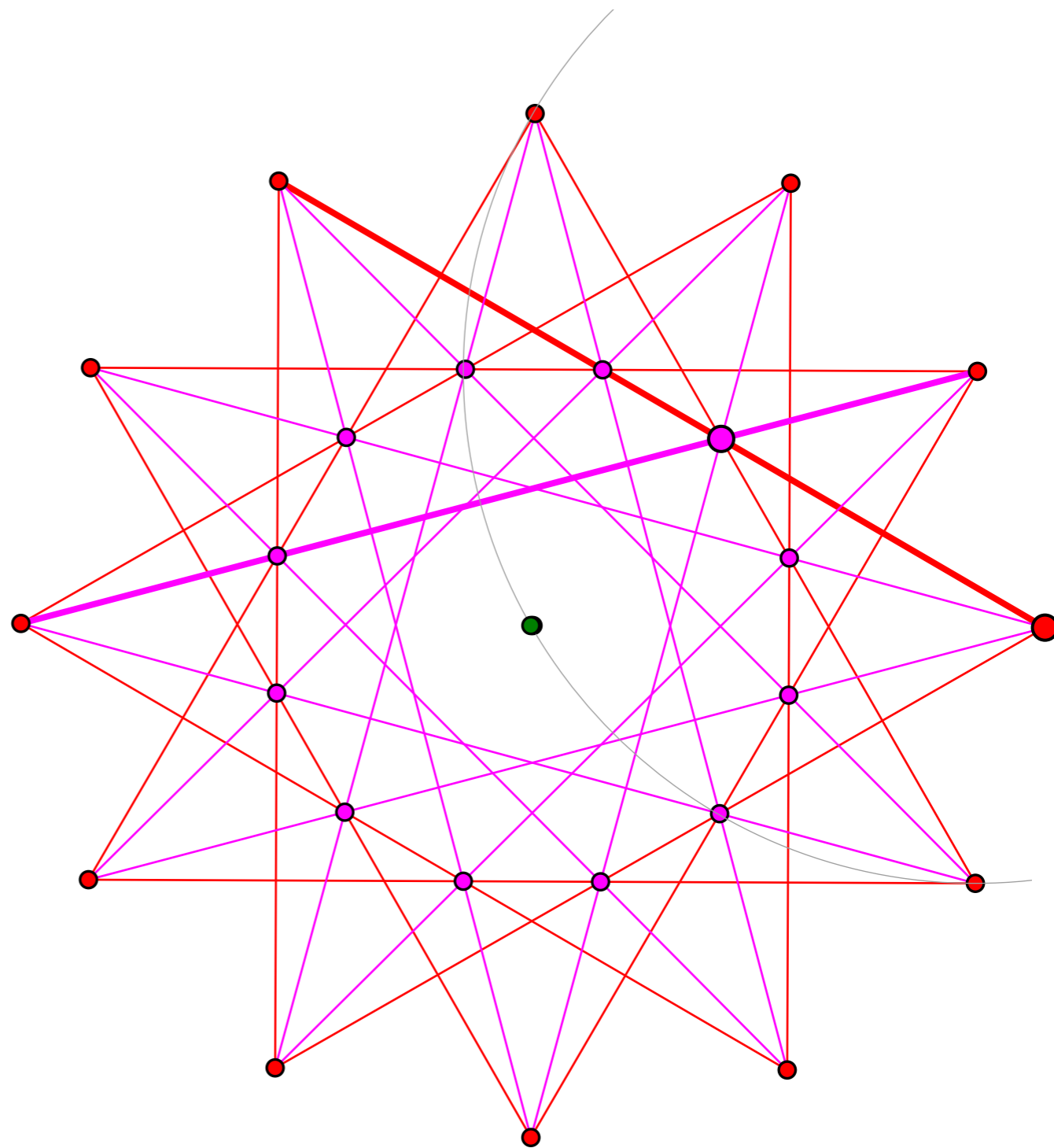
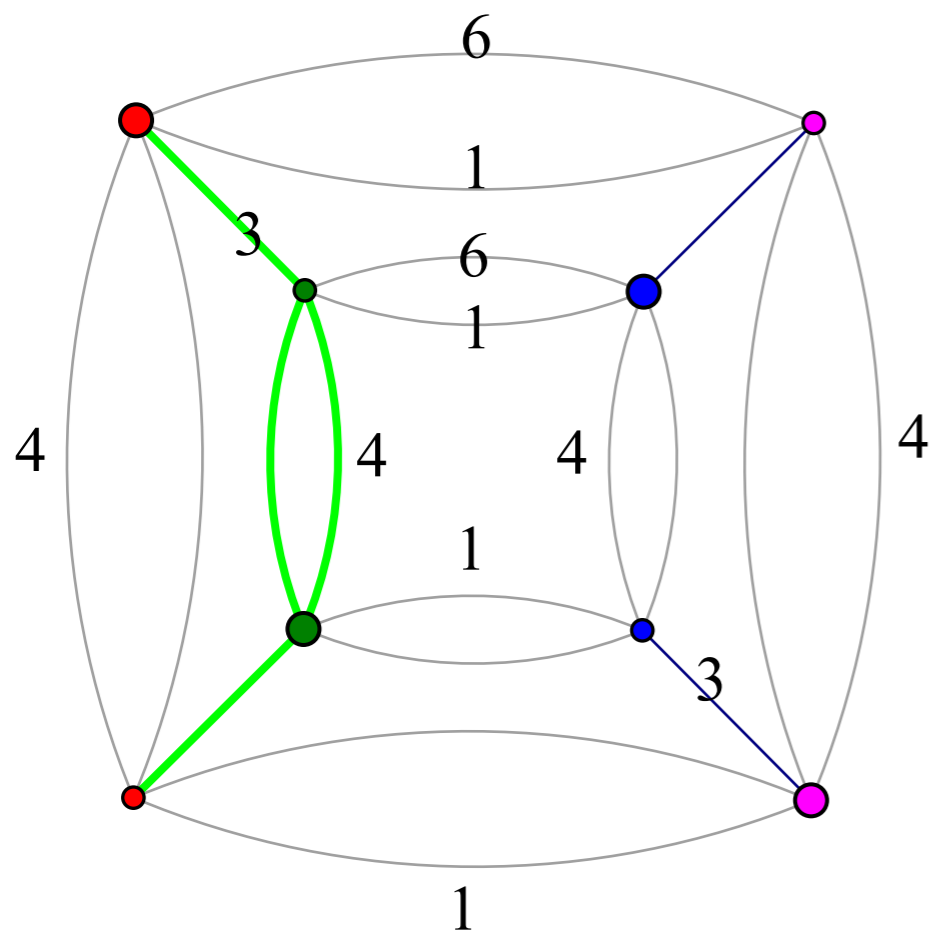


# MOVABLE 5-CONFIGURATIONS



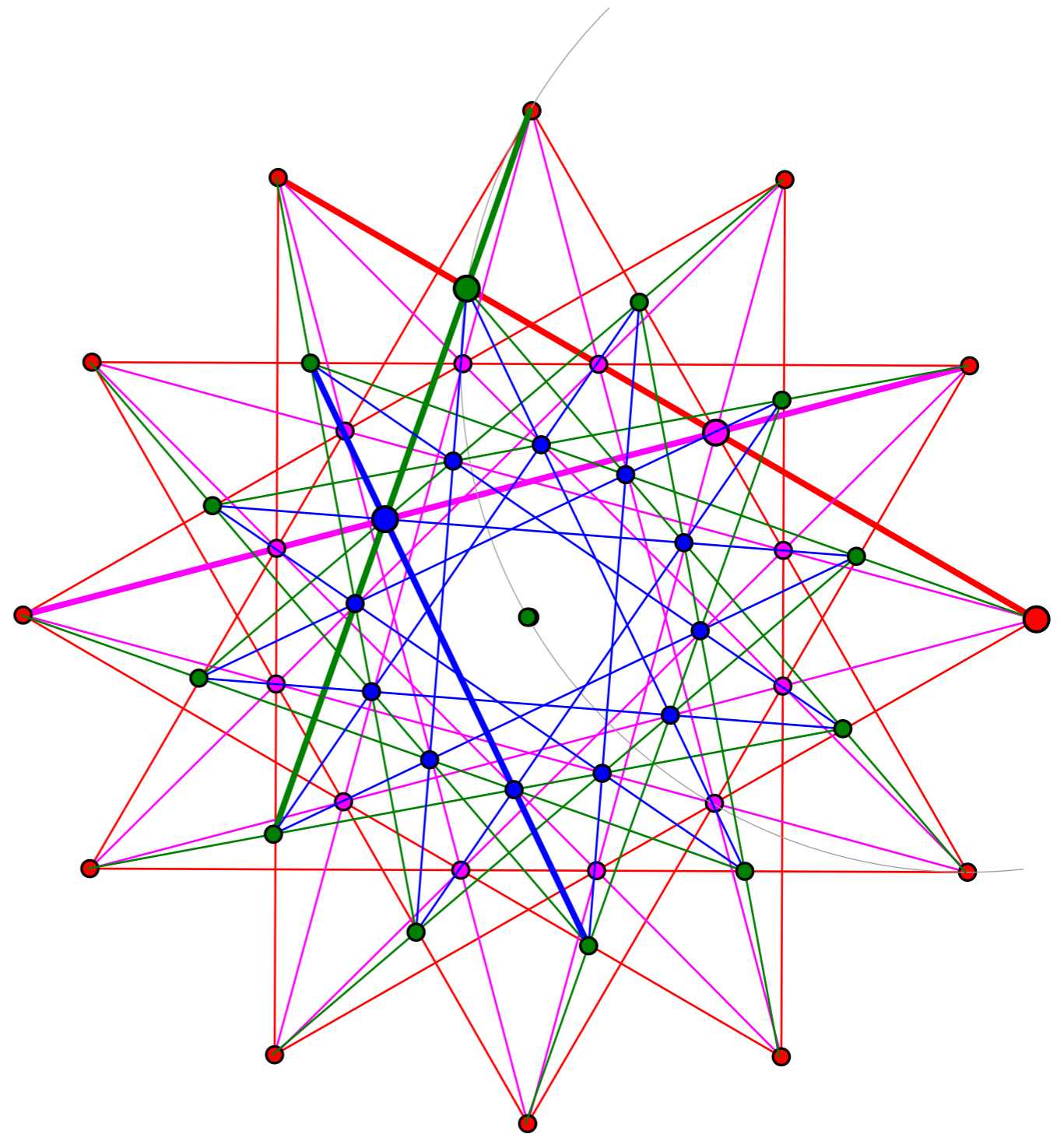
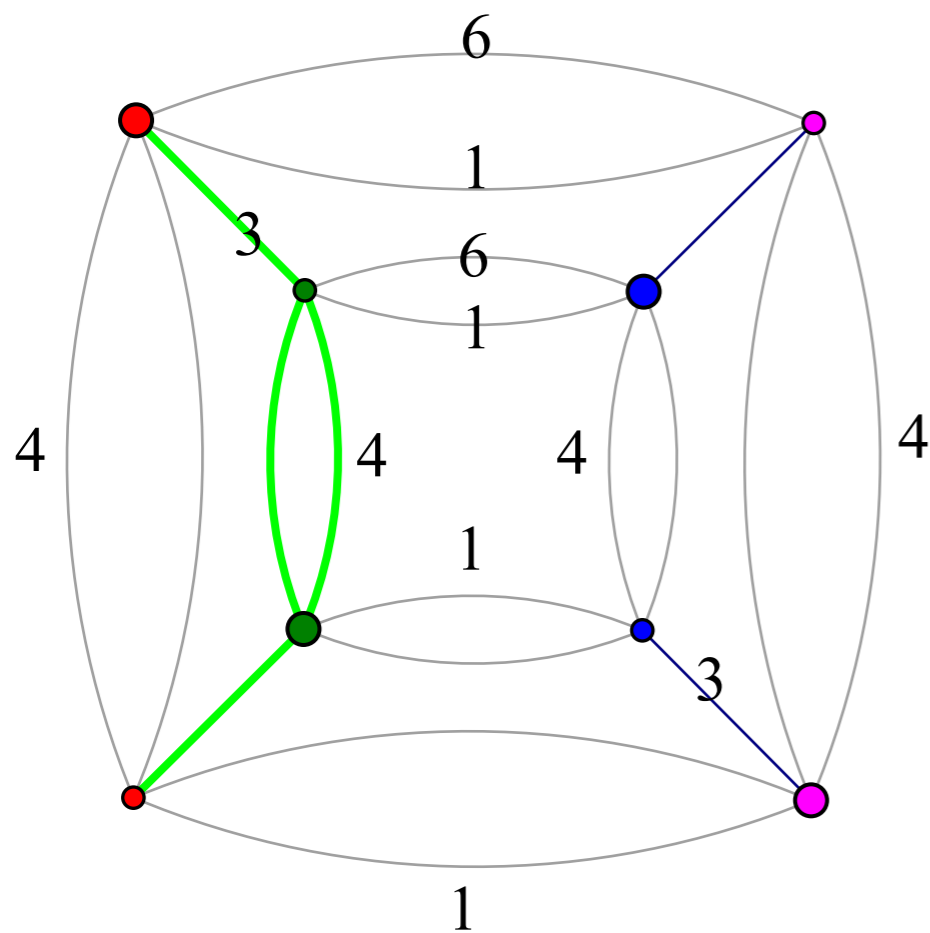
(48<sub>5</sub>)

# MOVABLE 5-CONFIGURATIONS



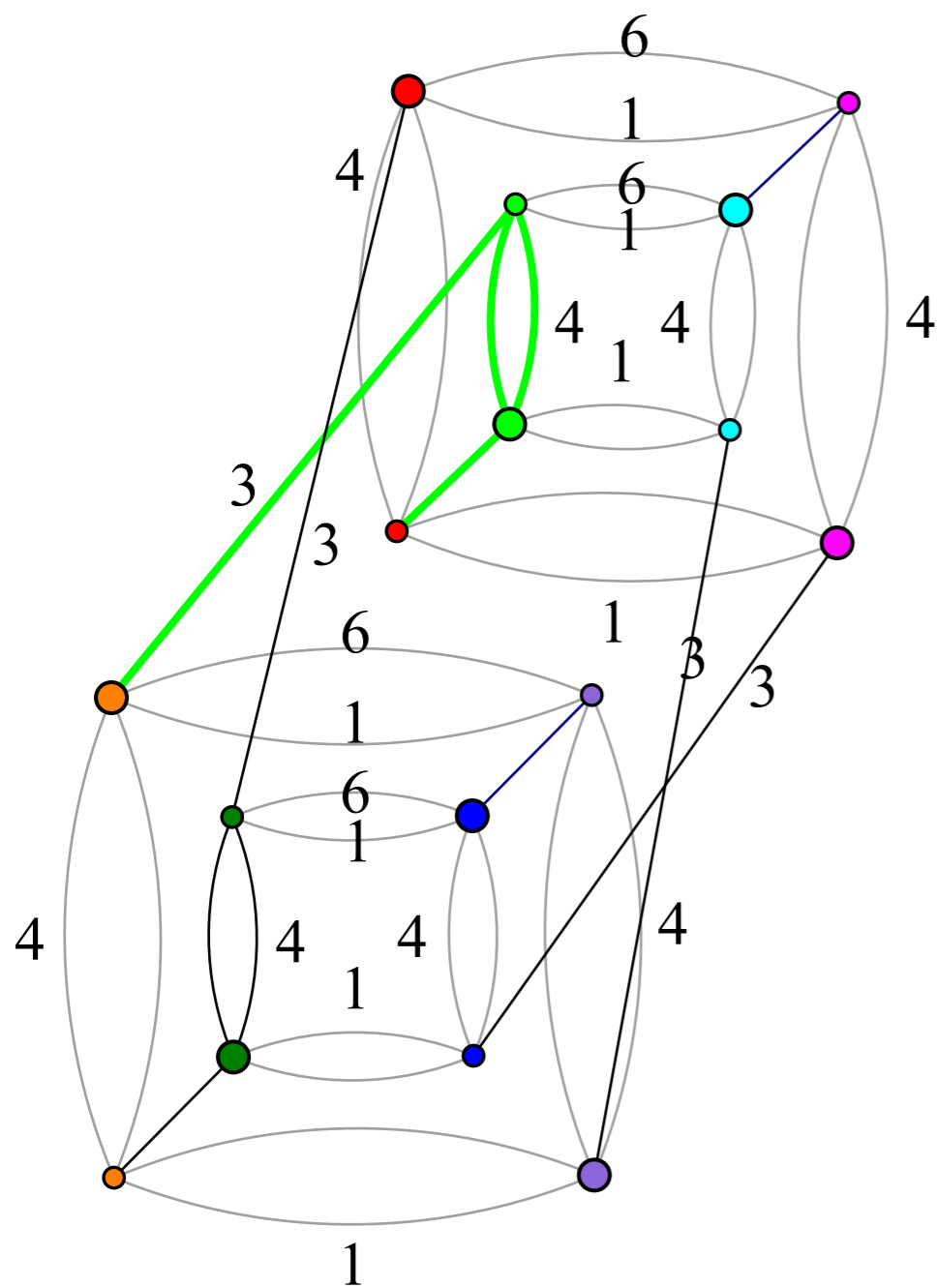
(48<sub>5</sub>)

# MOVABLE 5-CONFIGURATIONS

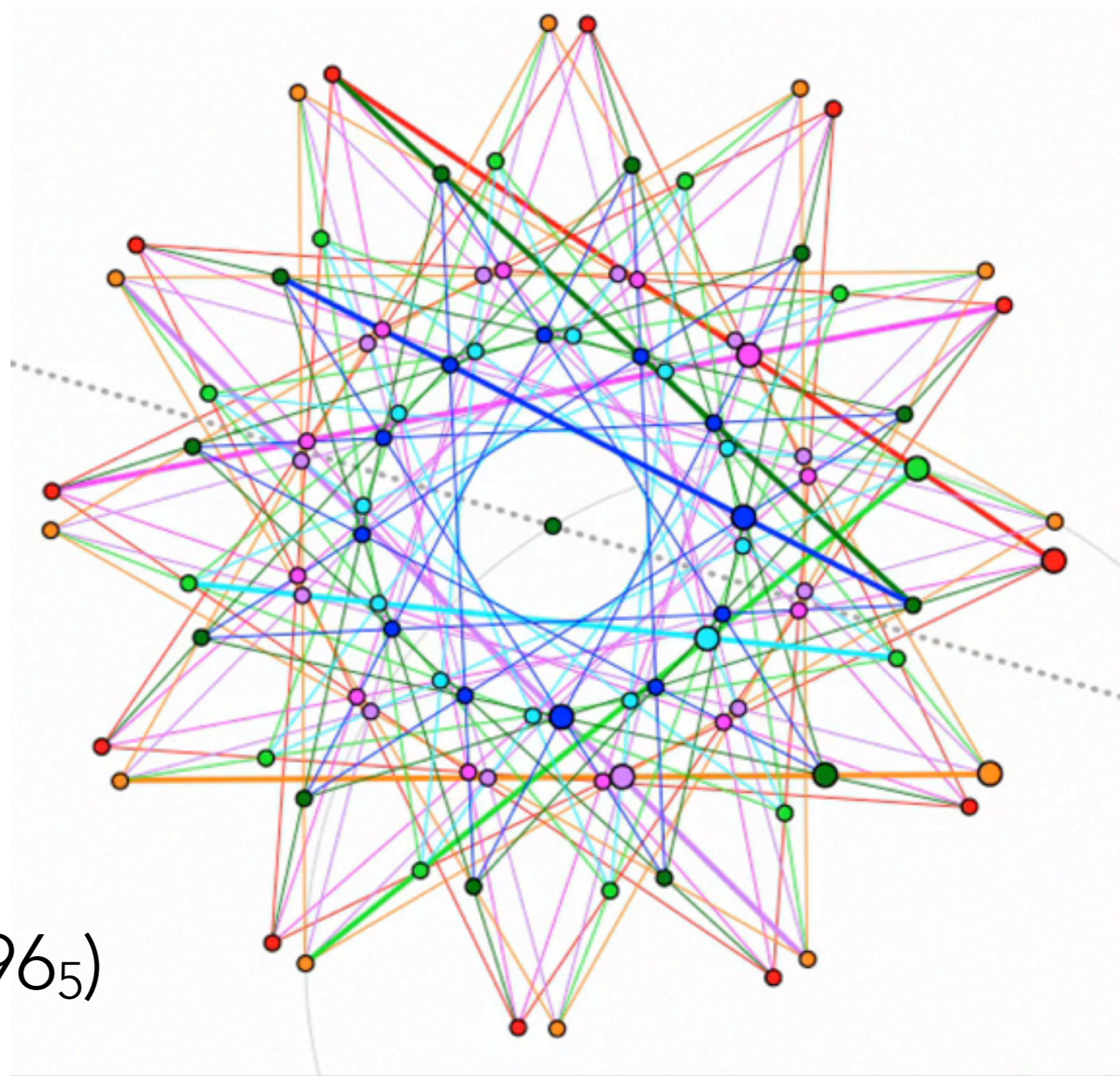


(48<sub>5</sub>)

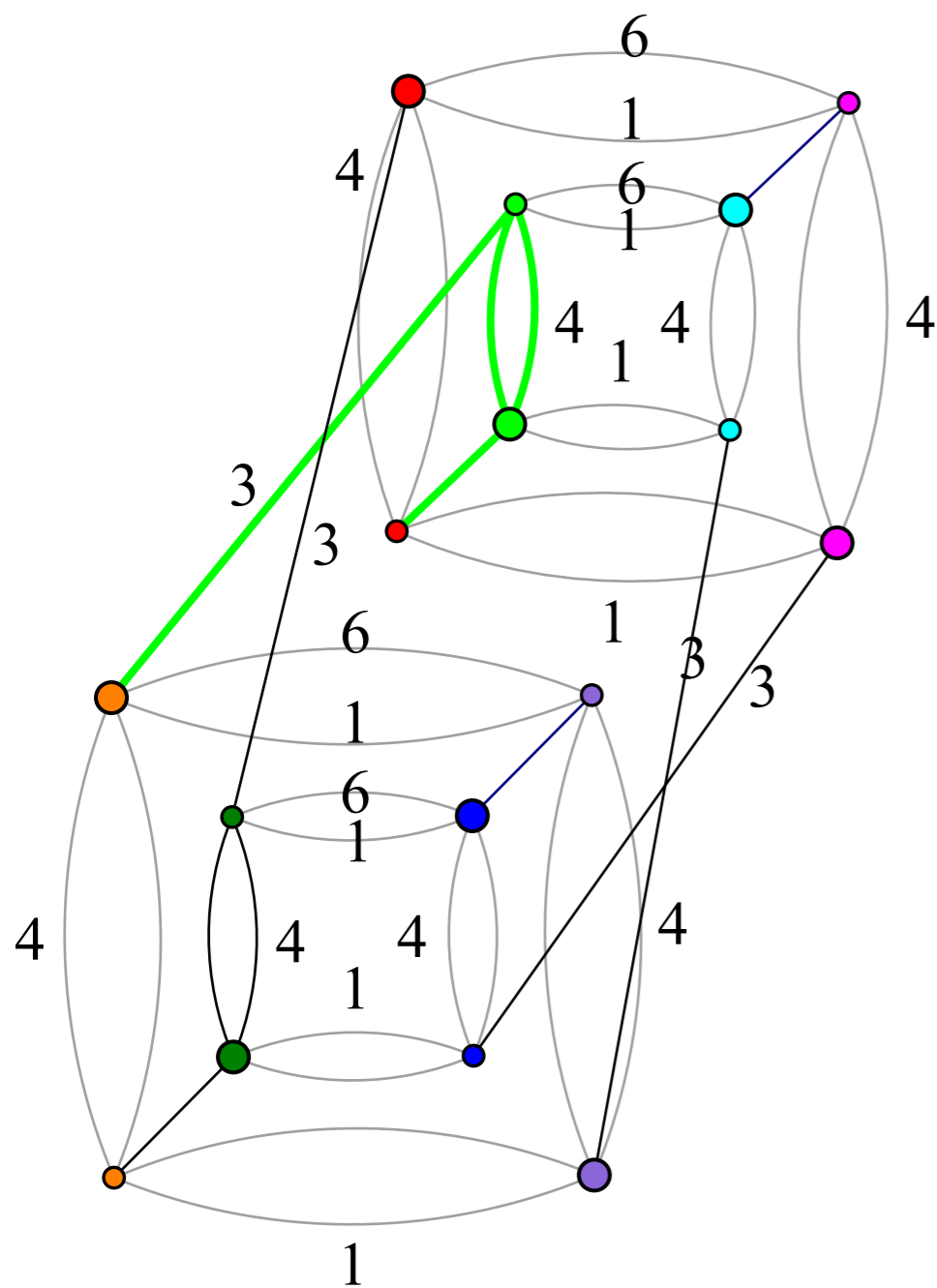
# MOVABLE 5-CONFIGURATIONS



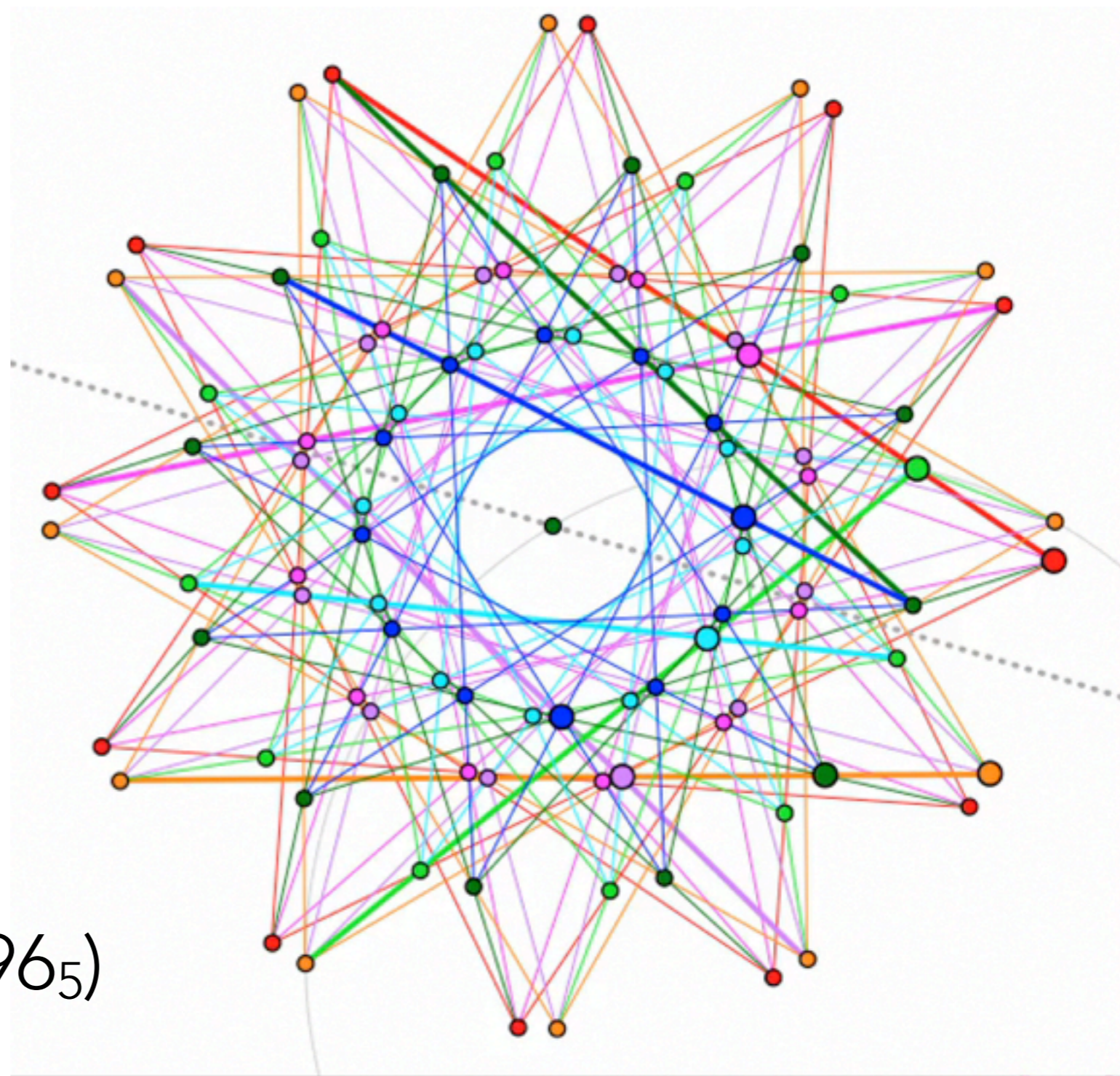
(96<sub>5</sub>)



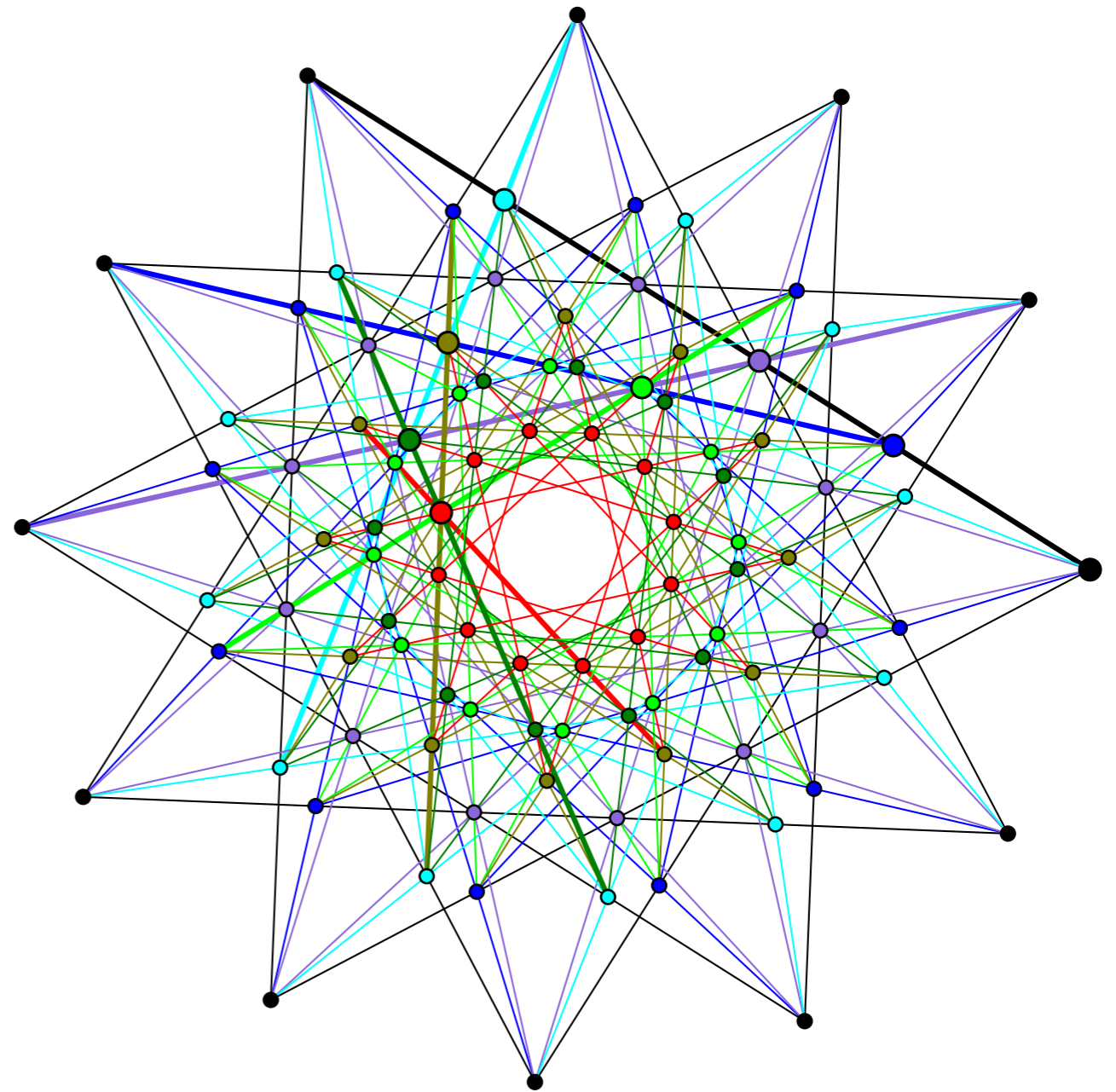
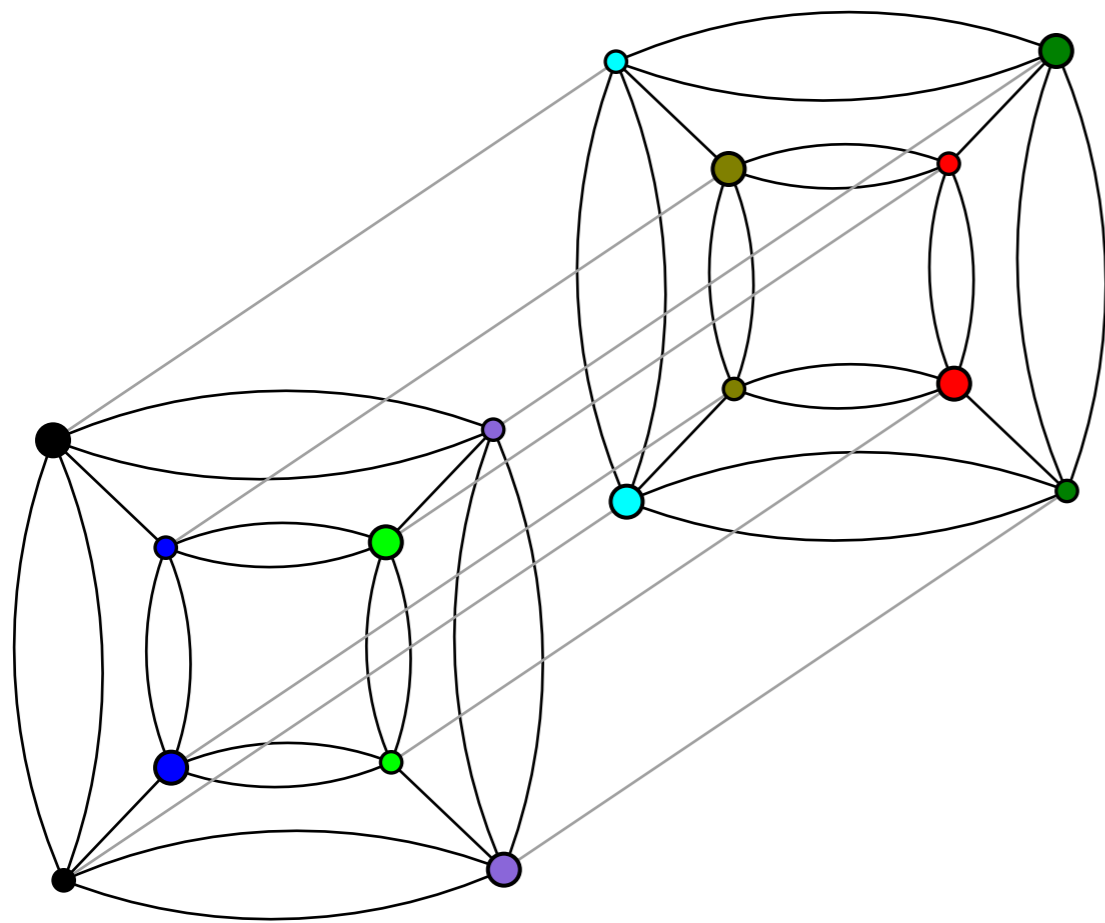
# MOVABLE 5-CONFIGURATIONS



(96<sub>5</sub>)

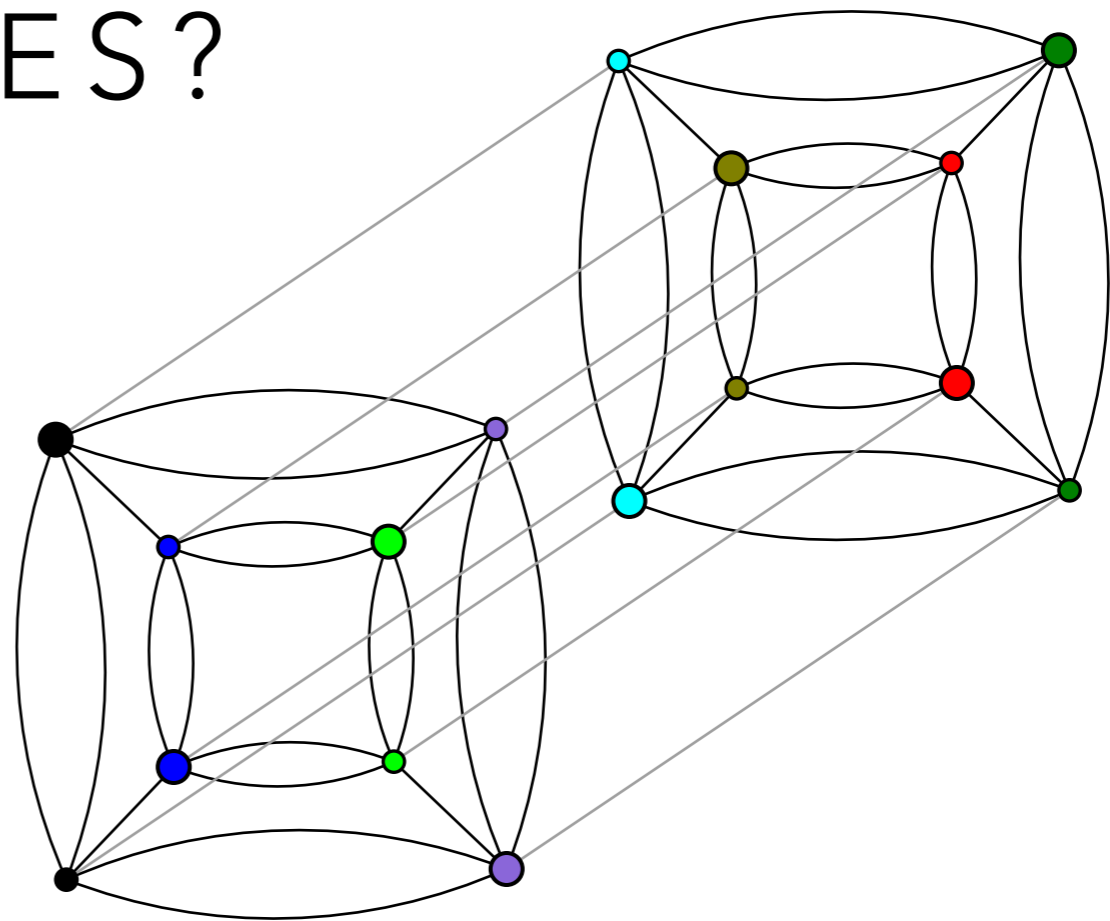
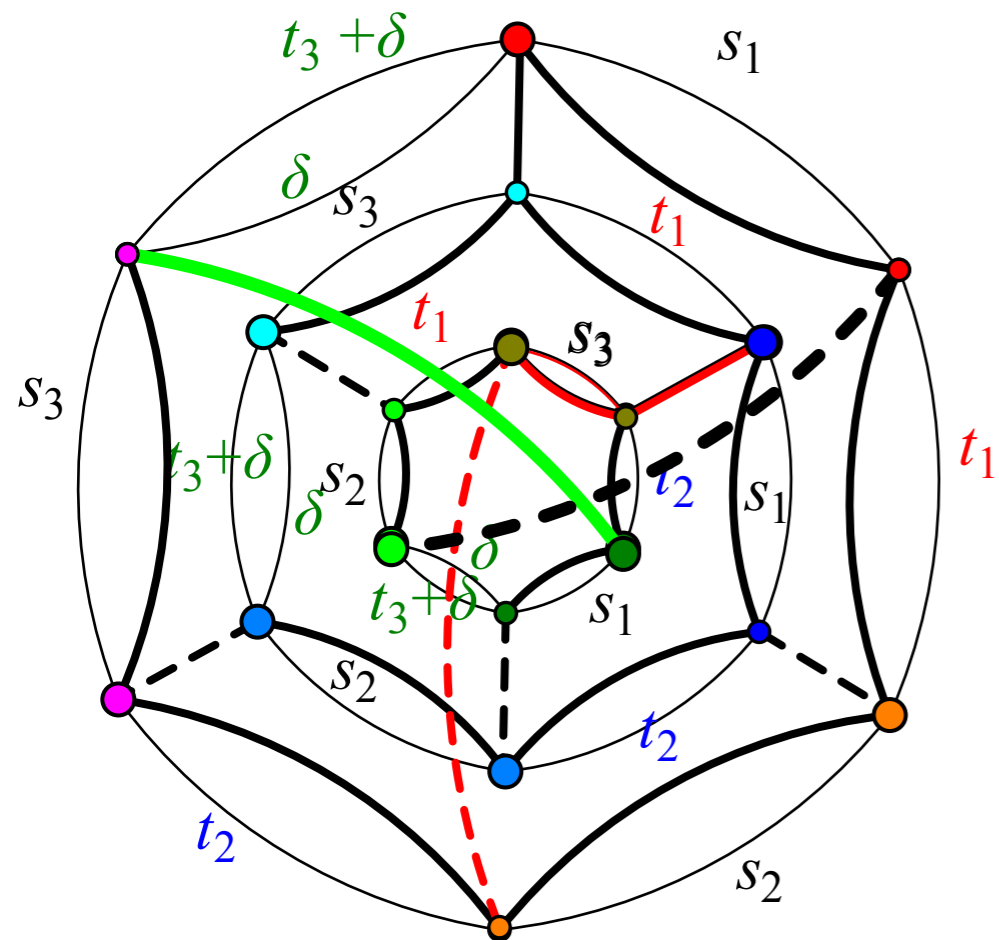
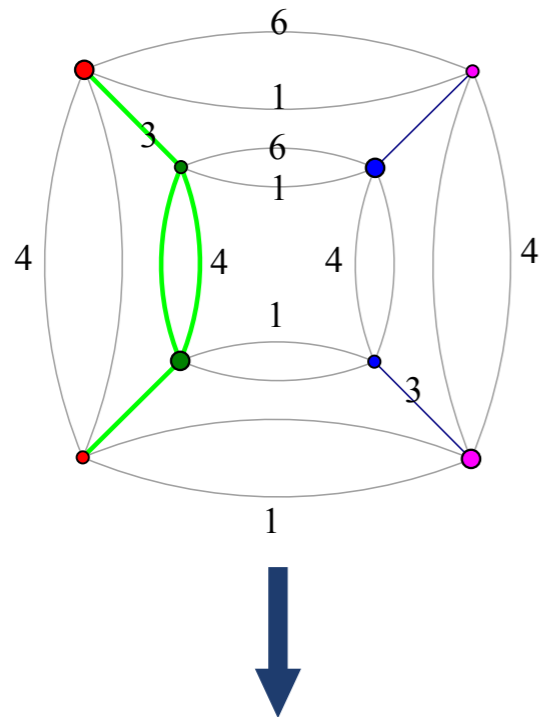


# LARGER EXAMPLES?



(96<sub>6</sub>)

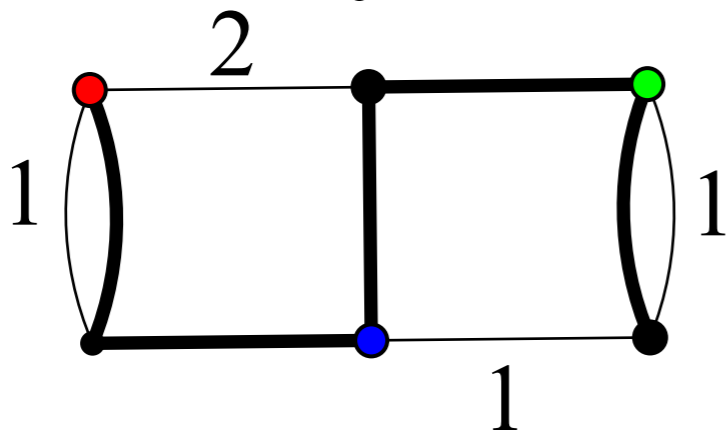
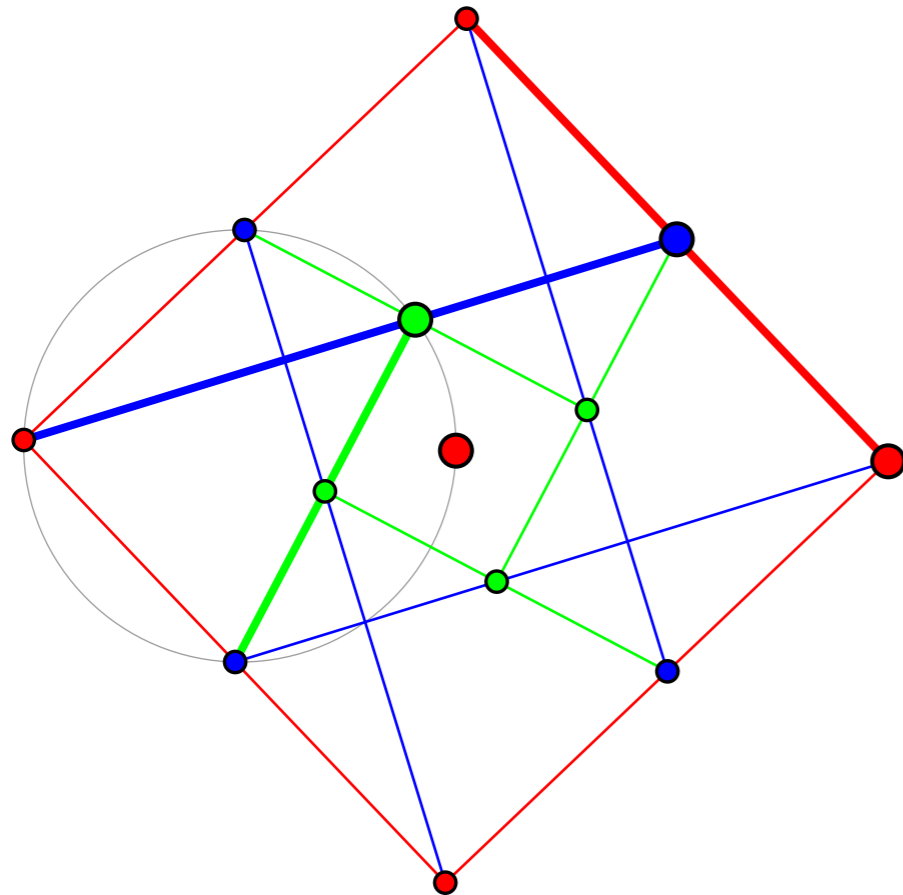
# LARGER EXAMPLES?



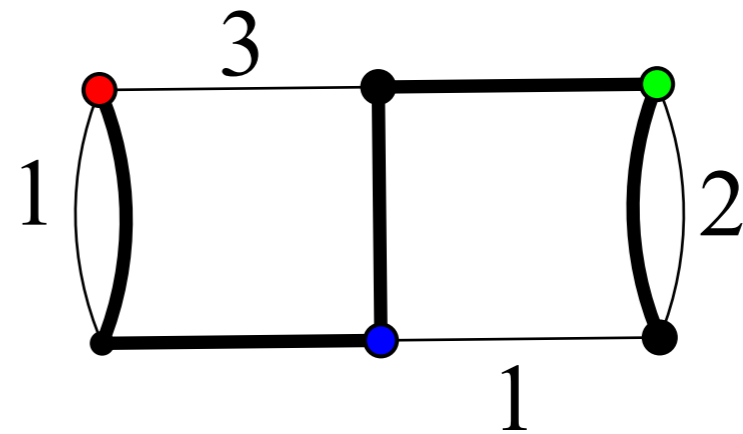
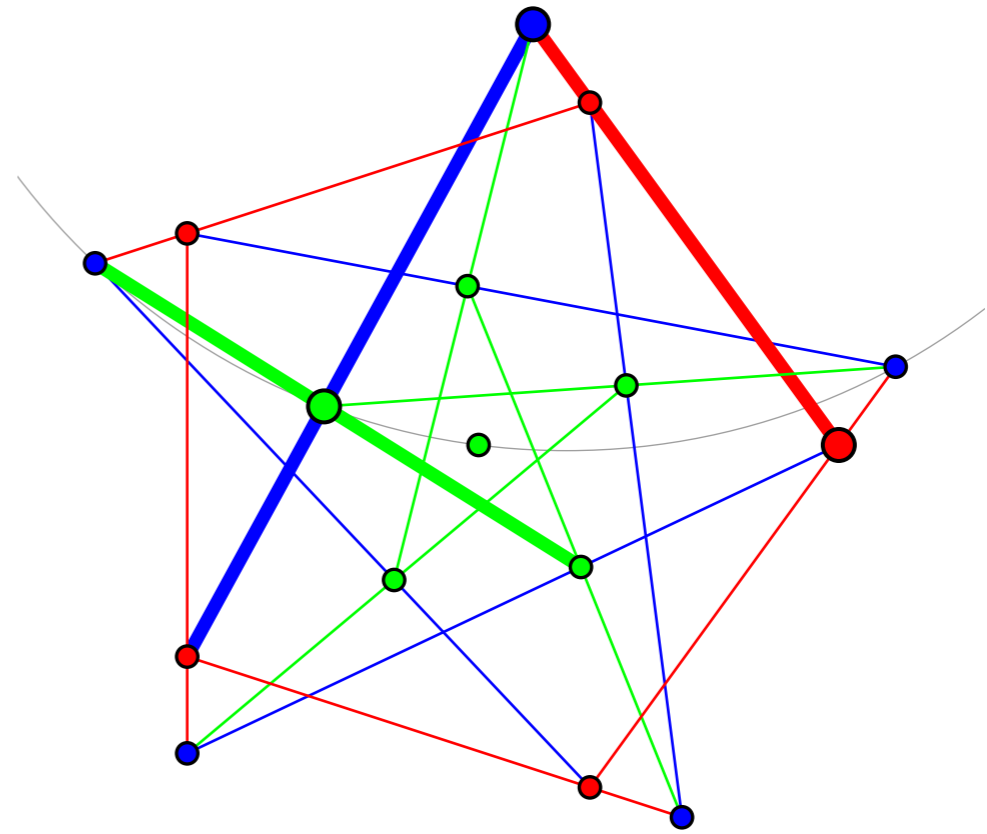
?

# VERY NICE CLASSES?

What can we say about the automorphism groups?



$(12_3)$  "Zacharias"



$(15_3)$  Cremona-Richmond

THANK YOU!